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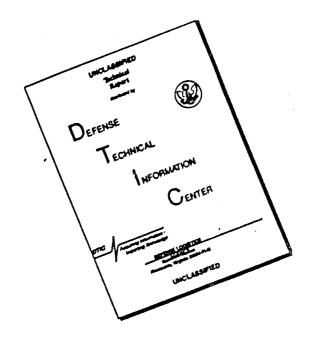
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STATIC AND DYNAMIC STABILITY STUDIES ON SEVERAL LAZY DOG CONFIGURATIONS AT SUBSONIC AND TRANSONIC SPEEDS (U)

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Aerodynamics Research Report 191

STATIC AND DYNAMIC STABILITY STUDIES ON SEVERAL LAZY DOG CONFIGURATIONS AT SUBSONIC AND TRANSONIC SPEEDS

Prepared by:
J. B. Eades, Jr.
C. Powers

ABSTRACT: A summary is presented of the investigations conducted in the Naval Ordnance Laboratory's Supersonic Tunnel No. 1 on several of the Navy's Lazy Dog weapon configurations. Lazy Dog is a free-fall missile employing a 50 caliber bullet or its core as the basic aerodynamic body.

Static stability tests were conducted on six configurations over a Mach number range from 0.3 to 1.3. Dynamic stability tests were made using the more promising configurations. In addition to these tests, ballistics range firings were conducted.

As a consequence of the information obtained in this investigation, two alternate configurations have been proposed.

U. S. NAVAL ORDNANCE LABORATORY WHITE OAK, MARYLAND



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18 May 1964

STATIC AND DYNAMIC STABILITY STUDIES ON SEVERAL LAZY DOG CONFIGURATIONS AT SUBSONIC AND TRANSONIC SPEEDS

The purpose of this investigation was to determine the aero-dynamic characteristics of several Lazy Dog configurations. This work was performed at the request of the Bureau of Naval Weapons under Task Number RMMO-42-005/212-1/F008-09-01.

The contributions of W. D. Piper, V. L. Schermerhorn, F. J. Regan, I. Shantz and P. A. Cerreta are gratefully acknowledged.

R, E, ODENING Captain, USN Commander

K. R. ENKENHUS
By direction

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INTRODUCTION

Lazy Dog is the name of a project established by the Bureau of Naval Weapons to develop an antipersonnel weapon from the existing surplus of 50 caliber bullets. The modified bullets are to be dropped, in quantity, from high speed, low flying aircraft. Concentrations of ground troops will be the principal targets. In order to accomplish its mission, Lazy Dog must have a concentrated mass and possess a relatively high kinetic energy at impact.

This report describes and summarizes the testing program, and the subsequent evaluation, for several Lazy Dog configurations. In those cases where the 50 caliber bullet served as the basic body, the unloaded shell casing was retained attached to the projectile. Various stabilizing afterbodies were produced by cutting and forming the shell casing. Other configurations were formed by attaching a finned afterbody to the bullet core.

The principal result is the recommendation that the steel core of the 50 caliber bullet be utilized as the basic missile body. An afterbody with stabilizing fins is added to form a low drag, fin stabilized weapon. The fins provide the stabilization which is normally realized by spin in the conventional application of the bullet.

This report represents a significant contribution to the aerodynamics of the 50 caliber bullet. It appears that prior to these tests very little aerodynamic data had been gathered on the bullet. A literature search led to the belief that no systematic studies of this sort had been conducted. Therefore, it is presumed that this report contains the majority of the aerodynamic data on this ballistic shape.

AERODYNAMIC SYMBOLS

| A | reference area (based on maximum bullet or core | | | | | | | | |
|----------------|---|--|--|--|--|--|--|--|--|
| | diameter) (in ²) | | | | | | | | |
| b | span (in) | | | | | | | | |
| c | chord (in) | | | | | | | | |
| CA | axial force coefficient (F_{A}/qA) | | | | | | | | |
| c_{D} | drag force coefficient (Fp/qA) | | | | | | | | |
| C _m | pitching moment coefficient (My/qAd) | | | | | | | | |

| $^{\mathrm{C}}_{\mathrm{m}}{}_{a}$ | slope of the curve of pitching moment coefficient versus angle of attack; the stability derivative $(dC_m/d\alpha)$ |
|---|--|
| C _N | normal force coefficient (F _N /qA) |
| $^{\text{C}}_{\text{N}_{\alpha}}$ | slope of the normal force coefficient-angle of attack curve; the stability derivative $(dC_N/d\alpha)$ |
| $C_{\mathbf{m}_{\dot{\theta}}^{\bullet}} + C_{\mathbf{m}_{\dot{\alpha}}^{\bullet}}$ | the pitch damping coefficient, $\frac{\partial C_m}{\partial (\frac{\partial d}{2V})} + \frac{\partial C_m}{\partial (\frac{\partial d}{2V})}$ |
| c_{ι} | rolling moment coefficient (M _X /qAd) |
| c, | roll damping derivative, $\frac{\partial C_{\ell}}{\partial (\frac{pd}{2V})}$ |
| d | reference length (bullet or core maximum diameter) (in) |
| FA | axial force (lbs) |
| $\mathbf{F}_{\mathbf{D}}$ | drag force (lbs) |
| $\mathbf{F}_{\mathbf{N}}$ | normal force (lbs) |
| I _{xx} | mass moment of inertia about the longitudinal axis $(slug-in^2)$ |
| I уу | mass moment of inertia about the transverse axis (slug-in ²) |
| L | rolling moment (in-lbs) |
| Lp | roll damping moment derivative (in-lbs-sec/rad) |
| \mathbf{L}_{δ} | induced rolling moment derivative (in-lbs/rad) |
| m | mass (slugs) |
| M | Mach number |
| Ma | slope of the pitching moment-angle of attack curve $(in-lbs/rad)$ |
| Mx | (rolling) moment about the body x-axis (in-lbs) |
| My | (pitching) moment about the body y-axis (in-lbs) |
| p | body spin rate (rad/sec) |

| q | windstream dynamic pressure (psia) | | | | | | |
|-----------------------------|--|--|--|--|--|--|--|
| t | time (sec) | | | | | | |
| V | velocity (ft/sec) | | | | | | |
| W | model weight (lbs) | | | | | | |
| X _{CG} | distance to the center of gravity from the nose measured along the x-axis (calibers) | | | | | | |
| X _{CP} | distance to the center of pressure from the nose measured along the x -axis (calibers) | | | | | | |
| X _{RC} | distance to the moment reference center from the nose measured along the x-axis (calibers) | | | | | | |
| α | angle of attack (deg, rad) | | | | | | |
| å | angle of attack angular velocity, $d\alpha/dt$ (rad/sec) | | | | | | |
| ä | angle of attack angular acceleration, $d^2\alpha/dt^2$ | | | | | | |
| | (rad/sec ²) | | | | | | |
| $\overline{\alpha}$ | $a_0^{\lambda t}$ which is the envelope of the pitch damping | | | | | | |
| | trace (deg) (see Appendix A) | | | | | | |
| Δα | angle (of attack) difference $(\alpha_p - \alpha_j)$ (rad) | | | | | | |
| ∆t | time difference $(t_j - t_i)$ (sec) | | | | | | |
| $\hat{\boldsymbol{\theta}}$ | pitch angle (deg, rad) | | | | | | |
| Subscript | s | | | | | | |
| С | refers to the 50 caliber bullet core | | | | | | |
| F | refers to an afterbody fin | | | | | | |
| in | initial conditions | | | | | | |
| im | impact conditions | | | | | | |
| j | refers to a general point or position | | | | | | |
| o | zero angle of atta conditions | | | | | | |
| g | peak angle of attack conditions | | | | | | |
| t | terminal condition | | | | | | |

MODELS, TEST TECHNIQUES AND DATA REDUCTION

The 50 caliber bullet, the bullet core, and the six flared or finned configurations tested in this program are shown in

Figures 1 through 8, and are listed in Table 1. Figure 1 is a sketch of the 50 caliber bullet, while Figure 2 depicts the core alone. It should be noted that the dimensions on Figure 1 are given in inches, while those on the other model drawings are expressed in calibers.

Configurations 1, 2 and 3 (see Figures 3-6) are flared tail models which were formed by simply cutting and shaping the cartridge case of the 50 caliber round. These three shapes were initially chosen on the basis of their performance as observed during drop tests conducted at the Naval Ordnance Laboratory. Configuration 1 (Figure 3) is the most elementary design, wherein the case has been clipped and the powder charge removed. This design represents a relatively simple aerodynamic shape which, incidentally, was later discarded due to its poor performance. Configurations 2 and 3 (Figures 4 and 5) are more sophisticated split skirt designs.

After the above-mentioned configurations utilizing the bullet and cartridge core were found to have rather poor aerodynamic qualities, several finned designs employing the bullet core were devised, tested and evaluated. Those considered have been designated as Configurations 4, 5 and 6 and are sketched in Figures 6, 7 and 8. Configurations 4 and 6, which were designed by the Naval Ordnance Test Station, are quite similar; they differ only in the planform shape of the uncanted stabilizing fins attached to the basic body. Configuration 5 is comprised of the bullet core fitted with four canted fins, serving to both fin-stabilize the body and provide for an aerodynamically induced spin which produces a degree of gyrodynamic stability. This design, which was suggested by the Bureau of Naval Weapons, was subsequently discarded after testing due to certain undesirable characteristics.

Figures 11 through 14 are photographs of the wind tunnel models tested. Figure 11 shows the 50 caliber core, Figure 12 the three flared configurations, and Figures 13 and 14 the three finned shapes. Once again it is recalled that the configurations employ two different forebodies. Each is fitted with differing aerodynamic stabilizing afterbodies to form the various shapes tested. Configuration 4 in Figure 13 does not have the nose section attached; the nose is in place on Configuration 5. The nose is employed whenever these bodies are being tested.

The initial part of the testing program was concerned with the measuring of static forces and moments on the several configurations, just discussed above, and the 50 caliber bullet core alone. These data were gathered from tests conducted in NOL Supersonic Tunnel No. 1 (reference (1)) with the models

mounted on a six-component, internal strain gage balance (see reference (2)). The data were collected and reduced to to aerodynamic coefficients, with corrections applied to account for sting deflection due to aerodynamic loads.

A brief analysis of the data indicated the overall superior qualities of Configurations 4 and 6, the finned models with zero fin cant angle. As a consequence, Configuration 6 was chosen as the model for further study and evaluation. This configuration was dynamically tested to ascertain its damping capabilities in pitch and in roll. A photograph of the pitch damping apparatus is shown as Figure 15. Highspeed motion pictures were used to obtain the time to damp to half amplitude, which determines the total pitch damping coefficient, $C_{m_0^2} + C_{m_0^2}$. This technique is described in reference (3),

An estimate of the pitching moment coefficient for the model can also be made from these photographic records. This scheme requires that the oscillatory mode be viewed in regard to how the motion, in the vicinity of the peak oscillation, is related to the aerodynamically induced pitching moment. The photographic records are utilized to provide an approximate expression for the angular acceleration; the approximation (see Appendix B) is

$$\frac{\mathrm{d}^2 \alpha}{\mathrm{d}t^2} \approx -\frac{2 \hat{\alpha}}{(\Delta t)^2} \tag{1}$$

where Δa is the difference in (pitch) angle of attack occurring during the time increment Δt . Using equation (1) in the single-degree-of-freedom relationship specialized for peak displacement equation (B-8) gives:

$$\frac{C_{m}}{a_{p}} = -\frac{2\Delta a I_{yy}}{(\Delta t)^{2} q A d}$$
 (2)

where $C_{m}|_{\alpha_{D}}$ is the pitching moment coefficient at the peak

angle of attack, $\alpha_{\rm p}$. A more complete description of this method of analysis is available in Appendix B. Incidentally, this model had three tail fins and was tested in two modes; one with a tail fin placed vertically and the other with a fin horizontally located. This procedure was adopted to see if a difference in damping would be noted.

Roll damping derivatives were obtained for Configuration 6 using the apparatus described in reference (4). Briefly, the

model is driven at a predetermined roll rate, and then the rolling motion allowed to decay with time. The roll rate-time history is recorded and then analyzed to determine the time for the motion to decay to a desired level, etc. This information is then utilized, analogous to the scheme set down above, to calculate values of the roll damping derivatives. See Appendix C for a more complete description of the method employed.

The last phase of testing on Configuration 6 was conducted in the NOL Pressurized Ballistics Range No. 3 and the NOL Aerodynamics Range No. 1. Here full scale models were test-fired down these ranges to ascertain their free-flight behavior. Several shots were made, at high subsonic and transonic Mach numbers, and at initial launch angles of 15, 45 and 90 degrees. No quantitative data were collected from the range firings; the purpose of these shots was to verify the stability evaluations made from the aerodynamic data gathered during the wind tunnel testing program.

A compendium of the wind tunnel and range testing conditions is given in Table 1.

The overall results of this investigation indicate that none of the configurations tested is entirely satisfactory for the purposes intended. As a consequence, two designs have been proposed which should better meet the requirements of the Lazy Dog weapon; these are presented herein as Configurations 7 and 8, and are shown in Figures 9 and 10. These designs were analytically determined employing data gathered during this testing program and other experimental data. It is suggested that models of the configurations be constructed and tested to prove their effectiveness.

DISCUSSION OF RESULTS AND CONCLUSIONS

The data collected, reduced and calculated during this program are set down in Figures 18 through 69. All of the wind tunnel data have been corrected for aeroelastic deformations of the balance sting. It should be recalled that these results have been collected essentially for a family of three body types. These include the basic 50 caliber shell, cut and formed to provide a stabilized configuration; the 50 caliber bullet core with stabilizing fins added; and the bullet core alone.

As mentioned in the preceding section, wind tunnel tests were conducted to ascertain the static and certain dynamic (stability) characteristics of the several configurations. In Figures 18 through 32, normal force data are presented as a

function of angle of attack for several free-stream Mach numbers. The free-stream Mach numbers for these tests varied from approximately 0.3 to 1.26. The corresponding static pitching moment data, for the several bodies, are presented on Figures 35 through 49. The angle of attack range for the stabilized bodies (formed and finned afterbodies) was $-4^{\circ} \le \alpha \le +16^{\circ}$, while for the bullet core alone the range was $-5^{\circ} \le \alpha \le +90^{\circ}$. Figures 33 and 34 show the normal force coefficient slope (C_N) determined in the neighborhood of $\alpha = 0$. The moment

coefficient slope (C_{m}) is presented on Figures 50 and 51.

From these results the static stability margin $(X_{RC} - X_{CP})$ is readily determined; this quantity also serves as a measure of a configuration's static longitudinal stability. For those cases where the margin of stability is positive $(X_{RC} - X_{CP}) > 0$, the body is statically stable; that is, the center of pressure lies aft of the moment reference center. In this regard, when the moment reference center coincides with the center of the mass then the constrained margin of stability (as determined here from wind tunnel data) would ideally be the same as that experienced by a prototype in free flight under similar aerodynamic flight conditions.

Figure 54 presents the drag data (C_{A_0} , axial force or drag coefficient at a=0) for Configurations 1-6, inclusive, over the Mach number range from 0.49 to 1.26. Generally speaking, then, Figures 33, 34, and 50 through 54 summarize the basic (static) aerodynamic characteristics of the bodies tested in the Lazy Dog program.

A study of Figures 18 through 29 indicates that the configurations fitted with stabilizing afterbodies develop a decided nonlinearity of the normal force coefficient in the transonic speed range. This nonlinear influence is most pronounced at the higher angles of attack and after the typical onset of transonic compressible influence. Apparently, these diversities are brought on by local sonic conditions, since they appear at near the drag divergence Mach number and diminish at approximately the upper (Mach number) limit for transonics. It is rather interesting to note that Configurations 2 and 3 (see Figures 4 and 5) show almost identical normal force variations throughout the transonic speed range. This would imply that these body types are essentially equivalent in transverse force capabilities. Configuration 5, with its canted fins, generates the largest normal force. Configuration 1 generates the least.

Special attention is called to the data presented for Configurations 4 and 6, because these are the configurations on which the dynamic stability tests were performed. Configuration 4 is better than 6, with regard to normal forces produced over the entire transonic speed range.

From Figure 33, it is evident that the fin stabilized bodies are more susceptible to transonic influences than are the skirted afterbodies. Configurations 4, 5 and 6 show the typical transonic "hump" in the normal force curve slope ($^{\rm C}_{\rm N}$).

Though the other configurations (1, 2 and 3) show a similar influence, it is not nearly so severe.

The bullet core data, C_N vs. α , for the several Mach numbers, is presented on Figures 30 through 32. Here, a decided nonlinearity, at angles of attack not near zero, is quite apparent. These results, up to approximately 60 degrees angle of attack, are typical for bodies of revolution having an ogival type nose. The rather abrupt rise in slope (C_N) at approxi-

mately 30 degrees angle of attack, and the subsequent reduction in slope at about 60 degrees, is indicative of the influence of body shape and flow separation on $C_{\rm N}$.

Figures 35 through 59 present pitching moment coefficients versus angle of attack for the speed range of the tests. Analogous to those cases just discussed, the nonlinear influence of transonics is quite evident. It should be noted that Configuration 1 is statically unstable over the entire range of angle of attack. The other configurations (2 through 6) are statically stable about their trim angle of attack. A study of these graphs indicates that in general the stable configurations have an increased stability index (C_m) at transonic speeds.

They also experience an increased nonlinearity in $C_{\rm m}$ at these (same) speeds. These effects are most apparent for Configurations 1, 4 and 6 and least evident for the shapes designated as "2" and "3." Actually, near sonic speeds the trend is for the more largely influenced bodies to develop a trim angle outside of the test range; that is, for $\alpha > 16^{\circ}$. This is somewhat disturbing in view of the many launch conditions possible for the Lazy Dog weapon. A second trim angle means that the bomblet might not properly trail.

In terms of the static stability index (C), Configuration 5, with its canted fins, is clearly superior to all others.

Configurations 4 and 6 have the next best stability characteristics, and, as mentioned previously, Configuration 1 is statically unstable (see Figure 50).

On Figures 47 through 49 the static instability of the bullet core alone is described. Once again the phenomena of flow separation and/or compressibility are quite apparent. At least two changes in slope (C_{H}) are indicated, and a sharp

slope reversal is noted at approximately 60 or 70 degrees angle of attack. The need for some sort of stabilizing augmentation is clear. Further, it is apparent that the core possesses a second trim orientation in the vicinity of 100 degrees angle of attack. These conditions imply a need for, say, the spin stabilization of a bullet, and point up the sometimes noted "instability" of nonspinning, projectile—like bodies.

Analogous to the normal force coefficient, the basic stability derivatives (C $_{\rm m}$) for the core alone are only slightly $_{\rm o}$

influenced by Mach number, at least in the speed range of the tests as reported (see Figure 51).

Figures 52 and 53 summarize and give an aerodynamic representation to the data collected and described above. These figures describe the static margin of stability for the various configurations as a function of free-stream Mach number. As mentioned before, a positive value for the term implies a body which exhibits static stability. Also, the larger the magnitudes of this term the more stable is the configuration. This is apparent when one considers that for a wind tunnel model the measured moment is obtained about a moment center, which in turn is produced by the aerodynamically generated normal force. The ratio of the moment to the force is then proportional to the moment arm. This would be the same as the ratio of the linear slopes, Machine and Machine measured the slopes (see

Figures 33 and 50, for example) it is a sample matter to calculate the static margin, which is given here in calibers. The similarity to the curves of $C_{\rm rec}$ and $C_{\rm m}$ is immediately seen;

once again it is evident that Configuration 5 is superior to all others, with Configurations 6, 2 and 4 following on a next-best basis. Typically, Configuration 1 is indicative of the unstable situation where the center of gravity lies aft of the force center, or center of pressure, on the body. It is of interest to note that in the main the stable configurations show an increase in static margin over the transonic speed region, while the unstable Configuration 1 is at best only slightly affected by Mach number.

Figure 54, prepared for the bullet core, also shows the unstable character of this body type but shows a more marked dependence on free-stream Mach number.

In Figure 55 the last of the usual serodynamic wind tunnel data is presented. This graph is a plot of the zero angle of attack axial force, or the drag coefficient at $\alpha=0$, as a function of free-stream Mach number. Recalling that one requisite for Lazy Dog is low drag, then it is evident that the least values of C_A describe the best configurations. A cursory

glance at this figure indicates a choice of either Configuration 4 or 6 in terms of a least basic drag for the speed range considered.

Having the basic data from the wind tunnel measurements, it is now possible to select a configuration which would seem best suited to serve as the Lazy Dog Weapon. From an overall consideration it would appear that either Configuration 4 or 6 should be selected. As a consequence, Configuration 6 was chosen and used in the dynamic stability studies conducted as a part of the weapon's evaluation program. Even though Configuration 5 showed some superior capabilities it was not selected for further evaluation primarily because of the need for a least drag configuration. It should be noted that the canted fins on Configuration 5 would probably introduce an added drag component, when the bomblet was free to rotate, arising from the fin lift increment needed to provide the rotation. Of course, it is likewise apparent that body rotation is a necessary evil for fin stabilized bodies since it would be virtually impossible to mass produce a finned afterbody unit without some fin misalignment. Fin misalignments will produce some trim. Roll produced by fin cant aliminates dispersion due to such asymmetries. However, the phenomenon of pitch-roll resonance may be incurred. When the roll rate equals the natural pitching frequency, there is a large amplification of trim. The trim at resonance depends on the aerodynamic damping. If the damping is low, or if the asymmetry is sufficiently large, very erratic behavior (such as a flat spin) could result. In practice, it is difficult to manufacture fins with the small differential deflection required to keep the terminal roll rate below resonance. Hence, it is common to increase the fin cast to produce a roll rate above resonance. This incurs a papalty in the form of induced drag.

On Figures 55 through 59 the total pitch damping capacity (C $_{m_{\mathring{Q}}}$ + C $_{m_{\mathring{Q}}}$) of Configuration 6 is presented. This damping term

is measured as the sum indicated since the rechnique of experimentation used does not permit separation of the derivatives. Figures 56 through 59 are graphs of pitch damping as a function

of the angle α . Each graph represents a particular free-stream Mach number. The Mach number range is $0.3 \le M \le 0.9$. Figure 55 summarizes these data by showing the range of pitch damping as a function of free-stream Mach number. The range of the damping term, at a given Mach number, has been arbitrarily selected to correspond to an α variation of $0^{\circ} \le \alpha \le 10^{\circ}$. Values of the pitch damping derivatives were taken from Figures 56 through 59 for this purpose.

It should be pointed out that on these figures (56 through 59) there is a region of uncertainty connected with each graph. For this reason all curves have been extrapolated to the $\bar{\alpha}=0$ value shown, and the curve plotted as a dashed line in the region of uncertainty.

The damping in pitch of Configuration 6 was expected to depend on its roll orientation because of the triform tail. This expectation was studied by performing two damping tests, one with a fin vertically aligned in the wind tunnel and one with a fin parallel to the tunnel horizontal plane. The experimental results showed no effect of model roll orientation.

Figure 55, representing somewhat of a summary, shows that for the configuration tested there was a continual increase in pitch damping derivative with free-stream Mach number. Generally such results are expected. The damping derivatives arise from the pitching rate and from the heave. In most cases, the pitch rate damping C is the more important trim. It can be en-

hanced by increasing the tin domont arm or the fin area.

It should be mentioued, in connection with tests of this type and those conducted to determine other damping derivatives for other modes of motion, that an Tab yet unaccounted for" source of error is present. This error arises because of the uncertainty in the amount of bearing friction present in the experimental apparatus. It has been tacitly assumed that the magnitude of the moment created by the bearing friction is small compared to the aerodynamic moment.

A development carried out in Appendix A suggests that the pitch camping data can be utilized to determine the static

pitching moment. Two methods appear in the appendix; however, only the method suggested by equation (B-8) was actually utilized in this report. Having measured the time and angle increments, and knowing the characteristics of the body and the windstream, equation (B-8) is solved for a value of $C_{\rm m}$. The calculated values are presented as graphs of $C_{\rm m}$ versus α for the free-stream Mach numbers of the pitch damping tests. These graphs appear as Figures 60, 61 and 62 in this report.

In view of the inevitability of finned configurations having some rolling motion, a series of tests was conducted on Configuration 6 to ascertain its damping in roll. This characteristic of the bomblet could arise from fin cant angle (intentionally or accidentally provided) and could have a decided influence on the free-fall trajectory of the weapon.

Under the controlled testing conditions present in the wind tunnel, and for a precisely constructed model, accurate data have been collected and analyzed. Figures 63 and 64 present the roll damping derivative as a function of free-stream Mach number and angle of attack.

From Figure 63 it is seen that the Mach number influence on C_t is mainly confined to the transonic and supersonic speed p range. Too, it is evident that as the angle of attack is increased the influence of Mach number is reduced in comparison to, say, the $\alpha=0$ case.

A cross plot of these results appears on Figure 64. Here it is apparent that the Mach number influence can be more pronounced as the angle of attack is reduced. Once again the tendency of the body to seek a common level of roll damping, without regard to Mach number or angle of attack, is demonstrated. A diverse occurrence is observed on Figure 64. The general trend is for the roll damping capacity to decrease as the angle of attack is increased; all cases except that for the lowest test Mach number show this characteristic. For a free-stream Mach number of 0.3 the trend is reversed in that the damping capacity increases with increasing angle of attack, reaching a maximum and hinting that at still larger angles the expected decrease in $|\mathsf{C}_t|$ will occur.

The method used to calculate C_{ℓ} from the roll motion time history records is described in Appendix C. The equation used in connection with this report is equation (C-8). This represents the case of no induced roll action. The calculation

requires a knowledge of the roll rate, p(t), and certain properties of the model and the wind tunnel operation conditions. For cases where induced rolling would occur, and a subsequent steady state rolling would follow, the applicable formulation is given by equation (C-6), rather than (C-8).

In addition to the information gathered here, it was decided that several range firings of full scale models should be conducted. These tests were suggested primarily for the purpose of gaining further information on the free-flight behavior of the weapon, especially to observe flight characteristics for launchings at large initial angles of pitch. These tests were carried out in the NOL Pressurized Ballistics Range and the Aerodynamics Range.

The range test shots indicated that pitch damping was not as large as expected; that generally the high angle motion was lightly damped; and that in all probability the models were unstable to varying degrees. This confirms the wind tunnel data which indicated instabilities at large angles of attack and the possibility of relatively large trim angles.

After having completed these last studies, and with a full evaluation of all available test results, it was concluded that no one of the several configurations tests was acceptable. It was felt that Configuration 6 (see Figure 8), though the best of the original designs, in the last analysis did not satisfy all requirements of the Lazy Dog concept. In an effort to find a more optimal configuration, some added criteria were established from which two new designs evolved. These designs were to have the low drag of Configurations 4 and 6, yet they would hopefully have better stability characteristics, both static and dynamic. The criteria on stability suggest that the new configurations must have adequate stability up through angles of attack of 90 degrees, and have adequate damping to reduce pitching (in particular) to a low level within a few oscillations. Such requirements are necessary if the weapon is to properly trail and have a reasonably predictable trajectory. Configurations without fairly large damping and with good lifting capacities have the undesirable tendency of "sailing" rather than "falling" along their free-flight trajectories.

The design analysis, using the bullet core as the basic body, incorporated empirical data from reference (5). Thus, the analysis included several stabilizer configurations. The final selection was made in favor of fins having a rectangular planform. Primarily this selection was made in order to keep the center of pressure aft and to achieve the required static margin, namely, $(X_{RC}-X_{CP})=0.75$ calibers.

The overall center of pressure for the configuration can be estimated from a weighted factor formulation which includes only the known center of pressure locations for the various body elements and neglects interference and interaction effects. The mathematical description for a composite configuration is

$$X_{CP_{(C+F)}} = \frac{C_{N_{\alpha_{(C)}}} X_{CP_{(C)}} + C_{N_{\alpha_{(F)}}} \frac{2A_{(F)}}{A_{(C)}} X_{CP_{(F)}}}{C_{N_{\alpha_{(C)}}} + C_{N_{\alpha_{(F)}}} \frac{2A_{(F)}}{A_{(C)}}}$$
(3)

where subscripts (c) and (f) refer to the "core" and "fin", respectively; $A_{(F)}$ and $A_{(C)}$ are reference areas, and

 $A_{(F)} = \frac{b}{2} \times c$. Incidentally, the factor "2" is introduced into the equation to signify that two of the fins influence the center of pressure location. In view of the fact that the proposed configuration is one having cruciform fins, then (it is assumed that) only two fins would be influenced by a pitching action. Coupled effects, like interference effects, are neglected here.

The particulars of these newest configurations are as follows: It was estimated that the mass center for the core body and cruciform fins would be located 2.8 calibers (1.20 inches) aft of the nose. With the static margin set at 0.75 calibers (0.32 inches), then the overall center of pressure would be located at 3.55 calibers (1.52 inches) aft of the vehicle nose. These specifications, coupled with the aerodynamic data for the core, taken at a free-stream Mach number of 0.50, and data contained in reference (5), account for the calculated fin dimensions. A plot of the required span, as a function of chord length for these conditions, is given on Figure 65. Two configurations, selected from the possible family of solutions and designated as Configurations 7 and 8. are shown as Figures 9 and 10, respectively. It is apparent that these two designs are distinctive by the difference of fin dimensions selected for them. To date, no tests have been made on these configurations. They have been proposed for subsequent evaluation.

In connection with the overall research program, several particle, free-flight trajectories were calculated. These

trajectories do not show the influence of vehicle aerodynamics, except for drag, and only represent the motion in a vertical plane. Also, these particular studies were carried out in terms of a selected fixed parameter (W/CD) for each path. In this regard the variation of $\mathbf{C}_{\mathbf{D}}$ with Reynolds number and Mach number has been neglected. Primarily, the altitudes (and, in general, the velocities) are so low as to neglect the influence of these various dimensionless quantities. The trajectory analyses were conducted and results are included here to illustrate the influence of drag, or specifically $\mathbf{C}_{\mathbf{D}}$, on impact conditions; and to ascertain what launch conditions would be required to have the weapon reach the ground with the required kinetic energy.

The trajectory analysis is summarized on Figures 66 through 69. Each graph will show two reference velocities; one, the lower reference value, corresponding to a selected kinetic energy (at impact) of 58 foot-pounds, and the larger value (marked V_+) corresponding to the sea level terminal velocity for the particle having a value of (W/C_n) prescribed for that figure. Most of the results are similar, and the data of Figure 68, for the case of $(W/C_D) \approx 0.75$, are typical. The bomblet, when released from an altitude of 100 feet with no initial velocity, will strike the ground at a speed of 80 fps. This corresponds to an impact kinetic energy of 13.12 foot-pounds (the bomblet has a mass of approximately 0.0041 g-pounds). Therefore, the weapon would have to be launched from a 100 foot altitude at a speed of 140 fps to have the desired 58 foot-pounds of kinetic energy at impact. In the extreme case of a launching at 800 fps from a 100 foot altitude, the bomblet reaches the ground with an impact speed of 710 fps, corresponding to a kinetic energy of 1033.4 foot-pounds. Apparently, up through altitudes of 1,000 feet, at a launch speed of approximately 425 fps, the bomblet will impact at nearly a fixed speed -- or at essentially a fixed kinetic energy. At an altitude of approximately 5,000 feet, and upward, the launching speed has only a small influence on the impact speed; that is, the bomblet has about the same level of kinetic energy at impact, regardless of the initial speed. Though it is not apparent from the graph, the trajectory data show that for the higher altitudes the weapon's velocity first decreases (due to drag deceleration), passes through a lowest speed, and then accelerates slowly (due to gravity) as it continues to fall along its trajectory.

The above comments are generally true for all graphs of impact speed versus initial speed; the numbers quoted above are necessarily true only for the one case considered. This is evidenced by the differences in drag coefficients for the graphs. For instance, $(W/C_D) = 0.75$ corresponds to a bomblet

with a $\rm C_D\approx 0.176$, while for a (W/C_D) = 0.25 the $\rm C_D\approx 0.528$. It is expected that the proposed designs would have a drag coefficient somewhere between these levels at subsonic speeds. The general picture of drag influence on a trajectory is available from these figures (66 through 69), and a changing drag can be interpreted from a visual interpolation of the graphs.

In conclusion, a final comment is offered on the proposed Lazy Dog designs (Configurations 7 and 8): No attempt has been made to predict any of the dynamic characteristics for these shapes. It is well known that dynamic predictions are mere guesses, particularly at transonic speeds. There is good reason to believe that the suggested designs will be an improvement over the configurations tested; however, the verification of this surmise awaits actual experimental results.

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| | | NOTES | -5 TO+15 CNECM TESTS | -5 TO +15 CN CW TESTS | 510+15 CN&CM TESTS | -510 +15 CNCCM TESTS | 4 - STO+19 CNECM TESTS | -5ro+15 Cu&CuTESTS | PITCH | ROLL | -610+86 CNECM TESTS | PROPOSED | CONFIG'S | A LAUNCH | 4: LAUNCH |
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TABLE 2

TABULATED DATA

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TABULATED DATA

Normal Force and Pitching Moment Coefficients

| WTR | RUN CONFI | lG. |
|--------|----------------|---------|
| 739 | 21 1 | |
| a(deg) | C _w | C_ |
| - 4.98 | -0.4663 | -0.1645 |
| -04.07 | -0.3826 | -0.1464 |
| -02.82 | -0.3109 | -0.0911 |
| -01.07 | -0.1435 | -0.0549 |
| 00.03 | -0.0478 | -0.0183 |
| 01.08 | 0.0478 | 0.0183 |
| 01.99 | 0.1316 | 0.0364 |
| 03.09 | 0.2272 | 0.0730 |
| 04.03 | 0.2990 | 0.1005 |
| 05.05 | 0.3826 | 0.1464 |
| 06.08 | 0.4783 | 0.1830 |
| 07.15 | 0.5379 | 0.2478 |
| 08.28 | 0.6335 | 0.3123 |
| 09.08 | 0.6933 | 0.3491 |
| 10.03 | 0.7530 | 0.3859 |
| 11.00 | 0.8366 | 0.4578 |
| 12.10 | 0.9202 | 0.5337 |
| 13.07 | 0.9919 | 0.5611 |
| 14.02 | 1.0756 | 0.6071 |
| 15.01 | 1.1473 | 0.6346 |
| 15.83 | 1.2310 | 0.6306 |

| WTR | RUN CONFIC | 3. |
|---------|------------|---------------|
| 739 | 22 2 | |
| a (deg) | C | C |
| -05.02 | -0.4660 | 0.1(55 |
| -04.00 | -0.4062 | 0.1422 |
| -03.20 | -0.3465 | 0.1189 |
| -02.11 | -0.2389 | 0.0656 |
| -01.01 | -0.1434 | 0.0617 |
| 00.02 | -0.0837 | 0.0383 |
| 01.04 | 0.0239 | -0.0149 |
| 02.03 | 0.1434 | -0.0617 |
| 03.11 | 0.2390 | -0,0935 |
| 04.06 | 0.3107 | -0.1104 |
| 05.03 | 0.3703 | -0.1058 |
| 36.10 | 0.4779 | -0.1571 |
| 07.06 | 0.5735 | -0.1909 |
| | 0.6452 | - 1,2358 |
| 08.02 | 0.7408 | -0.2676 |
| 09.13 | 0.8364 | -0.2994 |
| 10.66 | 0.8961 | -0.3228 |
| 11.03 | 0.6751 | -0.3612 |
| 12.13 | | -0.3975 |
| 13.11 | 1.0534 | -0.4443 |
| 14.05 | 1.1352 | -C.4362 |
| 15.05 | 1.2308 | - C + 4 - O L |

| WTR | RUN CONFI | G. |
|--------|-----------|---------|
| 739 | 33 3 | |
| a(deg) | C | C |
| -05.06 | -0.4090 | 0.1567 |
| -04.05 | -0.3315 | 0.0921 |
| -03.12 | -0.2652 | 0.0737 |
| -02.15 | -0.1379 | 0.0608 |
| -00.97 | -0.1216 | 0.0424 |
| 00.00 | -0.0553 | 0.0240 |
| 01.08 | 0.0442 | -0.0037 |
| 02.03 | 0.1106 | -0.0480 |
| 03.21 | 0.1878 | -0.0349 |
| 04.08 | 0.2542 | -0.0792 |
| 05.03 | 0.3205 | -0.0377 |
| 06.08 | 0.3868 | -0.1161 |
| 07.18 | 0.4753 | -0.1751 |
| 08.28 | 0.5526 | -0.1880 |
| 09.10 | 0.6189 | -0.2064 |
| 10.17 | 0.6742 | -0.2304 |
| 11.10 | 0.7627 | -0.2895 |
| 12.04 | 0.8400 | -0.3023 |
| 13.11 | 0.9054 | -0.3207 |
| 14.09 | 0.9727 | -0.3392 |
| 15.05 | 1.0279 | -c.3373 |
| 15.42 | 1.0743 | -0074 |

| WTR | RUN CONFIG | |
|---------|------------|---------|
| 739 | 37 4 | |
| a(deg) | C | C |
| -04.60 | -0.5264 | 0.1390 |
| -03.09 | -0.3913 | 0.0847 |
| -01.98 | -0.2795 | 0.0584 |
| -01.02 | -0.1770 | 0.0200 |
| 00.10 | -0.0606 | 0.0009 |
| 01.00 | 0.0419 | -0.0241 |
| 02.05 | 0.1444 | -0.0585 |
| 03.01 | 0.2009 | -0.0873 |
| 04.14 | 0.3960 | -0.1250 |
| 05.06 | 0.4705 | -0.1254 |
| 06.33 | 0.6149 | -0.1838 |
| 07.05 | 0.7313 | -0.2409 |
| 08.12 | 0.8198 | -0.2746 |
| 09.09 | 0.9823 | -C.341: |
| 10.05 | 1.1040 | -0.3950 |
| 11.01 | 1.02)64 | -0.4516 |
| 12.12 | 1.3649 | -0.5:29 |
| 13.07 | 1.5001 | -0.6135 |
| . 14.05 | 1.5209 | -0.6742 |
| 15.00 | 1.7699 | -0.7625 |
| 15.84 | 1.8724 | -0.0190 |

| WIR | RUN CONFI | G. |
|--------------|----------------|---------|
| 7 3 9 | 09 5 | |
| a(deg) | C _丽 | C |
| -04.44 | -0.7262 | 0.5027 |
| -03.08 | -0.5121 | 0.3502 |
| -01.99 | -0.3631 | 0.2402 |
| -01.04 | -0.2281 | 0.1489 |
| 00.02 | -0.0792 | 0.0390 |
| 01.04 | 0.0558 | -0.0523 |
| 02.03 | 0.2002 | -0.1450 |
| 03.27 | 0.3677 | -0.2575 |
| 04.04 | 0.5120 | -0.3613 |
| 05.00 | 0.6703 | -0.4614 |
| 06.23 | 0.8193 | -0.5714 |
| 06.99 | 1.0008 | -0.7248 |
| 08.05 | 1.1451 | -0.3376 |
| 39.04 | 1.2820 | -0.9642 |
| 10.10 | 1.4755 | -1.1252 |
| 11.09 | 1.6477 | -1.2384 |
| 12.17 | 1.8199 | -1.4627 |
| 13.14 | 2.0200 | -1.5632 |
| 14.08 | 2.1829 | -1.8250 |
| 15.07 | 2.3597 | -2.0167 |
| 15.46 | 2.4657 | -2.1375 |

| VTR 729 | RUN CONF | IG. |
|-------------------------|----------------------------|-------------------------------|
| a(deg) | C | C |
| -04.88 -04.02 | -0.5340 -0.4577 | C.2345 |
| -03.01 -01.98 | -0.3362 -0.2527 | 0.1673 |
| -01.11 00.05 | -0.1812 -0.0620 | 0.0769 0.0439 |
| 01.05 02.07. | 0.0382 | -0.0078 -0.0274 |
| 03.08 | 0.2623 0.3385 | -0.0794 -0.1064 |
| 05.09 | 0.4434 | -0.1450 -0.1912 |
| 07.07 | 0.6399 | -0.2103 -0.2544 |
| 09.10 10.10 11.08 | 0.8487 | -0.1048 -0.3356 |
| 12.07 | 1.0156 | -0.3873 -0.4333 |
| 14.01 | 1.2310 1.3155 1.3070 | -0,4927 -0,55.0 -0,5702 |
| 15,70 | 1.4.,04 | -0.6041 |

| WIR | RUN | CONFIG | • |
|--------|--------|--------|---------|
| 739 | 20 | 1 | |
| a(deg) | C | K | C E |
| -05.09 | -0.4 | 284 | -0.1573 |
| -04.10 | -0.3 | 599 | -0.1311 |
| -02.89 | -0.2 | 628 | -0.1000 |
| -02.04 | -0.1 | 942 | -0.0743 |
| -01.10 | -0.1 | 142 | -0.0437 |
| 00.13 | -0.0 | 114 | -0.0177 |
| 01.09 | 0.0 | 629 | 0.0174 |
| 02,05 | 0.1 | 714 | 0.0523 |
| 03.05 | 0.2 | 399 | 0.0785 |
| 04.04 | 0.3 | 1.42 | 0.1003 |
| 05.05 | 0.3 | 942 | 0.1442 |
| 06.00 | 0.4 | 456 | 0.1572 |
| .07.02 | 0.5 | 483 | 0.2232 |
| 08.11 | 0.6 | 283 | 0.2671 |
| 09.10 | 0.7 | 082 | 0.3111 |
| 10.06 | 0.7 | 539 | 0.3419 |
| 11,00 | 0.8 | | 0.3947 |
| 12.08 | 0.9 | | 0.4341 |
| 13.02 | 1.00 | | 0.4781 |
| 14.10 | 1.1 | | 0.5174 |
| 15.09 | 1.1 | _ | 0.5436 |
| 15.65 | 1 • 2. | 393 | 0.5610 |

M=0.80

| WTR 739 | RUN CONFIC | 3. |
|--|--|--|
| a(deg) | C | C BA |
| -04.79 -04.39 -03.00 -02.15 -01.38 00.03 01.17 02.04 03.05 | -0.4568 -0.3997 -0.3083 -0.2341 -0.1256 -0.0228 0.0800 0.1528 0.2399 0.3141 | 0.2539 0.2098 0.1661 0.1263 0.0652 0.0009 -0.0500 -0.0559 -0.1633 -0.1897 |
| 04.10 05.05 06.04 07.05 08.33 09.05 10.04 11.15 12.12 13.23 14.05 15.02 | 0.4226 0.5025 0.5381 0.6908 0.7422 0.8279 0.9078 0.9991 1.0905 1.1533 1.2333 1.2789 | -0.2508 -0.2875 -0.3076 -0.3452 -0.3706 -0.4175 -0.4541 -0.4979 -0.5416 -0.5742 -0.6242 -0.6528 |

| WIR | RUN CONF | IG. |
|--------|----------|----------------|
| 739 | 3.2 3 | |
| a(deg) | c | C _m |
| -04.52 | -0.3880 | 0.1790 |
| -04.11 | -0.3594 | 0.1532 |
| -03.10 | -0.2795 | 0.1132 |
| -02.11 | -0.2054 | 0.0837 |
| -01.13 | -0.1312 | 0.0409 |
| 00.12 | -0.0228 | -0.0115 |
| 01.09 | 0.0514 | -0.0410 |
| 01.89 | 0.1313 | -0.0810 |
| 03.03 | 0.2055 | -0.1105 |
| 04.02 | 0.2910 | -0.1476 |
| 05.03 | 0.3709 | -0.1876 |
| 06.01 | 0.4555 | -0.2247 |
| 07.03 | 0.5421 | -0.2752 |
| 08.03 | 0.6334 | -0.3228 |
| 09.09 | 0.7133 | -0.3494 |
| 10.13 | 0.7761 | -0.3846 |
| 11.08 | 0.48560 | -0.4246 |
| 12.05 | 0.9415 | -0.4484 |
| 13.02 | 1.0100 | -0.4808 |
| 14.11 | 1.1012 | -0.5017 |
| 15.22 | 1.1583 | -0.5264 |

M-0,80

| WTR | RUN | COMFIG | • |
|---------|------|--------|---------|
| 739 | 06 | 4 | |
| a (deg) | C | M | Cal |
| -04.47 | -0.6 | | 0.2547 |
| -04.03 | -0.5 | | 0.2101 |
| -03.04 | -0.4 | | 0.1495 |
| -02.04 | -0.2 | | 0.1038 |
| -00.91 | -0.1 | | 0.0506 |
| 00.33 | -0.0 | | 0.0024 |
| 01.08 | | 948 | -0.0307 |
| 02.06 | | 1132 | -0.0719 |
| 03.05 | | 1293 | -0.1036 |
| 04.00 | | 643 | -0.1607 |
| 05.00 | | 5543 | -0.1893 |
| 06.12 | | 7131 | -0.2512 |
| 07.11 | 0.8 | 3457 | -0.3100 |
| 08.00 | | 381 | -0.3538 |
| 09.17 | | 1110 | -0.4389 |
| 10.13 | | 2271 | -0.5045 |
| 11.01 | | 3479 | -0.5665 |
| 12.00 | | 4758 | -0.6401 |
| 13.00 | | 6131 | -0.7067 |
| 14.12 | | 7671 | -0.8003 |
| 15.11 | | 8950 | -0.8740 |
| 16.09 | | 0276 | -0.9554 |
| 16.15 | 2 . | 0394 | -0.3148 |

M-0,80

| WIR | RUN | Config | • |
|---------|---------|--------|----------|
| 739 | 10 | 5 | |
| a (dog) | C | | C |
| -04.52 | -0.75 | 594 | 0.6581 |
| -04.10 | -0.68 | 350 | 0.5701 |
| -03.07 | -0.50 | 95 | 0.4392 |
| -01.91 | -0.32 | 293 | 0.2789 |
| -01.05 | -0,21 | 115 | 0.1733 |
| 00.02 | -0.08 | 389 | 0.0499 |
| 01.12 | 0.11 | 370 | -0.1026 |
| 02.10 | 0.3 | .96 | -0.2718 |
| 03.02 | 0 . 4 . | 78 | -0.3545 |
| 03.99 | 0.60 | 56 | -3.5216 |
| 05.01 | 0.77 | 737 | -0.6608 |
| 06.00 | 0.93 | 149 | -0.8119 |
| 07.14 | 1012 | 271 | -0.9940 |
| 08.30 | 1.31 | 23 | -1e1875 |
| 09.09 | 1.48 | 176 | -1.3432 |
| 10.06 | 1.64 | 86 | -1.4950 |
| 11.04 | 1.85 | 28 | -1,7046 |
| 12.15 | 2.07 | 87 | -1.09315 |
| 13.13 | 2.24 | 21 | -2.0866 |
| 14.10 | 2.47 | 04 | -2,3168 |
| 15.10 | 2.466 | 02 | -2.5071 |
| 15.67 | 2.67 | 7.0 | -2,5181 |

| WIT | RUB | COMPIG | • |
|---------|----------------|--------|---------|
| 739 | 02 | 6 | |
| a (deg) | \mathbf{c}_1 | Ĭ | C |
| -04.40 | -0.5 | 321 | 0.2438 |
| -03.08 | -0.3 | 937 | 0.1705 |
| -02.05 | -0.21 | B 6 7 | 0.1312 |
| -01.06 | -0.1 | 579 | 0.0657 |
| -00.02 | -0.04 | 462 | 0.0283 |
| 01.01 | 0.08 | 326 | -0.0372 |
| 02.04 | 0.19 | 920 | -0.0872 |
| 03.07 | 0.3 | 110 | -0.1333 |
| 04.08 | 0040 | 182 | -0.1706 |
| 05.09 | 0.53 | 346 | -0.2313 |
| 06.08 | 0.62 | 269 | -0,2647 |
| 07.07 | 0.73 | 3 1 4 | -0.3108 |
| 08.06 | 0.84 | 8 C+ | -0.3549 |
| 09.07 | 0.94 | +04 | -0.3971 |
| 10.08 | 1.03 | 352 | -0.4353 |
| 11=07 | 1.13 | 372 | -0.4823 |
| 12.08 | 1.23 | 393 | -0.5235 |
| 13.07 | 1.33 | 316 | -0.5627 |
| 14.06 | 1,44 | +10 | -0.6069 |
| 15.02 | 1.52 | 360 | -C.6489 |
| 15.67 | 1.60 | 38 | -0.6707 |

| MIB | RUB CONFIG. | |
|--------|----------------|----------|
| 739 | 19 1 | |
| a(deg) | C ^M | C |
| -05.07 | -0.4529 | -0.1621 |
| -04.13 | -0.3758 | -0.1213 |
| -03.03 | -0.2843 | -0.0919 |
| -02.05 | -0.2024 | -0.0550 |
| -01.10 | -0:1205 | -0.0405 |
| 00.11 | -0.0193 | -0.0074 |
| 01.05 | 0.0826 | 0.0184 |
| 02.01 | 0.1446 | 0.0441 |
| 03.07 | 0.2265 | 0.0698 |
| 04.00 | 0.3084 | 0.1068 |
| 05.10 | 0.3999 | 0.1362 |
| 06.02 | 0.4625 | 0.1545 |
| 07.10 | 0.5589 | 0.2027 |
| 08.06 | 0.6263 | 0.2285 |
| 09.02 | 0.7130 | 0,2954 |
| 10.11 | C.8045 | 0.3360 |
| 11.03 | Q.8316 | 0.3655 |
| 12,00 | 0.9731 | 0.3949 |
| 13.07 | 1.0647 | 0 • 4244 |
| 14.06 | 1.1559 | 0.4575 |
| 15.03 | 1.3526 | 0.4682 |
| 15.31 | 1.3153 | 0.4753 |
| | | |

| WIR | Run | COMPI | G. |
|--------|-------|-------|---------|
| 739 | 24 | 2 | |
| a(deg) | C | V | C |
| -05.04 | -0.4 | 765 | 0.2978 |
| -04.10 | -0.4 | 050 | 0.2587 |
| -03.09 | -0.3 | 240 | 0.2137 |
| -02.08 | -0.2 | 383 | 0.1601 |
| -01.15 | -0.1 | 430 | 0.1005 |
| 00.10 | -0.0 | 286 | 0.0179 |
| 01.05 | C.O | 620 | -0.0443 |
| 02.03 | 0.1 | 525 | -0.1005 |
| 03.02 | 0.2 | 383 | -0.1712 |
| 04.08 | 0.3 | 336 | -0.2308 |
| 05.06 | 0.4 | 146 | -0.2758 |
| 06.01 | 0.50 | 98 | -0.3243 |
| 07.13 | 0.60 | 003 | -0.3641 |
| 08:08 | 0.6 | 718 | -0.4032 |
| 09.03 | 0.74 | +32 | -0.4423 |
| 10.10 | 0.84 | 432 | -0.4882 |
| 11.06 | 0.92 | 342 | -0.5221 |
| 12.03 | 0.91 | 356 | -0.5612 |
| 13.25 | 1.00 | 361 | -0.6011 |
| 14.03 | 1.615 | 24 | -0.5487 |
| 15.11 | 1.25 | 74 | -0.0945 |
| 15.56 | 1.50 | 175 | -0.7184 |

M=0.95

| ALE | ruh | CONFIC | i. |
|--------|---------|--------|---------|
| 739 | 31 | 3 | |
| a(deg) | C | N | C |
| -05.09 | -0.4 | 770 | 0.3352 |
| -04.06 | -0.4 | 000 | 0.3063 |
| -03.07 | -0.3 | 132 | 0.2372 |
| -02.04 | -0.2 | 409 | 0.1833 |
| -01.09 | -0.1 | 446 | 0.1077 |
| 00.02 | -0.0 | 434 | 0.0346 |
| 01.09 | 0.0 | 530 | -0.0410 |
| 02.05 | 0.1 | 494 | -0.1053 |
| 03.16 | 0.24 | 457 | -0.1584 |
| 04.12 | 0.33 | 324 | -0.2275 |
| 05.10 | 0.40 | 095 | -0.2677 |
| 06.05 | 0 • 4 | 721 | -0,3038 |
| 07:25 | 0.51 | 781 | -0.3633 |
| 08.23 | 0.66 | 548 | -0.4099 |
| 09.03 | 0.71 | 371 | -0.4751 |
| 10.08 | 0.81 | 141 | -0.5040 |
| 11.03 | 0.89 | 960 | -0.5530 |
| 12.08 | 0.98 | 327 | -0.5996 |
| 13.00 | 1.06 | 94 | -0.6462 |
| 14.07 | 1 . 1.5 | 000 | -0.6928 |
| 15.01 | 1.22 | 283 | -C.7241 |
| 15.77 | 1.30 |)53 | -0.7530 |

| WIR | RUH CON | FIG. |
|--------|---------|-----------------|
| 739 | 05 4 | |
| a(deg) | C | C |
| -04.47 | -0.7803 | 0.4981 |
| -04.02 | -0.6485 | 0.4180 |
| -03.13 | -0.5533 | 0.3299 |
| -02.08 | -0.3648 | 0.2149 |
| -01.00 | -0,2088 | 0.1143 |
| -00.00 | -0.0183 | 0.0008 |
| 01.04 | 0.1257 | 0.0654 |
| 02.09 | 0.2939 | 0.1714 |
| 03.01 | 0.4358 | -0.2343 |
| 04.03 | 0,5979 | -0.3351 |
| 05.07 | 0.7013 | -0.3641 |
| 06.07 | 0.8412 | 0.4382 |
| 07.12 | 0.7932 | -0.5225 |
| 08.11 | 1.1472 | -0.6053 |
| 09.14 | 1.2770 | 0.6773 |
| 10.03 | 1.3925 | -0.7309 |
| 11.00 | 1.5192 | -0.7953 |
| 12.01 | 1.6520 | 0.8653 |
| 13.13 | 1,7898 | ~0. 9360 |
| 14.11 | 1,0155 | -1.0062 |
| 15.76 | 7.1020 | .1.0792 |

N=0.95

| FTR | run con | FIG. |
|--------|---------|----------|
| 739 | 12 5 | |
| e(dog) | C | C |
| -04.47 | -0.8749 | 0.9775 |
| -03.02 | -0.6034 | 0.6745 |
| -02.13 | -0.4575 | 0.4917 |
| -01.13 | -0.2615 | 0.3015 |
| 00.02 | -0.0603 | 0.0447 |
| 00.96 | 0.1407 | -0.1402 |
| 02.26 | 0.3570 | -0.4052 |
| 03.01 | 0.4877 | +0.5439 |
| 04.00 | 0.6733 | -0.7686 |
| 05.04 | 0.8498 | -0.9558 |
| 06.04 | 1.0458 | -1.1461 |
| 07.04 | 1.2167 | -1.3266 |
| 08.05 | 1.4078 | -1.5221 |
| 09.08 | 1.6089 | -1.7310 |
| 10.09 | 1.7898 | -1.9249 |
| 11.11 | 1.9959 | -7.1166 |
| 12.11 | 2.1919 | -2.054 |
| 13.12 | .4120 | -2:05057 |
| 14.16 | 2.5141 | -2.7037 |
| 15.84 | 1.010 | -3.2052 |

₽-0.95

| 739 | RUM CONFI | G, |
|--|---|---|
| e(dog) | C | C |
| -04.45 -03.10 -02.05 -01.07 00.05 01.09 02.11 03.13 04.12 05.12 06.12 07.11 08.08 09.11 | -0.7191 -0.5154 -0.3556 -0.2137 -0.0559 0.0899 0.2357 0.3576 0.4615 0.5934 0.7133 0.8052 0.9211 1.0210 1.1269 | 0.4808 0.3366 0.2324 0.1402 0.0353 -0.0458 -0.1364 -0.1983 -0.2435 -0.3641 -0.3641 -0.3997 -0.4449 -0.458 -0.5311 |
| 11.11 12.08 13.07 14.06 15.06 | 1.2208 1.3107 1.4067 1.4826 1.5666 | -0.5611 -0.5927 -0.6124 -0.6208 -0.5167 -0.6178 |

M=1.05

| WIR 739 | EUN COMP | IG. |
|----------------|----------------|--------------------------|
| a(deg) | CM | C |
| -04.82 | -0.4186 | -0.1756 |
| -04.04 | -0.3569 | -0.1510 |
| -03.11 | -0.2600 | -0.1046 |
| -02.03 | -0.1630 | -0.0675 |
| -01.10 | -0.0881 | -0.0440 |
| 00.00 | -0.0132 | -0.0205 |
| 00.96 | 0.0838 | 0.0063 |
| 02.35 03.04 | 0.1754 | 0.0151 |
| 04.01 | 0.2645 | 0.0498 |
| 05.01 | 0.3439 | 0.0596 |
| 06.13 | 0.5290 | 0.0899 |
| 07.07 | 2.6128 | 0.1201 |
| 08.06 | 0.7009 | 0.1265 |
| 09.04 | 0.7979 | 0.1499 0. 1768 |
| 10.03 | 0.9861 | 0.1899 |
| 11.03 | 0,9832 | 0.1859 |
| 12.00 | 1.0846 | 0.1784 |
| 13.12 | 1.3170 | 0.1571 |
| 14.11 | 1.3362 | 0.1358 |
| 15.11 | in mark to the | 0.1111 |
| 16.00 | 1.0877 | C.C1 |
| 16.33 | 1.6230 | 0.0860 |

| WTR | eun comp | IG. |
|--------|----------|---------|
| 739 | 25 2 | |
| a(deg) | C | C |
| -05.13 | -0.4855 | 0.2677 |
| -04.11 | -0.4155 | 0.2342 |
| -02.98 | -0.3193 | 0.1843 |
| -02.00 | -0.2302 | 0.1374 |
| -01.09 | -0.1356 | 0.0797 |
| 00.00 | -0.0219 | 0.0086 |
| 00.91 | 0.0569 | -0.0611 |
| 02.01 | C.1619 | -0.1268 |
| 03.09 | 0.2713 | -0.1900 |
| 04.04 | 0.3413 | -0.2338 |
| 05.03 | 0.4244 | -0.2806 |
| 06.13 | 0.5163 | -0.3329 |
| 07.08 | 0.5994 | -0.3798 |
| 08.20 | 0.6781 | -0.4035 |
| 09.03 | 0.7392 | -0.4263 |
| 10.10 | 0.8310 | -0.4582 |
| 11.0% | 0.9054 | -0.4791 |
| 12.03 | 0.9840 | -0.5079 |
| 13.09 | 1.0671 | -0.5240 |
| 14.16 | 1.1545 | -0.5625 |
| 15.09 | 1,2333 | -0.0074 |
| 16.09 | 1,3205 | -0.6574 |

| WIR | RUN CONF | IG. |
|---------|---------------------------|---------|
| 739 | 30 3 | |
| a (deg) | $\mathbf{c}^{\mathbf{M}}$ | C |
| -04.57 | -0.4066 | 0.1845 |
| -04.03 | -0.3541 | 0.1393 |
| -03.06 | -0.2710 | 0.0992 |
| -02.08 | -0.1923 | 0.3671 |
| -01.15 | -0.1093 | 0.0372 |
| 00.03 | -0.0131 | 0.0036 |
| 01.02 | 0.0700 | -0.0365 |
| 02.10 | 0.1618 | -0.0722 |
| 02.92 | 0.2230 | -0.1233 |
| 04.04 | 0.3018 | -C.1759 |
| 05.03 | 0.3893 | -0.2343 |
| 06.00 | 0.4724 | -0.2846 |
| 07.26 | 0.5687 | -0.3591 |
| 08.22 | 0.6562 | -0.4175 |
| 09.06 | 0.7262 | -0.4847 |
| 10.01 | 0.8137 | -0.5329 |
| 11.11 | 0.9029 | -0.5971 |
| 12.08 | 0.9930 | -0.6372 |
| 13.02 | 1.0761 | -0.6376 |
| 14.11 | 1.1502 | -0,7277 |
| 15.04 | 1.2510 | -0.7737 |
| 15.66 | 1.3035 | -0.7882 |

M=1.05

| WTR | RUN CONF | IG. |
|--------|----------|---------|
| 739 | 03 4 | |
| a(deg) | C | C |
| -04.58 | -0.8972 | 0.6872 |
| -04.01 | -0.7741 | 0.5646 |
| -03.09 | -0.6380 | 0.4604 |
| -02.01 | -0.4027 | 0.2816 |
| -01.02 | -0.2151 | 0.1414 |
| -00.01 | -0.0588 | 0.0349 |
| 01.08 | 0.1305 | -0.0995 |
| 02.22 | 0.3255 | -0.2254 |
| 03.08 | 0.4615 | -0.3077 |
| 04.06 | 0.6289 | -0.4235 |
| 05.08 | 0.8017 | -0.5352 |
| 06.06 | 0.9819 | -0.6589 |
| 07.21 | 1.0996 | -0.6936 |
| 08.10 | 1,2192 | -0.7532 |
| 09.13 | 1.3442 | -0.9174 |
| 10.12 | 1.4711 | -0.8758 |
| 11.00 | 1.5723 | -0.9185 |
| 12.00 | 1.6716 | -0.9494 |
| 12.99 | 1.7875 | -0.9898 |
| 14.00 | . 8960 | -1.0225 |
| 14.99 | 7017 | -1.0430 |
| 15.33 | 3837 | -1.0-43 |

| vir | RUN CONFIG. | |
|--------|-------------|----------------|
| 739 | 13 5 | |
| a(deg) | CM | C _m |
| -04.64 | -0.9568 | 0.2872 |
| -03.72 | -0.7346 | 0.7550 |
| -03.02 | -0.6075 | 0.6070 |
| -02.09 | -0.4126 | 0.4004 |
| -00.95 | -0.2358 | 0.2288 |
| 00.03 | -0.0317 | 0.0316 |
| 01.19 | 0.1768 | -0.1716 |
| 02.07 | 0.3718 | 0.3674 |
| 03.05 | 0.5441 | -0.5545 |
| 04.02 | 0.7346 | -0.7443 |
| 05.13 | 0.9341 | -0.9569 |
| 06.07 | 1.1337 | -1.1596 |
| 07.05 | 1.3378 | -1.3991 |
| 08.03 | 1.5464 | -1.6239 |
| 09.02 | 1.7505 | -1.8042 |
| 10.02 | 1.9709 | -2.1206 |
| 11.00 | 2.1995 | -2.3670 |
| 11.99 | 2.4172 | -2.5931 |
| 13.11 | 2,6803 | -2.8778 |
| 14.12 | 2.8934 | -3.1106 |
| 15.10 | 3.1292 | -3,3610 |
| 16.08 | 3.3878 | -3.05.24 |

| TTR 739 | RUN CONFI | G. |
|--|--|--|
| a(deg) | C | C wa |
| -04.86 -04.12 -03.06 -02.01 -01.13 00.01 01.03 02.04 03.08 04.08 | -0.7775 -0.6556 -0.5097 -0.3435 -0.2142 -0.0406 0.1127 0.2770 0.3971 0.5227 | 0.5985 0.5141 0.3994 0.2707 0.1760 0.0325 -0.0880 -0.2087 -0.2762 -0.3284 |
| 05.08 06.08 07.05 08.05 09.04 10.03 11.04 12.01 13.00 14.12 15.00 15.64 | 0.6539 0.7702 0.8755 0.9642 1.0530 1.1472 1.2359 1.3080 1.3857 1.3657 1.5557 | -0.4004 -0.4562 -0.4087 -0.5125 -0.5176 -0.5326 -0.5342 -0.5193 -0.5023 -0.4034 -0.4044 -0.4693 |

| -04.19 -0.3833 -0.1034 -03.11 -0.2802 -0.0886 -01.91 -0.1854 -0.0758 -01.00 -0.0988 -0.0571 00.03 -0.0041 -0.0166 02.02 0.1773 0.0342 04.11 0.3628 0.0811 05.04 0.4411 0.0876 05.04 0.4411 0.0876 07.03 0.6349 0.1120 08.08 0.7255 0.1622 09.02 0.8162 0.1777 10.09 0.9275 0.2154 11.01 1.0142 0.1757 12.06 1.1297 0.1652 13.09 1.2617 0.1652 14.14 1.3855 0.1550 | WTR | RUN CONF | IG. |
|---|--------|----------|---------|
| -05.04 | 739 | 17 1 | |
| -04.19 | a(deg) | C | C |
| -03.11 | -05.04 | -0.4534 | -0.1062 |
| -01.91 | -04.19 | -0.3833 | -0.1034 |
| -01.00 | -03,11 | -0.2802 | -0.0880 |
| 00.03 -0.0041 -0.0166 01.10 0.0866 -0.0005 02.02 0.1773 0.0342 03.07 0.2638 0.0625 04.11 0.3628 0.0811 05.04 0.4411 0.0870 06.07 0.5442 0.1120 07.03 0.6349 0.1179 08.08 0.7255 0.1622 09.02 0.8162 0.1777 10.09 0.9275 0.2154 11.01 1.0142 0.1757 12.06 1.1207 0.1726 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | -01.91 | -0.1854 | -0.0758 |
| 01.10 0.0866 -0.0005 02.02 0.1773 0.0342 03.07 0.2638 0.0625 04.11 0.3628 0.0811 05.04 0.4411 0.0870 06.07 0.5442 0.1120 07.03 0.6349 0.1179 08.08 0.7255 0.1622 09.02 0.8162 0.1777 10.09 0.9275 0.2154 11.01 1.0142 0.1757 12.06 1.1207 0.1726 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | -01.00 | -0.0988 | -0.0571 |
| 02.02 0.1773 0.0342 03.07 0.2638 0.0625 04.11 0.3628 0.0811 05.04 0.4411 0.0870 06.07 0.5442 0.1120 07.03 0.6349 0.1179 08.08 0.7255 0.1622 09.02 0.8162 0.1777 10.09 0.9275 0.2154 11.01 1.0142 0.1757 12.06 1.1207 0.1726 13.09 1.2617 0.1652 14.14 1.3855 0.1550 | 00.03 | -0.0041 | -0.0160 |
| 03.07 0.2638 0.0625 04.11 0.3628 0.0811 05.04 0.4411 0.0870 06.07 0.5442 0.1120 07.03 0.6349 0.1179 08.08 0.7255 0.1622 09.02 0.8162 0.1777 10.09 0.9275 0.2154 11.01 1.0142 0.1757 12.06 1.1297 0.1726 13.09 1.2617 0.1652 14.14 1.3855 0.1550 | 01.10 | 0.0856 | -0.0005 |
| 04.11 0.3628 0.0811 05.04 0.4411 0.0870 06.07 0.5442 0.1120 07.03 0.6349 0.1179 08.08 0.7255 0.1622 09.02 0.8162 0.1777 10.09 0.9275 0.2154 11.01 1.0142 0.1957 12.06 1.1297 0.1726 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | | 0.1773 | 0.0342 |
| 05.04 | 03.07 | 0.2638 | 0.0625 |
| 06.07 | 04.11 | 0.3628 | 0.0811 |
| 07.03 | 05.04 | 0.4411 | 0.0870 |
| 08.08 | | 0.5442 | 0.1120 |
| 09.02 0.8162 0.1777 10.09 0.9275 0.2154 11.01 1.0142 0.1757 12.06 1.1297 0.1726 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | 07.03 | 0.6349 | 0.1179 |
| 10.09 0.9275 0.2154 11.01 1.0142 0.1757 12.06 1.1297 0.1726 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | | 0.7255 | 0.1622 |
| 11.01 1.0142 0.1757 12.06 1.1297 0.1726 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | | 0.8162 | 0.1777 |
| 12.06 1.1207 0.1726 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | | 0.9275 | 0.2154 |
| 13.09 1.2617 0.1653 14.14 1.3855 0.1550 | | 1.0142 | 0.1757 |
| 14.14 1.3855 0.1550 | | 1.1297 | 0.1726 |
| 16.00 | | 1.2617 | 0.1653 |
| 15.09 1.5/22 0 2//4 | | | 0.1550 |
| | | 1.5092 | 0.1/46 |
| 16.32 1.6908 0.1082 | 16.32 | 1.5708 | 0.1082 |

| 739 | RUN CONFIC | |
|--------|-------------|-----------|
| a(deg) | C | C |
| -05.08 | -0.4987 | 0.3166 |
| -04.12 | -0.4287 | C.2872 |
| -03.33 | -0.3463 | 0.2357 |
| -02.24 | -0.2473 | 0.1739 |
| -01.03 | -0.1278 | 0.1040 |
| 00.03 | -0.0083 | 0.0148 |
| 01.21 | 0.0550 | -0.0509 |
| 02.10 | 0.1731 | -0.1179 |
| 03.17 | 0.2762 | -0.1871 |
| 04.13 | 0.3677 | -0.2364 |
| 05.07 | 0.4534 | -0.2930 |
| 00.13 | 0.5440 | -0.3.01 |
| 07.74 | 0.6306 | -0.3797 |
| 08.11 | 7274 | -0.4753 |
| 09.15 | 0.8377 | -0.4664 |
| 10.08 | B.8860 | -0.5009 |
| 11.00 | 0500 | -0.5206 |
| 12.05 | 1.00,34 | -) 654/2 |
| 13.08 | 1-1-31 | -0.5734 |
| 14.13 | 1.2278 | -0.5042 |
| 15.07 | 1 + 2 1 2 4 | -0.6220 |
| 16.5 | | -0.5616 |

| WIR | RIVIN | CONFIG. | |
|--------|----------------|---------|---------|
| 739 | 29 | 5 | |
| a(deg) | C | H | C |
| -04.89 | -0.4 | | 0.1917 |
| -04.05 | C • 3 | 542 | 0.1498 |
| -03.37 | -0.2 | 965 | 0.1209 |
| -02.00 | -C • 1 | 853 | 0.0708 |
| -01.09 | -0.1 | 030 | 0.0447 |
| 00.03 | -0.0 | 165 | 0.0014 |
| 01.14 | 0.0 | 783 | -0.0474 |
| 02,22 | 0.1 | 524 | -0.0777 |
| 03.04 | 0.2 | 104 | -0.1120 |
| 04.04 | 0.2 | 884 | -0.1443 |
| 05.04 | 0.3 | 273 | -0.2007 |
| 06.17 | 0.4 | 82C | -0.24)5 |
| 07.01 | 0.5 | 645 | -0.3045 |
| 08.04 | 2.5 | 592 | -0.3630 |
| 09.10 | 0.7 | 540 | -0.4214 |
| 10.14 | ^ . 8 · | 488 | -0.4505 |
| 11.29 | 0.9 | | -0.5170 |
| 12.05 | 11.0 | 1-3 | -0.5450 |
| 13.39 | 1.00 | 277 | -0.5719 |
| 14.00 | 1.1 | 742 | -0.056 |
| 15.21 | ' | ₹ ? e | -0.6755 |
| 15.67 | 11.35 | £ 4 | -0.6977 |

M=1.15

| WTR | RUH CONFI | G. |
|--------|----------------|--------------|
| 739 | 02 4 | |
| a(deg) | C _N | C. |
| -04.62 | -0.8507 | 0.6561 |
| -04.07 | -0.7433 | 0.5547 |
| -03.05 | -0.5822 | 0.4315 |
| -02.00 | -0.3621 | 0.2700 |
| -00.91 | -0.1698 | 0.1207 |
| 00.02 | -0.0295 | 0.0151 |
| 01.03 | 0.1334 | -0.0860 |
| 02.10 | 0.3154 | -0.2224 |
| 03.06 | 0.46.7 | -0.3105 |
| 04.14 | 0.6221 | -0.4101 |
| 05.06 | 0.7711 | -0.5092 |
| 06.00 | 0.9184 | -0.c014 |
| 07.10 | 1.0969 | -0.7156 |
| 08.03 | 1.2371 | -0.8045 |
| 09.01 | 1.3880 | -0.9066 |
| 10.03 | 1.5578 | -1.0150 |
| 11.03 | 1.7059 | -1,1050 |
| 18.11 | - 1.8767 | -1 - 2 1 4 2 |
| 13.05 | 2.0257 | -1.092 |
| 14.02 | 2.1678 | -1.4218 |
| 15.08 | 2256 | -1.4079 |
| 15.83 | 2.3845 | -1.6492 |

COEFIDERTIAL NOLTE 63-47

M-1.15

| WIR | eve comp | IG. |
|--------|---------------------------|----------|
| 739 | 14 5 | |
| a(deg) | $\mathbf{c}_{\mathtt{N}}$ | C |
| -04.87 | -1.0200 | 1.1068 |
| -04.08 | -0.8521 | 0.9133 |
| -03.02 | -0.6455 | 0.6834 |
| -02.18 | -0.4949 | 0.5282 |
| -01.01 | -0.2411 | 0.2913 |
| 00.02 | -0.0560 | 0.0645 |
| 01.12 | 0.1635 | -0.1673 |
| 01.94 | 0.3400 | -0.3621 |
| 03.02 | 0.5337 | -0.5901 |
| 04.08 | 0.7790 | -0.3462 |
| 05.03 | 0.9511 | -1.0455 |
| 06.05 | 1.1750 | -1.3036 |
| 07.00 | 1.3859 | -1.5341 |
| 08.04 | 1.6054 | -1.7864 |
| 09.12 | 1.8421 | -2.0412 |
| 10.05 | 2.0487 | 4-2.2967 |
| 11.12 | 2.2812 | -2.5663 |
| 12.02 | 1.5007 | -2.3084 |
| 13.09 | 2.7374 | -3.0734 |
| 14.04 | 2.9741 | -3.3202 |
| 15.25 | 1.24. 2 | -1.149 |
| 15.72 | 3.3873 | -3.1778 |

| WIR | RUN | CONFIC | }. |
|--------|-----------|--------|----------|
| 739 | 35 | ٤ | |
| a(deg) | C | n | C |
| -04.78 | -0.7 | 408 | 0.5995 |
| -04.04 | -0.6 | 165 | 0.4917 |
| -03.04 | -0.4 | 5 د 6 | 0.5031 |
| -02.04 | -0.3 | 367 | C.2635 |
| -01.C3 | -C.1 | 848 | 0.1500 |
| -00.02 | -0.0 | 276 | 0.0262 |
| 01.00 | 0.1 | 123 | -J.C796 |
| 02.00 | 0.2 | 487 | -0.1745 |
| 03.02 | 0.3 | 920 | -0.2749 |
| 04.02 | 0.5 | 250 | -0.3629 |
| 05.02 | €.5 | 373 | -0.4260 |
| 06.01 | 0.7 | 7:5 | -9.7038 |
| 07.00 | <u></u> S | 712 | -0.5738 |
| 07.99 | 1,00 | 1:0 | -0.015 |
| 29.01 | 1.1 | | -0.7271 |
| 10.16 | 1.2 | 702 | -0.8172 |
| 11.12 | 4 | - | -0.0087 |
| 12.10 | , o - | 147 | -0.7106 |
| 13.10 | 4.0 | 1, 4 | უე"ისხნ |
| 14.00 | | | -1.0130 |
| 15.06 | 1.63 | | -1.00567 |
| 10.60 | i o ?. | | -10077.0 |

COMFIDENTIAL WOLTE 63-47

| WTR | rue comp | IG. |
|--------|----------|---------|
| 739 | 16 1 | |
| a(deg) | CM | C |
| -04.57 | -0.4287 | -0.1177 |
| -04.05 | -0.3771 | -0.1026 |
| -03.53 | -0.3295 | -0.0937 |
| -03.04 | -0.2977 | -0.0815 |
| -02.52 | -0.2461 | -0.0664 |
| -02.00 | -0.1945 | -0.0605 |
| -01.50 | -0.1588 | -0.0422 |
| -01.01 | -0.1111 | -0.0333 |
| -00.47 | -0.0675 | -0.0212 |
| -00.02 | -0.0278 | -0.0153 |
| 00.57 | 0.0238 | 0.0091 |
| 01.08 | 0.0794 | 0.0211 |
| 01.60 | 0.1151 | 0.0302 |
| 02.00 | 0.1429 | 0.0362 |
| 02,49 | 2.1985 | 0.0482 |
| 03.03 | 0,2501 | 0.0633 |
| 03.53 | 0.2898 | 0.0785 |
| C4.07 | 0.3414 | 0.0843 |
| 04.45 | 0.3732 | 0.0872 |
| 05.00 | 0.4248 | 0.1022 |

M-1.26

| WTR | RUN CONFIC | 3. |
|----------------|---------------------------|--------|
| 739 | 16 1 | |
| $\alpha(\deg)$ | $\mathbf{c}^{\mathbf{M}}$ | C |
| 05.50 | 0.4545 | 0.1083 |
| 06.03 | 0.5200 | 0.1295 |
| 06.67 | 0.5577 | 0.1446 |
| 07.09 | 0.6193 | 0.1536 |
| 07.46 | 0.6511 | 0.1565 |
| 08.54 | 0.7543 | 0.1775 |
| 09.06 | 0.8059 | 0.1926 |
| 09.59 | 0.8975 | 0.1984 |
| 10.10 | 0.9891 | 0.2136 |
| 10.48 | 0.7528 | 0.2164 |
| 11.04 | 1.0005 | 0.2151 |
| 11.53 | 1.0640 | 0.2219 |
| 12.07 | 1.1236 | 0.2215 |
| 12.57 | 1.1832 | 0.2213 |
| 13.12 | 1 * 2467 | 0.2269 |
| 13.51 | 1.2904 | 0.2298 |
| 14.01 | 1.3540 | 0.2170 |
| 14.55 | 1.4175 | 0.2321 |
| 15.24 | 1.5049 | 0.2284 |
| 15 . c 1 | 1.5645 | 0.2373 |

M-1,26

| WTR 739 | EUN CONF : 27 2 | IG. |
|-------------------|------------------------|---------|
| a(deg) | CN | C |
| -04.54 | -0.4405 | 0.2800 |
| -03.33 | -0.3413 | 0.2226 |
| -02.04 | -0.2143 | 0.1525 |
| -01.65 | -0.1826 | 0.1234 |
| -00.99 | -0.1231 | 0.1001 |
| 00.11 | -0.0159 | 0.0192 |
| 01.14 | 0.0794 | -0.0496 |
| 02.08 | 0.1667 | -0.1135 |
| 03.21 | 0.2461 | -0.1631 |
| 04.05 | 0.3413 | -0.2226 |
| 05.00 | 0.4127 | -0.2580 |
| 06.00 | 0.5119 | -0.3061 |
| 27.08 | 2.6111 | -0.3542 |
| 08.23 | 0.7261 | -0.4029 |
| 09.00 | 3.7855 | -0.4169 |
| 10.01 | 0.8648 | -0.4387 |
| 11.05 | 0.9520 | -0.4561 |
| 12.09 | 1.0392 | -0.4643 |
| 12.78 | 1.1105 | -0.4718 |
| 14.03 | 1.7016 | -0.4592 |
| 15.07 | 1.3008 | -0.4887 |
| 15.66 | 1.2300 | -0.5012 |

| WTR | RUN CONF | IG. |
|--------|----------|---------|
| 739 | 28 3 | |
| a(deg) | CH | C |
| -04.51 | -0.3846 | 0.1501 |
| -03.99 | -0.3410 | 0.1164 |
| -03.07 | -0.2736 | 0.0946 |
| -02.00 | -0.1784 | 0.0588 |
| -01.08 | -0.0872 | 0.0211 |
| -00.02 | -0.3119 | 0.0033 |
| 01.01 | 0.0555 | -0.0278 |
| 02.06 | 0.1428 | -0.0675 |
| 03.01 | 0.2142 | -0.0966 |
| 04.02 | 0.3054 | -0.1250 |
| 05.01 | 0.4164 | -0.1713 |
| 06.00 | 8854.0 | -0.1931 |
| 07.08 | 0.5750 | -0.2401 |
| 08.10 | 0.6583 | -0.2813 |
| 09.00 | C.7416 | -0.3235 |
| 10.01 | 0.8288 | -0.3447 |
| 11.07 | 0.7082 | -0.3791 |
| 12.07 | 0.7953 | -0.3909 |
| 13.00 | 1.0786 | -3.4048 |
| 14.15 | 1.177 | -3.4473 |
| 15.37 | 1.2768 | -0,4-15 |
| 15.73 | 1.487 | -0.5014 |

M=1.26

| WIR | RUU | COMFIG | • |
|--------|---------|--------|------------|
| 739 | 01 | 4 | |
| a(deg) | c, | ı | C |
| -04.61 | -0.7 | 834 | 0.5659 |
| -04.21 | -0.60 | 950 | 0.4850 |
| -03.96 | -0.6 | 567 | C.4581 |
| -03.53 | -0.58 | B 6 7 | 0.4072 |
| -03.04 | -0.50 | 034 | 0.3464 |
| -02.63 | -0.4. | 334 | 0.2955 |
| -02.08 | -0.34 | 184 | 0.2359 |
| -01.59 | -0.23 | 500 | 0.1749 |
| -01.04 | -0.1 | 784 | 0.1129 |
| -00.51 | -0.10 | 133 | 0.0657 |
| 00.02 | -0.03 | | 0.0036 |
| 00.55 | 0.0 | 717 | -0.0497 |
| 01.24 | 2.1 | 717 | -0.1130 |
| 02.04 | 0.27 | | -0.1939 |
| 02.89 | 0.3. | | -0.2495 |
| 04.03 | 0.51 | | -0.3895 |
| 25.20 | 0.71 | | -0.4598 |
| 06.04 | 0.84 | | -0.5630 |
| 06.57 | 3.35 | | -0.6075 |
| 07.12 | 1 - 1 4 | | -0.6538 |
| 08.7% | 1.17 | | -0.7419 |
| 01.11 | 1. | | -0,7272 |
| 10.0: | . 0 1 | | -C -= 1. 4 |
| 11.16 | . 0 | | -1.000:4 |
| 12.04 | 7 - | | -1.5 |
| 13.11 | | | -1415 : 3 |
| 14.00 | 2.05 | | -1.2006 |
| 1.5 | 7.13 | | -1. |
| 157 | 3. | 1.0 | 4.17 |

COMPIDENTIAL NOLTE 63-47

M-1.26

| FTR | run conf | IG. |
|--------|----------------|-------------|
| 739 | 15 5 | |
| a(deg) | c ^M | C |
| -04.62 | -0.8953 | 3.0455 |
| -03.97 | -0.7544 | 2.7910 |
| -03.43 | -3.5632 | 0.6088 |
| -03.06 | -7.6:51 | 0.6212 |
| -02.39 | -0.4808 | 0.5044 |
| -02.C1 | -0.4187 | 0.4509 |
| -01.31 | -0.3192 | 0.3476 |
| -00.99 | -0.2280 | 0.2553 |
| -00.45 | -0.1337 | 0.1575 |
| 00.03 | -0.0374 | 0.0696 |
| 00.59 | 0.0562 | -0.0393 |
| 00+98 | 001112 | -0.1304 |
| 01.51 | 0.2163 | -0.171 |
| 02.03 | 0.8108 | -0.3247 |
| 02.42 | 0.4051 | -0 · 2 c 48 |
| 03.11 | 7.5253 | -).5259 |
| 03,43 | 0 0 : 5 1 | -0.6015 |
| 04,03 | 3.7004 | -0.7002 |
| 04.55 | 2.725,8 | -0.8158 |
| 05.12 | 0.7.01 | -0.1337 |
| 05,62 | 1 | -1.0303 |

| WIR | RUE | COMFIC | |
|---------|-------|-------------|---------|
| 737 | 15 | 5 | |
| a (deg) | C | H | C |
| 06.02 | 1.0 | 983 | -1.1225 |
| 06.54 | 1.2 | 020 | -1.2413 |
| 07.09 | 1.3 | 097 | -1.3458 |
| 07.59 | 1 . 4 | 051 | -1,4634 |
| 08.03 | 1.5 | 005 | -1.5612 |
| 08.55 | 1.6 | 165 | -1.6965 |
| 09.08 | 1.7 | 078 | -1.7986 |
| 09.59 | 1.8 | 2 79 | -1.9198 |
| 10.14 | 1.9 | 398 | -2.0299 |
| 10.52 | 2.0 | 269 | -2.1265 |
| 11,59 | 2.2 | 549 | -2.3621 |
| 11.97 | 2.3 | 460 | -2.4445 |
| 12.52 | 2.4 | 496 | -2.5533 |
| 13.04 | 2.5 | 782 | -2.6954 |
| 13.46 | 2,60 | 552 | -2.7723 |
| 13.99 | 2.7 | 995 | -2,9089 |
| 14.51 | 2.9 | 180 | -3.0411 |
| 15.06 | 3.0 | 133 | -3,1857 |
| 15.48 | 3.1 | 377 | -3.2656 |
| 16.08 | 3.2 | 356 | -3.4624 |

胤-1.26

| WIR | BUN COMF | IG. |
|--------|----------------|---------|
| 739 | 07 6 | |
| a(deg) | C ^M | C |
| -04.96 | -0.6734 | 0.5119 |
| -04.06 | -0.5789 | 0.4182 |
| -02.07 | -0.4296 | 0.3184 |
| -02.09 | -0.3085 | 0.2392 |
| -01.09 | -0.1808 | 0.1349 |
| 00.02 | -0.0265 | 0.0371 |
| 01.02 | 0.1045 | -0.0580 |
| 02.02 | 0.2372 | -0.1445 |
| 03.02 | 0.3633 | -0.2218 |
| 03.99 | 0.4927 | -0.2978 |
| 05.11 | 0.6255 | -0.3685 |
| 06.07 | 0.7366 | -0.4358 |
| 07.05 | 0.8528 | -0.5011 |
| 08.01 | 0.9788 | -0.5704 |
| 08.99 | 1.0900 | -0.6259 |
| 10.13 | 1.2277 | -0.6907 |
| 11.09 | 1.3389 | -0.7422 |
| 12.07 | 1.4567 | -0.7792 |
| 13.03 | 1.5679 | -0.8228 |
| 14.14 | 1.6957 | -0.8559 |
| 15.05 | 1.8052 | -0.8804 |
| 15.81 | 1.8516 | -0.8980 |

M-0.30

50 CALIBER CORE

| a(deg) | C | C |
|--------|---------|---------|
| -C5.35 | -0.0539 | -0.4007 |
| -04.15 | -0.0558 | -0.2736 |
| -02.31 | -0.0373 | -0.1750 |
| -01.10 | -0.0380 | -0.0882 |
| 00.13 | -0.0192 | 0.0159 |
| 01.99 | 0.0377 | 0.1165 |
| 03.23 | Q.0565 | 0.1999 |
| 04.99 | 0.0746 | 0.3440 |
| 06.19 | 0.0933 | 0.4184 |
| 08.55 | 0.1501 | 0.5750 |
| 10.34 | 0.1693 | 0.7079 |
| 12.07 | C.2445 | 0.8561 |
| 14.38 | 0.2621 | 0.9567 |
| 15.54 | 0.3011 | 1.0450 |
| 16.69 | 0.3006 | 1.1015 |
| 17.84 | 0.3583 | 1.1490 |
| 19.52 | 0.3965 | 1.2090 |
| 20.04 | 0.4542 | 1.2556 |

M-0.30 50 CALIBER CORE

| a (deg) | $\mathbf{c}^{\mathbf{M}}$ | C _m |
|---------|---------------------------|----------------|
| 22.22 | | 1.4063 |
| 24.06 | 0.8207 | 1.4166 |
| 25.90 | 0.8979 | 1.4518 |
| 28.33 | 1.1493 | 1.4885 |
| 30.18 | 1.3038 | 1.5306 |
| 32.02 | 1.5360 | 1.5513 |
| 35.13 | 1.9422 | 1.6018 |
| 38.22 | 2.3568 | 1.7529 |
| 40.04 | 2.5401 | 1.8674 |
| 42.53 | 2.7908 | 1,9888 |
| 45.53 | 3.0987 | 2.2143 |
| 47.95 | 3.4076 | 2.3268 |
| 50.36 | 3.6006 | 2.4006 |
| 52.76 | 3.7936 | 2,4744 |
| 55.14 | 4.0058 | 2.5641 |

M=0.30 50 CALIBER CORE

| a(deg) | CM | C |
|--------|--------|--------|
| 58.51 | 4.0047 | 2.5350 |
| 61.94 | 4.1587 | 2.6335 |
| 64.82 | 4.1964 | 2.7500 |
| 67.15 | 4.1577 | 2.7465 |
| 70.11 | 4.2159 | 2.7376 |
| 72.97 | 4.1395 | 2.6177 |
| 75.83 | 4.0633 | 2.4695 |
| 77.54 | 4.0061 | 2.3655 |
| 78.10 | 3.7379 | 2.0305 |
| 79.23 | 3.4517 | 1.5385 |
| 82.03 | 3.4918 | 1.3725 |
| 84.34 | 3.4156 | 1.2243 |
| 87.71 | 3.4180 | 0.9418 |
| 89.42 | 3.4583 | 0.7476 |
| 90.13 | 3.4011 | 0.6435 |

M=0.50 50 CALIBER COME

| a(deg) | $c_{\mathbf{n}}$ | C _m |
|--------|------------------|----------------|
| -05.57 | -0.0596 | -0.3959 |
| -03.71 | -0.0293 | -0.2553 |
| -02.46 | -0.0144 | -0.1621 |
| -00.58 | 0.0158 | -0.0101 |
| 00.01 | →0.0233 | 0.0308 |
| 01.93 | 0.0613 | 0.1893 |
| 03.17 | 0.0684 | 0.2876 |
| 04.98 | 0.0909 | 0.4217 |
| 07.47 | 0.1288 | 0.5916 |
| 09.90 | 0.1823 | 0.7745 |
| 12.94 | 0.2356 | 0.9803 |
| 15.33 | 0.2973 | 1.1236 |
| 19.45 | 0.4055 | 1.3631 |

M-0.50 50 CALIBER CORN

| a (deg) | C _N | C |
|---------|----------------|--------|
| 22.21 | 0.5129 | 1.5183 |
| 24.59 | 0.6299 | 1.6032 |
| 27.60 | 0.8252 | 1.7066 |
| 30.00 | 1.0998 | 1.7025 |
| 33.60 | 1.6175 | 1.7145 |
| 36.03 | 2.0403 | 1.8096 |
| 37.81 | 2.2980 | 1.9530 |
| 40.16 | 2.6020 | 2.1922 |
| 42.55 | 2.8984 | 2.4020 |
| 45.53 | 3.2497 | 2.6110 |
| 47.86 | 3.4946 | 2.7644 |
| 50.18 | 3.6320 | 2.8572 |
| 52.50 | 3.8894 | 3.0464 |
| 54.32 | 4.0612 | 3.1305 |

M-0.50 50 CALIBER CORE

| a(deg) | $\mathbf{c}_{\mathbf{N}}$ | C |
|--------|---------------------------|--------|
| 56.34 | 4.2430 | 1.0958 |
| 58.00 | 4.2079 | 2.0750 |
| 59.66 | 4.3606 | 3.1006 |
| 52.40 | 4.4542 | 3.1779 |
| 65.51 | 4.5243 | 3.2356 |
| 66.99 | 4.5242 | 3.2471 |
| 69.25 | 104247 | 2.1091 |
| 710 +7 | 694 | 2.3325 |
| 72.58 | | . 7444 |
| 73.12 | 3.3200 | 2.0056 |
| 74.22 | 7.7355 | 1.3756 |
| 76.42 | 7.7369 | 1.6753 |
| 78.65 | 3.7459 | 1.5443 |
| 81.41 | 7472 د | 1.3839 |
| 84.10 | 3.74C9 | 1.2057 |
| 86.36 | ₹.7577 | 1.0697 |
| 57.47 | 5.1432 | 0.3309 |
| 38.55 | 1.7:16 | 0.8177 |
| 20.22 | 3.7062 | 0.6582 |

M-0.70 50 CALIBER CORE

| $\alpha(\deg)$ | $\mathbf{c}^{\mathtt{M}}$ | C |
|----------------|---------------------------|---------|
| -05.46 | -0.0628 | -0.4135 |
| -04.24 | -0.0587 | -0.3336 |
| -03.02 | -0.0406 | -0.2421 |
| -01.17 | -0.0134 | -0.1014 |
| -00.53 | 0.0050 | -0.0376 |
| 00.05 | 0.0048 | -0.0030 |
| 01.90 | C.0319 | 0.1446 |
| 03.09 | 0.0500 | 0.2430 |
| 04.30 | 0.0681 | 0.3483 |
| 05.49 | 0.0864 | 0.4259 |
| 07.21 | 0.1089 | 0.5627 |
| 08.37 | 0.1350 | 0.6482 |
| 10.12 | 0.1733 | 0.7828 |
| 12.43 | 0.2147 | 0.9213 |
| 14.16 | 0.2705 | 1:0507 |
| 16.45 | 0.3356 | 1.1810 |
| 18.74 | 0.4102 | 1.3190 |
| 20.33 | 0.4710 | 1.4100 |

M=0.70 50 CALIBER CORE

| a(deg) | C | C |
|--------|--------|--------|
| 22.19 | 0.5537 | 1.5250 |
| 23.88 | 0.6333 | 1.6045 |
| 25.04 | 0.7130 | 1.5772 |
| 27.84 | 0.9006 | 1.8250 |
| 30.07 | 1.1215 | 1,5447 |
| 32.38 | 1.4414 | 2.0707 |
| 34.65 | 1.8005 | 2.2004 |
| 36.36 | 2.1618 | 2.2963 |
| 38.03 | 2.4578 | 2.4010 |
| 39.14 | 2.6790 | 2.5425 |
| 40.22 | 2.3107 | 2.6586 |
| 42.47 | 3.1284 | 2.1284 |
| 44.10 | 3.3258 | 3.1017 |
| 45,73 | 3.5274 | 3.2709 |
| 47.37 | 3.7289 | 3.4501 |
| 48.97 | 3.8698 | 3.5395 |
| 50.02 | 3,9449 | 3.6004 |
| 52.70 | 4.1514 | 3.7772 |
| 54.27 | 4.2502 | 3.8250 |

M-0.70 50 CALIBER CORE

| a(deg) | C _M | C |
|--------|----------------|--------|
| 56.73 | 4.6594 | 3.9539 |
| 58.95 | 4.8151 | 3.9713 |
| 60.04 | 4.8575 | 3.9785 |
| 61.17 | 4.9048 | 3.9590 |
| 62.80 | 4.8258 | 3.8205 |
| 63.88 | 4.7655 | 3.6876 |
| 64.75 | 4.6630 | 3.5198 |
| 66.05 | 4.5048 | 3.2437 |
| 67.67 | 4.1892 | 2.6018 |
| 68.69 | 4.0971 | 2.3247 |
| 70.32 | 4.0607 | 2.1422 |
| 74.03 | 4.0912 | 1.036 |
| 75.54 | 4.0717 | 1.6140 |
| 78.75 | 0035 | 1.::20 |
| 80.84 | 0804 | 1.4093 |
| 33.44 | 1288 | 1.519 |
| 86.51 | 7.2075 | 1.1526 |
| 89.07 | 4.0430 | 0.0857 |
| 90.38 | 4.0438 | 0.1037 |

TABULATED DATA

Normal Force and Pitching Moment Coefficient Slopes and Center of Pressure Locations

| | $C_{\mathbf{m}_{\alpha_{\mathbf{Q}}}}$ | c _{Na} | X _{RC} -X _{CP} | M |
|-------------|--|---|---|--|
| | (per deg) | (per deg) | (calibers) | |
| CONFIG. | 1 | | | |
| | 0.0303 0.0305 0.0274 0.02174 0.0294 0.0253 | 0.0909 0.0836 0.0833 0.0830 0.0909 0.08888 | 0.3333 0.3648 0.3289 0.2619 0.3234 0.2846 | 0.4850 0.8080 0.9350 1.0500 1.1500 1.2600 |
| CONFIG. | 2 | | | |
| | -0.0315 -0.05195 -0.0650 -0.0666 -0.0672 -0.06211 | 0.0909 0.0907 0.0926 0.0961 0.0952 0.0926 | -0.3465 -0.57277 -0.7019 -0.6930 -0.7059 -0.6707 | 0.4850 0.8080 0.9350 1.0500 1.1500 1.2600 |
| CONFIG. | 3 | | | |
| - - - | -0.0222 -0.0370 -0.0578 -0.0433 -0.0370 -0.03053 | 0.0714 0.0843 0.0930 0.0843 0.0814 0.0778 | -0.3109 -0.4394 -0.6215 -0.5136 -0.4545 -0.3924 | 0.4850 0.8080 0.9350 1.0500 1.1500 1.2600 |
| CONFIG. | 4 | | | |
| - | 0.0280 0.0437 0.0908 0.1136 0.1126 0.1042 | 0.1062 0.1263 0.1568 0.1732 0.1600 0.1541 | -0.2636 -0.3460 -0.5791 -0.6560 -0.7040 -0.6762 | 0.4850 0.8080 0.9350 1.0500 1.1500 1.2600 |

| | $^{\mathrm{C}}_{^{\mathrm{m}}\alpha}$ | $^{\mathrm{C}}{}_{\mathrm{N}_{_{lpha}}}$ | XRC-XCP | M |
|----------|---------------------------------------|--|------------|--------|
| | (per deg) | o (per deg) | (calibers) | |
| | _ | | | |
| CONFIG. | 5 | | | |
| | -0,0930 | 0.1385 | -0.6715 | 0.4850 |
| | -0.1351 | 0.1449 | -0.9317 | 0.8080 |
| | -0.2024 | 0.1938 | -1.0444 | 0.9350 |
| | -0.1887 | 0.1894 | -0,9963 | 1,0500 |
| - | -0.2112 | 0.1976 | -1.0688 | 1.1500 |
| - | -0.1894 | 0.1779 | -1.0646 | 1.2600 |
| | | | | |
| CONFIG. | 6 | | | |
| | -0.03883 | 0.1000 | -0.3883 | 0.4850 |
| | -0.0505 | 0.1152 | -0.4387 | 0.8080 |
| | 0.0822 | 0.1464 | -0.5615 | 0.9350 |
| | 0.1160 | 0.1506 | -0.7702 | 1.0500 |
| | 0.1111 | 0.1416 | -0.7846 | 1.1500 |
| | 0.09153 | 0.13441 | -0.6810 | 1.2600 |
| | | | | |
| | | - 10-7 | | |
| 50 CALIE | BER BULLET C | OKR | | |
| | | | 4.267 | 0.3000 |
| | | | 5.314 | 0.5000 |
| | | | 5.396 | 0.7000 |

TABULATED DATA

Drag Coefficients

| C _A o | M |
|--|--|
| CONFIG. 1 | |
| 0.4145 0.4543 0.5836 0.7316 0.8807 1.1132 | 0.4850 0.7980 0.9350 1.0370 1.1490 1,2540 |
| CONFIG. 2 | |
| 1.3362 1.5403 1.9375 2.3543 2.4425 1.9962 | 0.4850 0.7980 0.9460 1.0470 1.1490 1.2540 |
| CONFIG. 3 | |
| 0.7099 0.8460 1.1215 1.5256 1.7326 1.6084 | 0.5040 0.7980 0.9350 1.0470 1.1490 1.2540 |
| CONFIG. 4 | |
| 0.2307 0.2804 0.3617 0.6136 0.8000 0.7608 | 0.5040 0.3080 0.9350 1.0470 1.1490 1.2540 |

| C _A o | M |
|------------------|--------|
| CONFIG. 5 | |
| 0.4445 | 0.5040 |
| 0.5173 | 0.7980 |
| 0.6529 | 0.9350 |
| 0.9201 | 1.0470 |
| 1.1277 | 1.1490 |
| 1.0259 | 1.2540 |
| CONFIG. 6 | |
| 0,2483 | 0.4950 |
| 0.2778 | 0.7880 |
| 0.3154 | 0.8960 |
| 0.3791 | 0.9460 |
| 0.6001 | 1.0370 |
| 0.7911 | 1.1490 |
| 0.7650 | 1.2540 |

TABULATED DATA

Pitch Damping Coefficients

CONFIG. 6

| M | Œ | Cm+Cma |
|-------|---------|---------|
| 0.300 | 31.4 | -39.7 |
| 0.300 | 24.2 | -35.4 |
| 0.300 | 19.1 | -33 + 1 |
| 0.300 | 15.2 | -31.4 |
| 0.300 | 12.4 | -29.3 |
| 0.300 | 10.1 | -27.9 |
| 0.300 | 08.4 | -26.8 |
| 0.300 | 07.0 | -27.1 |
| 0.300 | 05.8 | -26.3 |
| 0.300 | 04.8 | -23.9 |
| 0.300 | 04.2 | -20.9 |
| 0.300 | 03.6 | -22.3 |
| 0.310 | 03.2 | -11.4 |
| 0.500 | 32.8 | -33.4 |
| 0.500 | 22.2 | -36.2 |
| 0.500 | 15.4 | -34.0 |
| 0.500 | 11.1 | -19.0 |
| C.500 | 08.3 | -47.0 |
| 0.500 | J6.4 | -22.0 |
| 0.500 | 25.2 | -19.7 |
| 00000 | 37.8 | -45.0 |
| 0.500 | 25.0 | -46.0 |
| 0.500 | 10.0 | -34.5 |
| 3.500 | 11.8 | -31,0 |
| 0.200 | 38.6 | 7.1 |
| 0.200 | 35.3 | -20. |
| 0.500 | 24.5 | -35.0 |
| 0.700 | (· · · | - 4 |
| 0.700 | 13.1 | -30.0 |
| 0.700 | 23.1 | -35.3 |

CONFIG. 6

| M | Œ | C + C m a |
|-------|------|-----------|
| 0.700 | 05.1 | -39.1 |
| 0.700 | 03.0 | -48.1 |
| 0.700 | 01.6 | -49.6 |
| 0.700 | 23.4 | -43.5 |
| 0.700 | 13.8 | -38.3 |
| 0.700 | 08.8 | -31.4 |
| 0.700 | 05.8 | -34.4 |
| 0.700 | 03.8 | -36.6 |
| 0.700 | 02.4 | -29.5 |
| 0.700 | 01.7 | -25.5 |
| 0.900 | 11.3 | -53.2 |
| 0.900 | 07.0 | -49.2 |
| 0.900 | 04.5 | -48.2 |
| 0.900 | 03.0 | -43.1 |
| 0.900 | 02.1 | -34.8 |

TABULATED DATA

Roll Damping Coefficients

| M | α | С, |
|-------|---------|--|
| | | $^{\mathrm{c}}{_{\iota_{\mathrm{p}}}}$ |
| 0.299 | 0.0 | 03.3 |
| 0.299 | 05.0 | 03.37 |
| 0.299 | 1 C • O | 03.48 |
| 0.299 | 15.0 | 03.50 |
| 0.504 | 0.0 | 03.16 |
| 0.504 | 05.0 | 03.24 |
| 0.524 | 10.0 | 03.19 |
| 0.524 | 15.0 | 03.20 |
| 0.798 | 00.0 | 03.49 |
| 0.798 | 05.0 | 02.42 |
| 0.798 | 10.0 | 03.27 |
| 0.946 | 0.0 | 02.87 |
| 0.946 | 35.0 | 03.59 |
| 0.946 | 15.0 | 03.35 |
| 1.297 | 00.0 | 04.20 |
| 1.297 | 05.0 | 00.70 |
| 1.297 | 10.0 | 03.65 |
| 1.297 | 15.0 | 03.50 |

APPENDIX A

THE METHOD EMPLOYED FOR DETERMINING THE DAMPING IN PITCH

A free oscillation technique is used for the measurement of the damping in pitch coefficient, $C_{m_{\mathring{A}}} + C_{m_{\mathring{A}}}$. In this

technique the model is attached to a transverse rod by means of ball bearings. Because of the constraints imposed by the support rod the model has one degree of freedom, that being in pitch. A mathematical expression relating the inertial to aerodynamic moments is postulated to have the form:

$$I_{yy} \stackrel{..}{\theta} = \sum M_{EXTERNAL} = M_{\alpha} \stackrel{.}{\sigma} + M_{\alpha} \stackrel{.}{\alpha} + M_{\beta} \stackrel{.}{\theta}$$
 (A-1)

Making use of the fact that the support constraints imply that $\alpha = \theta$, it is possible to rearrange equation (A-1) as:

$$\ddot{a} - \frac{(M_{\alpha} + M_{0})}{I_{vv}} \dot{a} - \frac{(M_{\alpha})}{I_{vv}} \alpha = 0$$

or:

$$\ddot{\alpha} = \frac{\begin{pmatrix} C_{m_0^*} + C_{m_{\dot{\alpha}}} \end{pmatrix}_{qAd^3}}{2VI_{yy}} \dot{\alpha} = \begin{pmatrix} C_{m_{\dot{\alpha}}} + C_{m_{\dot{\alpha}}} \end{pmatrix} \dot{\alpha} = 0 \qquad (A-2)$$

where use has been made of the following coefficient definitions:

$$C_{m_{\alpha}} = \frac{M_{\alpha}}{q A d}$$

$$C_{m_{\dot{U}}^{\bullet}} + C_{m_{\dot{\alpha}}^{\bullet}} = \frac{M_{\dot{U}}^{\bullet} + M_{\dot{\alpha}}^{\bullet}}{(qAd)(\frac{d}{2V})}$$

The solution to equation (A-2) may be expressed in the following form:

$$\alpha = \alpha_0 e^{\lambda t} Cos(\omega t + \psi)$$
 (A-3)

where the constants α_0 and ψ depend solely upon the initial conditions. Of importance in the data reduction is the log decrement λ and the frequency ω . These quantities are given, respectively, as:

$$\lambda = \frac{\binom{C_{m_{\hat{\theta}}} + C_{m_{\hat{\alpha}}}}{4VI_{yy}}}{qAd^2}$$
(A-4)

$$\omega = \sqrt{\frac{\frac{C_{m_{\alpha}} qAd}{a}}{I_{yy}}} \sqrt{1 - \frac{\left(\frac{C_{m_{\theta}} + C_{m_{\alpha}}}{a}\right)^{3} qAd^{3}}{16V^{2}I_{yy}}}$$
 (A-5)

Since wind tunnel models are lightly damped (by making I_{yy} as large as possible), the second term in the radicand of equation (A-5) may be neglected to give:

$$\omega = \sqrt{-\frac{C_{m}qAd}{I_{yy}}}$$
 (A-6)

Figure (A-1), below, represents a typical damped pitch oscillation of a wind tunnel model:

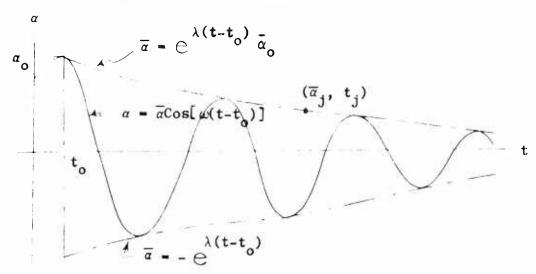


FIGURE (A-1)
Typical Pitch Damping Trace

A-2 CONFIDENTIAL

It should be noted in the above figure that the envelope of the damped sinusoid is given as:

$$\overline{\alpha} = \alpha_0 e^{\lambda (t - t_0)}$$
 (A-7)

Using the amplitude record (obtained photographically) one may obtain the envelope, $\overline{\alpha}(t)$. From this envelope, the log decrement, λ , may be obtained. If this is done, and λ is in turn replaced by its equivalent from equation (A-4), one has an expression for the pitch damping coefficient in terms of measurable quantities.

$$C_{m_{\theta}^{*}} + C_{m_{\alpha}^{*}} = \frac{4VI_{yy}}{qAd^{a}(t_{j} - t_{o})} \quad 'n \left(\frac{\ddot{\alpha}_{j}}{\alpha_{o}}\right)$$
 (A-8)

Equation (A-8) is based upon the supposition that aerodynamic damping is a linear phenomenon, i.e., that the coefficients of equation (A-2) are constant. For cases where the amplitude envelope does not support this hypothesis ($\overline{\alpha}(t)$) not exactly exponential), a method of "piecewise" linearization is used. In this approach the amplitude envelope is divided into small time intervals over which intervals the pitch damping is assumed linear. This is accomplished as illustrated in Figure (A-2).

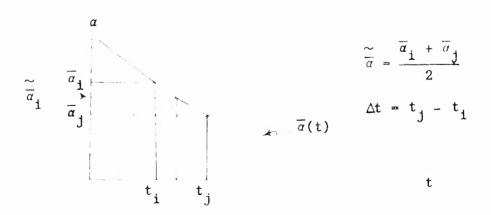


FIGURE (A-2)
Pitch Damping Envelope

A-3 CONFIDENTIAL

Since equation (A-2) is assumed linear over the interval Δt , equation (A-8) may be rewritten as:

$$C_{\mathbf{m}_{\dot{\theta}}^{\bullet}}(\widetilde{\overline{\alpha}_{\mathbf{i}}}) + C_{\mathbf{m}_{\dot{\alpha}}^{\bullet}}(\widetilde{\overline{\alpha}_{\mathbf{i}}}) = \frac{4VI_{yy}}{qAd^{2}\Delta t} \ln\left(\frac{\overline{\alpha}_{\mathbf{i}}}{\overline{\alpha}_{\mathbf{j}}}\right)$$
(A-9)

APPENDIX B

METHODS FOR DETERMINING THE STATIC MOMENT COEFFICIENT FROM PITCH DAMPING RECORDS

In addition to the damping coefficient, $C_{m_{\overset{\bullet}{\theta}}}+C_{m_{\overset{\bullet}{\alpha}}}$, it is also possible to use the pitch damping record to obtain static

also possible to use the pitch damping record to obtain static data. The equation describing the single-degree-of-freedom pitch oscillation (equation (A-2)) has been stated as:

$$\ddot{a} - \left(\frac{\left(C_{m_{\dot{\theta}}} + C_{m_{\dot{\alpha}}}\right) qAd^{2}}{2VI_{yy}}\right) \dot{a} - \left(\frac{C_{m_{\alpha}} qAd}{I_{yy}}\right) \alpha = 0 \quad (B-1)$$

In the vicinity of the oscillation peak, $\alpha = \alpha_p$, equation (B-1) may be simplified as:

$$\ddot{a}_{p} - \left(\frac{C_{m}|_{\alpha}^{qAd}}{I_{yy}}\right) a_{p} = 0$$
(B-2)

where the following statements have been assumed valid in the vicinity of the local maximum of the function a(t):

$$\alpha \mid t = t_p = \alpha_p$$

$$\dot{a}$$
| t=t_p ≈ 0

$$\ddot{a}$$
 | t=t_p $\approx \ddot{a}$ p

Equation (B-2) may be rewritten as a solution for $c_{\rm m}|_{\alpha_{\rm p}}$

$$C_{m \mid \alpha_{p}} = \frac{\ddot{\alpha}_{p} I_{yy}}{q A d}$$
 (B-3)

It now becomes necessary to obtain some approximation to \ddot{a}_p . In Figure (B-1), below, a typical pitch oscillation is shown.

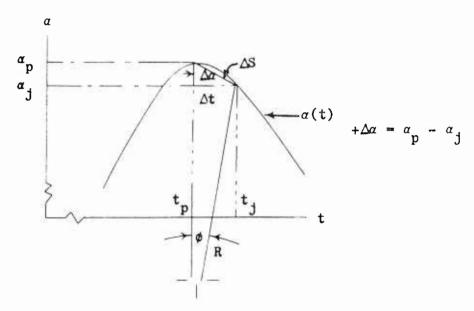


FIGURE (B-1) A Representative Curve of a(t)

The curvature of a(t) in the vicinity of t_p is

$$R = \frac{\left[1 + (\dot{\alpha})^2\right]^{3/2}}{\ddot{\alpha}} \mid t = t_p \stackrel{\sim}{=} \frac{1}{\ddot{\alpha}_p}$$
 (B-4)

where $(\dot{a})^2$ has been assumed negligible compared with unity over the interval, Δt . Over this interval, Δt , the following relationships are held to be valid:

$$-\Delta\alpha = R(1 - \cos\phi) \approx \frac{R\phi^2}{2}$$
 (B-5)

but

$$\phi \simeq \frac{\Delta S}{R} \simeq \sqrt{\frac{1 + (\mathring{\alpha})^2}{R}} \quad \Delta t \simeq \frac{\Delta t}{R}$$
 (B-6)

Combining (B-4), (B-5), and (B-6), one readily obtains:

$$\ddot{a}_{p} = -\frac{2\Delta\alpha}{(\Delta t)^{2}} \tag{B-7}$$

Finally, inserting equation (B-7) into equation (B-3), one obtains:

$$C_{\mathbf{m}|_{\alpha_{\mathbf{p}}}} = -\frac{2\Delta\alpha \mathbf{I}_{\mathbf{y}\mathbf{y}}}{(\Delta \mathbf{t})^{2} \, \mathbf{q} \, \mathbf{A} \mathbf{d}}$$
 (B-8)

An alternate method exists for obtaining essentially the same information. It can readily be shown (equation (A-6)) that the period of oscillation can be expressed as:

$$T = 2\pi \sqrt{-\frac{I_{yy}}{C_{m_{\alpha}}qAd}}$$
 (B-9)

Equation (B-9) may now be solved for the slope of the static pitching moment coefficient, $C_{m_{\alpha}}$, to give:

$$C_{m_{\alpha}} = -\frac{4\pi^2 I_{yy}}{T^2 qAd}$$
 (B-10)

Equation (B-10) is easier to use than equation (B-9); however, since equation (B-10) gives only the slope through the origin, it cannot be used to evaluate nonlinearities in the static pitching moment coefficient, $C_{\rm m}$. For evaluation of $C_{\rm m}(\alpha)$ where it varies nonlinearly it would be necessary to make use of equation (B-8).

APPENDIX C

THE METHOD EMPLOYED FOR THE DETERMINATION OF DAMPING IN ROLL

A free decay technique is used for the measurement of the damping in roll coefficient, C_{t_n} , and the induced rolling

moment coefficient (due to fin cant, $\delta_{\mathbf{f}}$, or control deflection, $\delta_{\mathbf{c}}$), $C_{\ell_{\delta}}$. In this procedure the model is axially mounted

to a rotating sting. The model-sting combination is spun to a high spin rate, decoupled from the drive system, and permitted to decay to either zero spin rate or a steady state spin rate, if any. An analog record of the spin history is obtained from a magnetic tachometer. An identical run is made in a vacuum to provide a tare for the removal of the damping contribution of bearing friction.

Because of the nature of the support and drive system, a first order homogeneous differential equation relating the inertial to aerodynamic moments is presumed to describe the spin decay. This equation may be written as:

$$I_{xx}\dot{p} = \Sigma L_{EXTERNAL} = L_{p}p + L_{\delta}\delta \qquad (C-1)$$

where p is the spin rate, I_{xx} the axial moment of inertia, L_{δ}^{δ} the induced roll moment, and L_{p} the roll damping moment. The solution of equation (C-1) is:

$$\left(p + \frac{L_{\delta}^{\Delta}}{L_{p}}\right) = \left(p_{o} + \frac{L_{\delta}^{\Delta}}{L_{p}}\right) \in \frac{\frac{L_{p}}{I_{xx}}}{(t-t_{o})}$$
 (C-2)

In equation (C-2) the initial conditions are chosen as $p=p_0$ when $t=t_0$. The definition of steady state roll follows from equation (C-1) and may be expressed as:

$$\dot{p} = 0$$
, $p = p_{SS} = -\left(\frac{L_{\delta}}{L_{p}}\right)\delta$

Using the above definition, equation (C-2) may be rewritten as:

$$\frac{L_{p}}{(p-p_{ss}) - (p_{o}-p_{ss})} = \frac{1}{2}xx \qquad (C-3)$$

The roll damping moment derivative, L_p , and the induced rolling moment derivative, L_{δ} , have the following definition in terms of nondimensional quantities:

$$L_{p} = C_{\ell_{p}} \frac{qAd^{2}}{2V}$$
 (C-4)

$$L_{\delta} = C_{\ell_{\delta}} \text{ qAd} \tag{C-5}$$

If equation (C-3) is solved for the roll damping moment derivative, L_p , and then rewritten in terms of the roll damping coefficient, C_{ℓ_p} , from equation (C-4), the result is:

$$C_{\ell p} = -\frac{I_{xx}}{(t-t_0)} \left(\frac{2V}{qAd^2}\right) \ln \left(\frac{p_0 - p_{ss}}{p-p_{ss}}\right)$$
 (C-6)

Definition of the steady state roll and the definition of $C_{\ell_{\delta}}$ from equation (C-5) results in the following expression:

$$C_{\ell_{\delta}} = -\frac{P_{ss}}{\delta} \left(\frac{b}{2v}\right) C_{\ell_{p}} \tag{C-7}$$

Thus it should be noted that both coefficients C $_{\ell p}$ and C $_{\ell \delta}$ may be calculated from measurable quantities.

Where there is no induced roll (C $_{\delta}$ $_{\delta}$ - 0) equation (C-6) becomes:

$$C_{\ell_{p}} = -\frac{I_{xx}}{(t-t_{o})} \left(\frac{2V}{qAd^{a}}\right) \ell_{n} \left(\frac{p_{o}}{p}\right)$$
 (C-8)

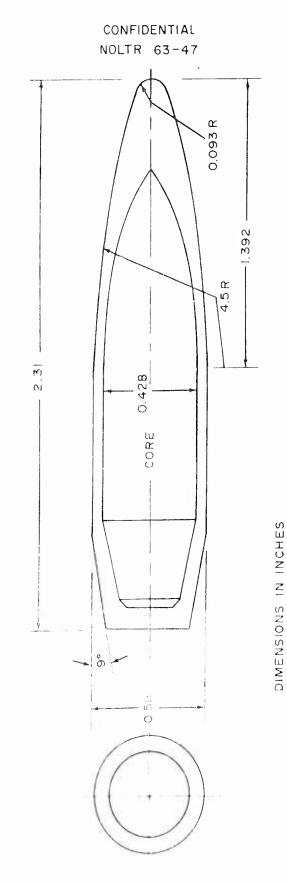


FIG. 1 50 CALIBER BULLET

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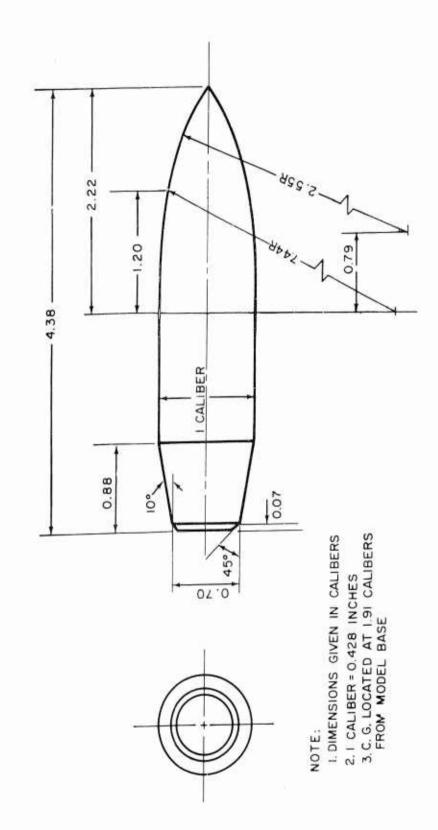


FIG.2 50 CALIBER STEEL CORE

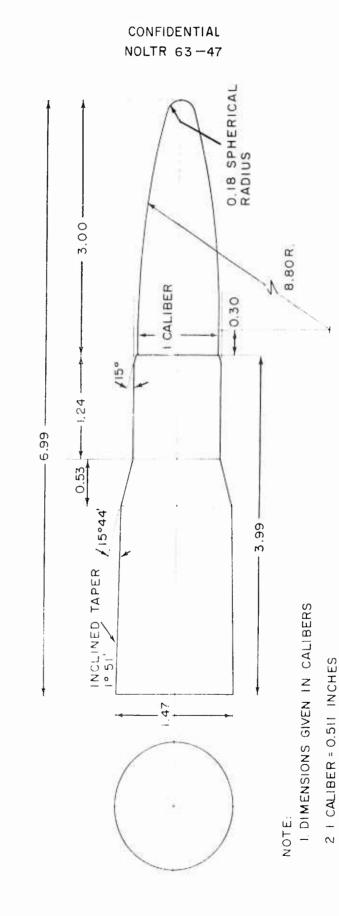
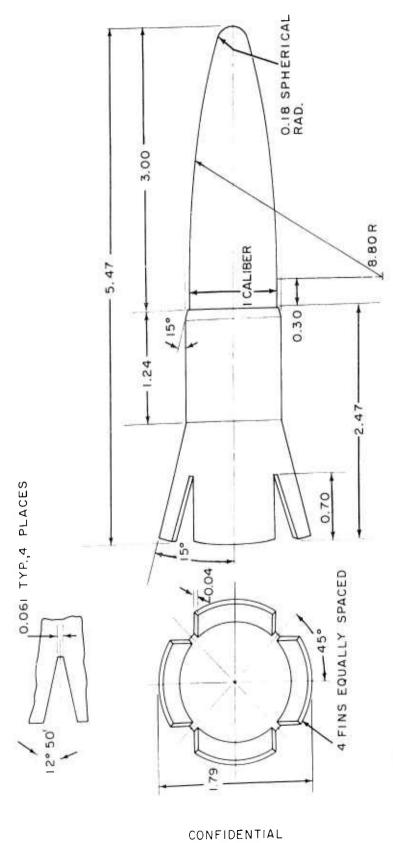


FIG.3 LAZY DOG CONFIGURATION I

3. C. G. LOCATED AT 4.05 CALIBERS FROM MODEL BASE

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NOTE:

- 1. DIMENSIONS GIVEN IN CALIBERS
- 2. I CALIBER = 0.511 IN.
- 3. C.G. LOCATED 2.89 CALIBERS FROM MODEL BASE

FIG.4 LAZY DOG CONFIGURATION 2

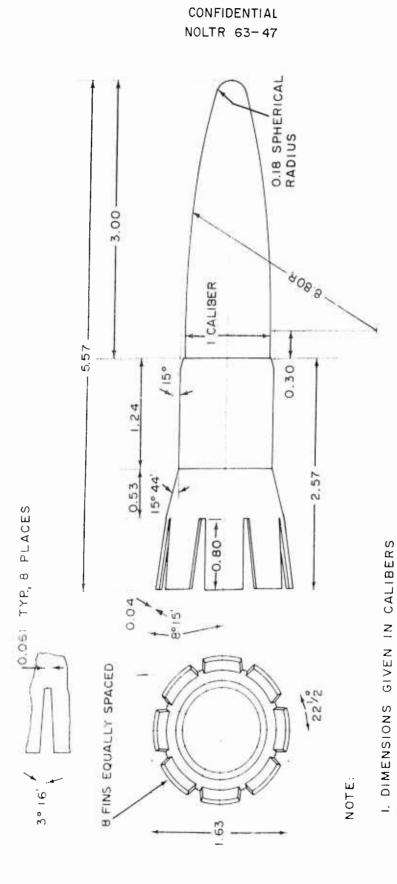
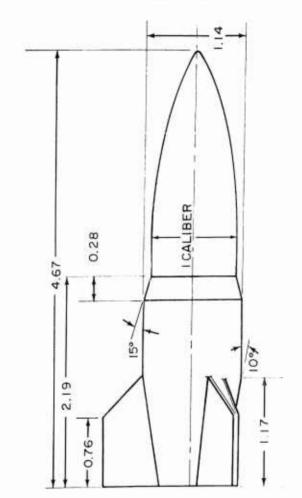


FIG.5 LAZY DOG CONFIGURATION 3

2. I CALIBER = 0.511 INCHES
3. C.G. LOCATED 2.89 CALIBERS FROM
MODEL BASE

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0.08

NOTE:

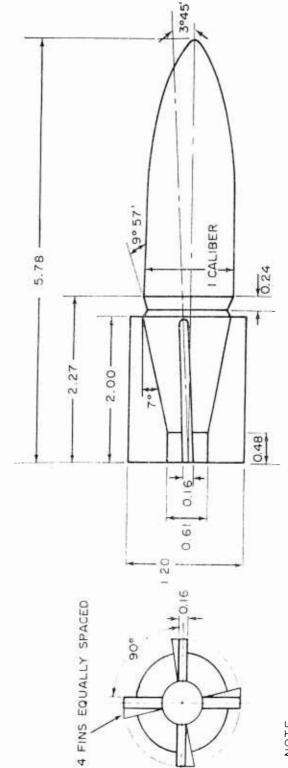
- 1. DIMENSIONS GIVEN IN CALIBERS
- 2. I CALIBER = 0.428 INCHES
- C. G. LOCATED 2.18 CALIBERS FROM MODEL BASE

FIG. 6 LAZY DOG CONFIGURATION 4

3 FINS EQUALLY SPACED

0.23

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NOTE.

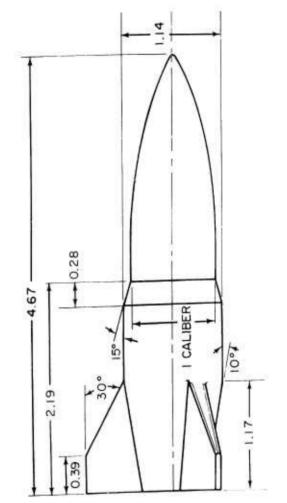
I. DIMENSIONS GIVEN IN CALIBERS

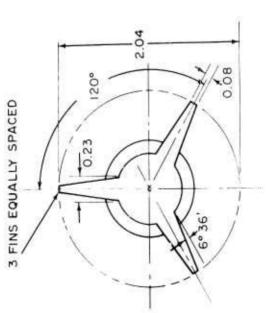
2 | CALIBER = 0.428 | N

3. C.G. LOCATED 2.96 CALIBERS FROM MODEL BASE

FIG.7 LAZY DOG CONFIGURATION 5

CONFIDENTIAL NOLTR 63-47





NOTE

- 1. DIMENSIONS GIVEN IN CALIBERS
 - 2. I CALIBER = 0.428 IN.
- 3. C.G. LOCATED 2.18 CALIBERS FROM MODEL BASE

FIG.8 LAZY DOG CONFIGURATION 6

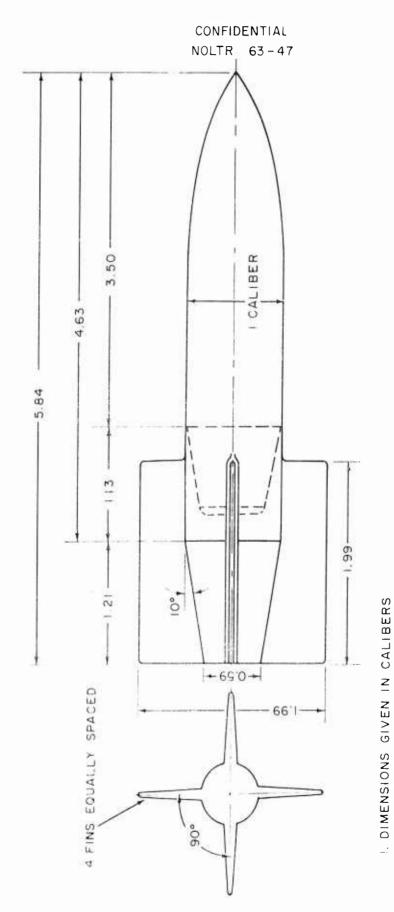


FIG.9 LAZY DOG CONFIGURATION 7

3. C.G. LOCATED AT 3.04 CALIBERS FROM MODEL BASE

2. I CALIBER = 0.428 INCHES

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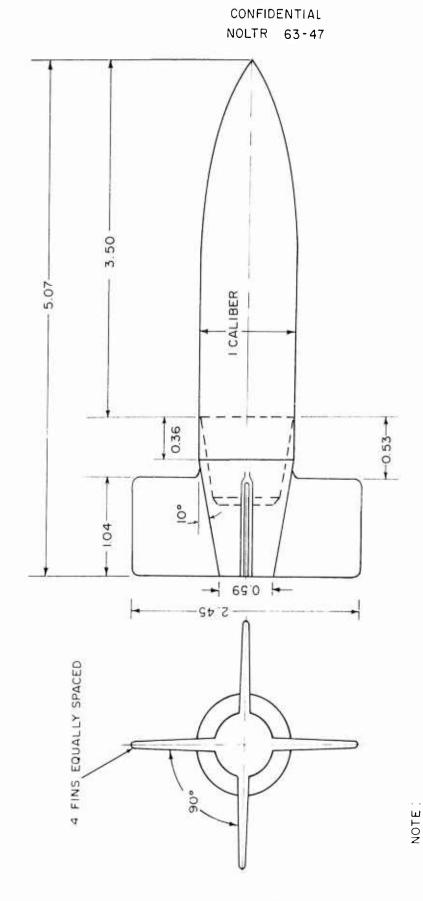


FIG. 10 LAZY DOG CONFIGURATION 8

1. DIMENSIONS GIVEN IN CALIBERS

2 | CALIBER = 0.428 | INCHES

C.G. LOCATED 2.27 CALIBERS FROM MODEL BASE

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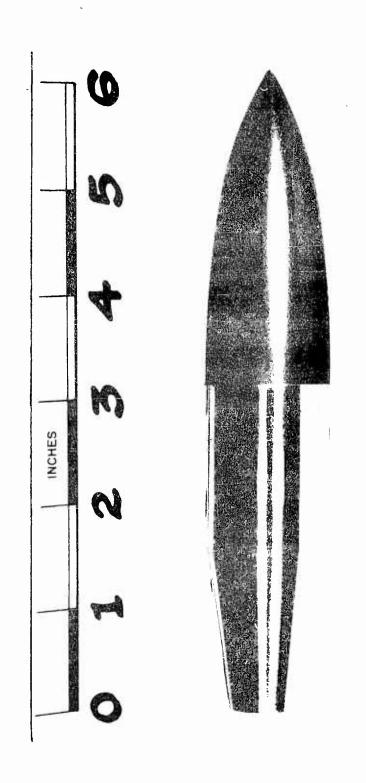


FIG. II A 2.92 SCALE, 50 CALIBER CORE MODEL

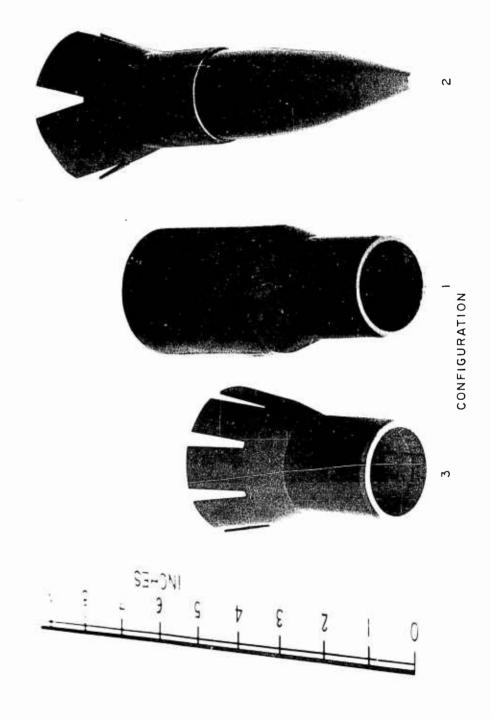


FIG. 12 THE 2.50 SCALE MODELS OF CONFIGURATIONS 1,2 AND 3

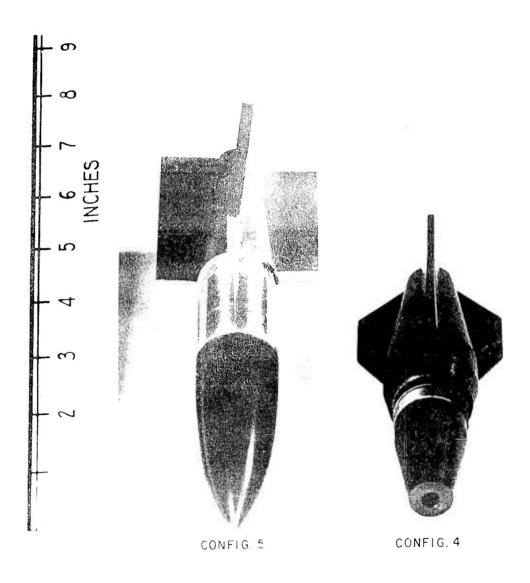


FIG.13 THE 2.92 SCALE MODELS OF CONFIGURATIONS 4 AND 5

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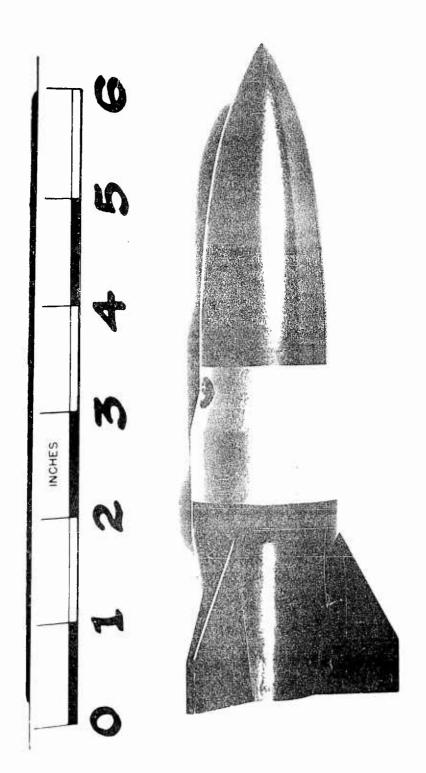


FIG. 14 A 2.92 SCALE MODEL OF CONFIGURATION 6

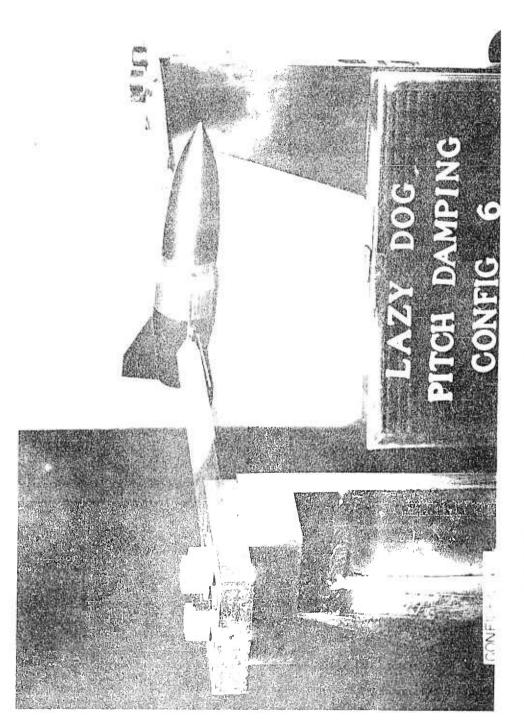


FIG IS THE 2 92 SCALE, PITCH-DAMPING MODEL OF CONFIGURATION 6

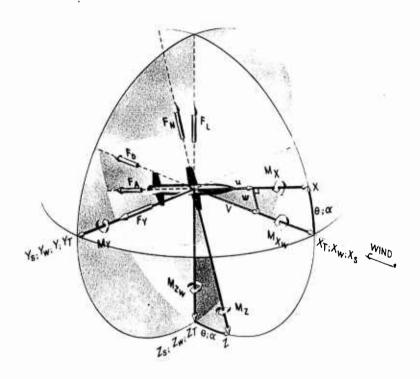
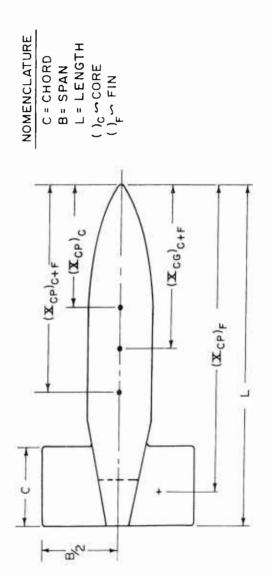


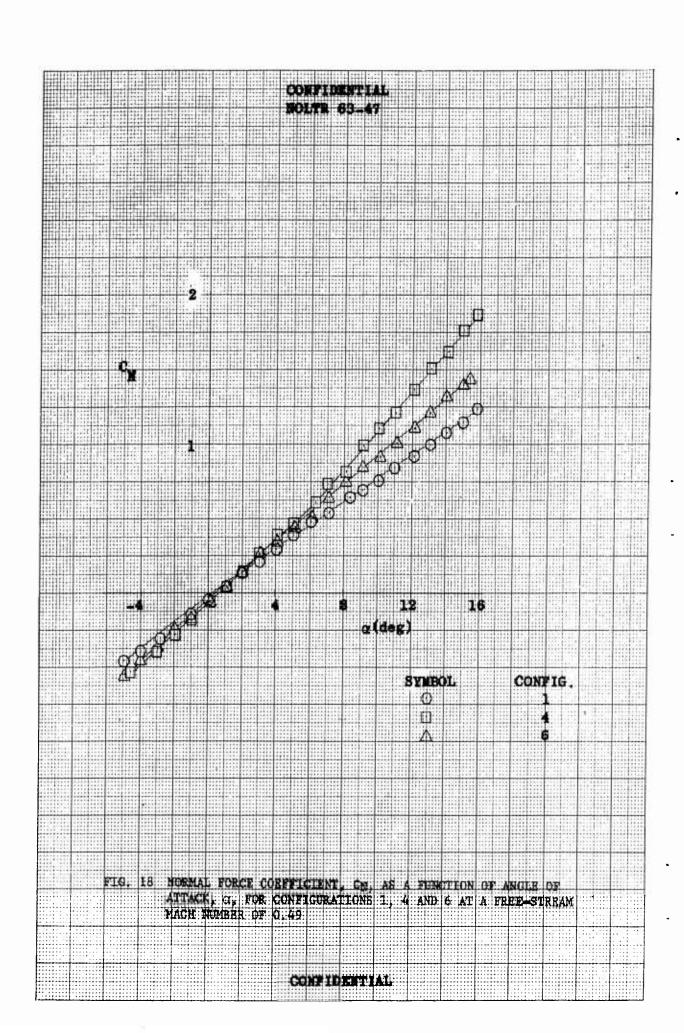
FIG.16 AXES SYSTEMS, BODY ROTATED THROUGH AN ANGLE OF PITCH.

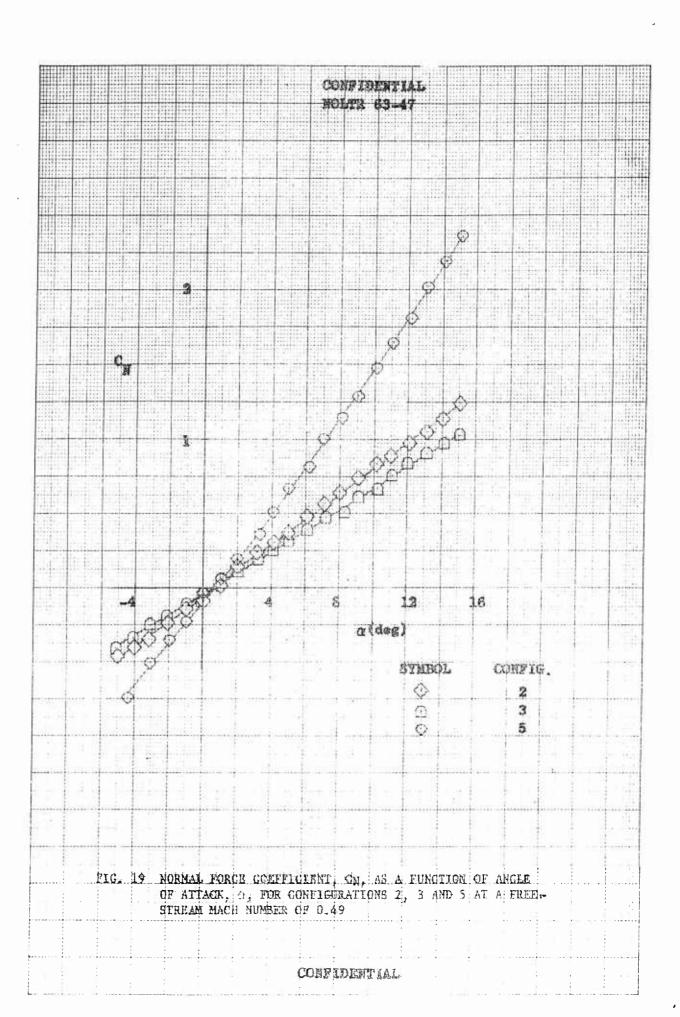


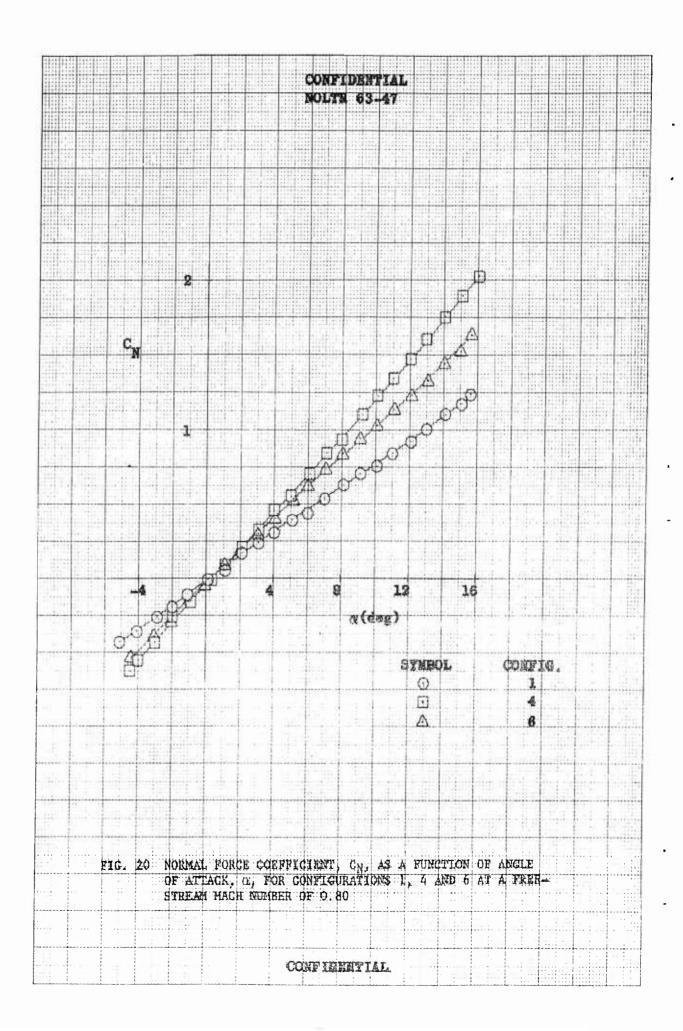
STATIC MARGIN = $(\mathbf{X}_{CG})_{C+F}$ — $(\mathbf{X}_{CP})_{C+F}$

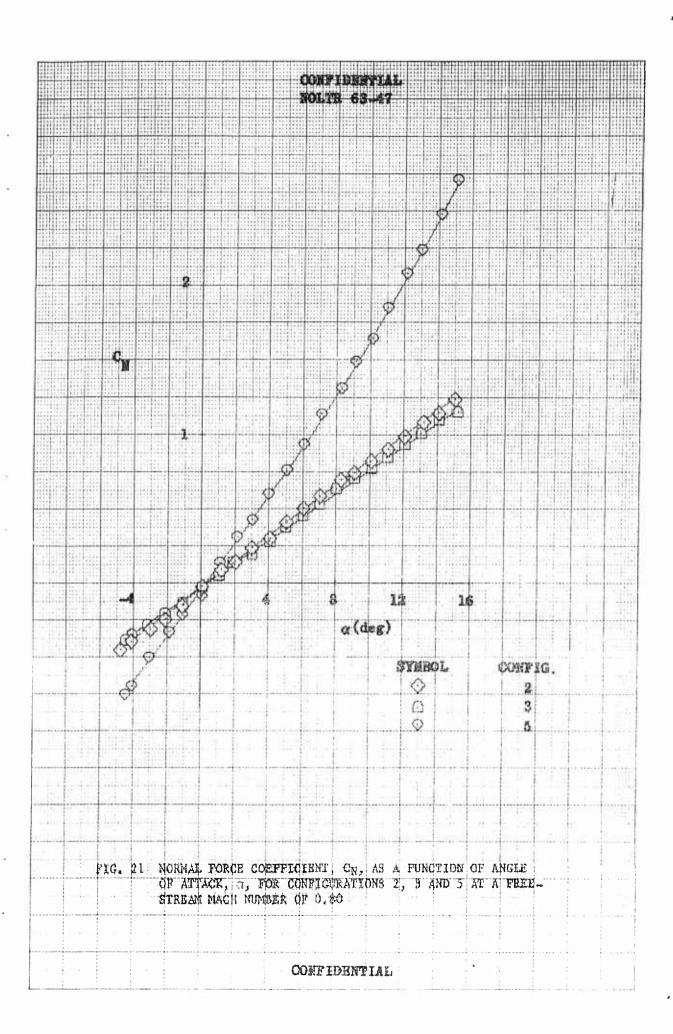
FIG 17 CENTER OF PRESSURE (\mathbf{X}_{GP}) and center of gravity (\mathbf{X}_{GG}) locations for the 50 caliber bullet core with rectangular fins.

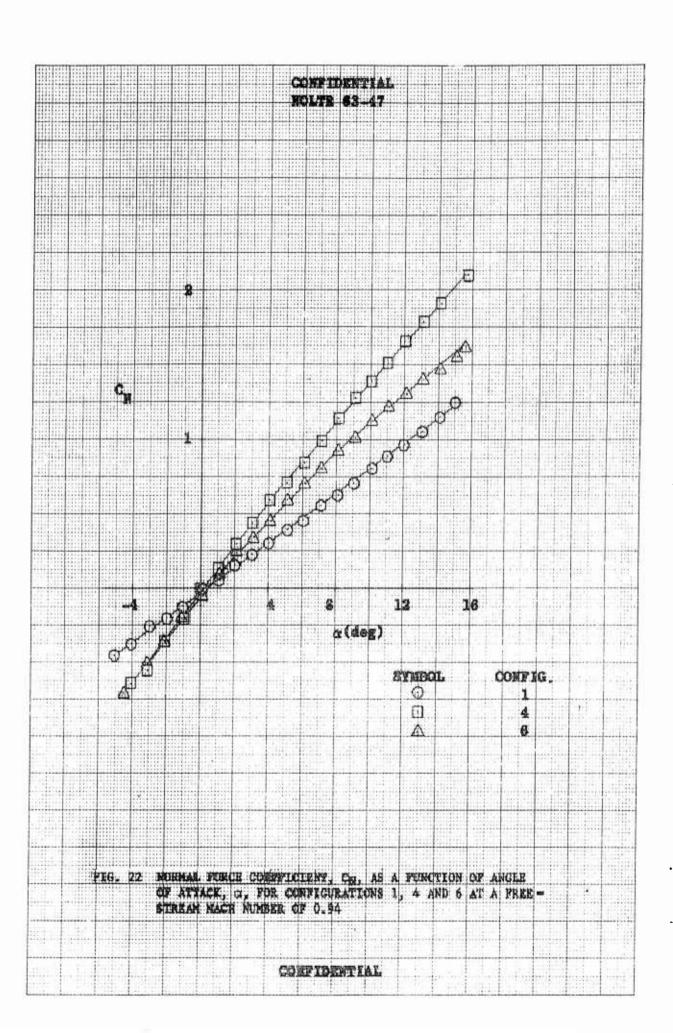
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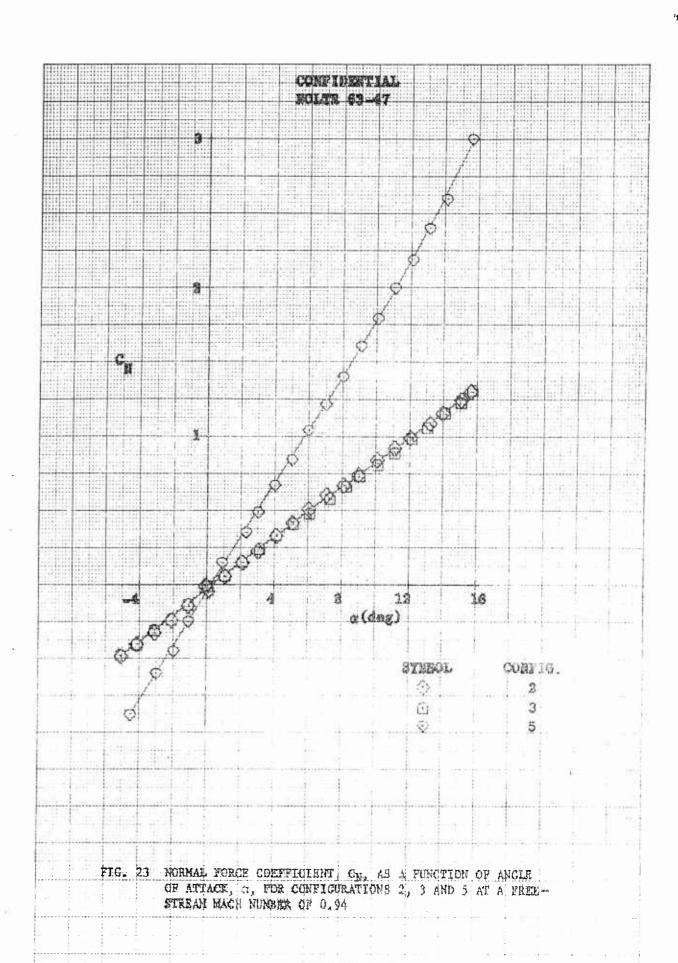




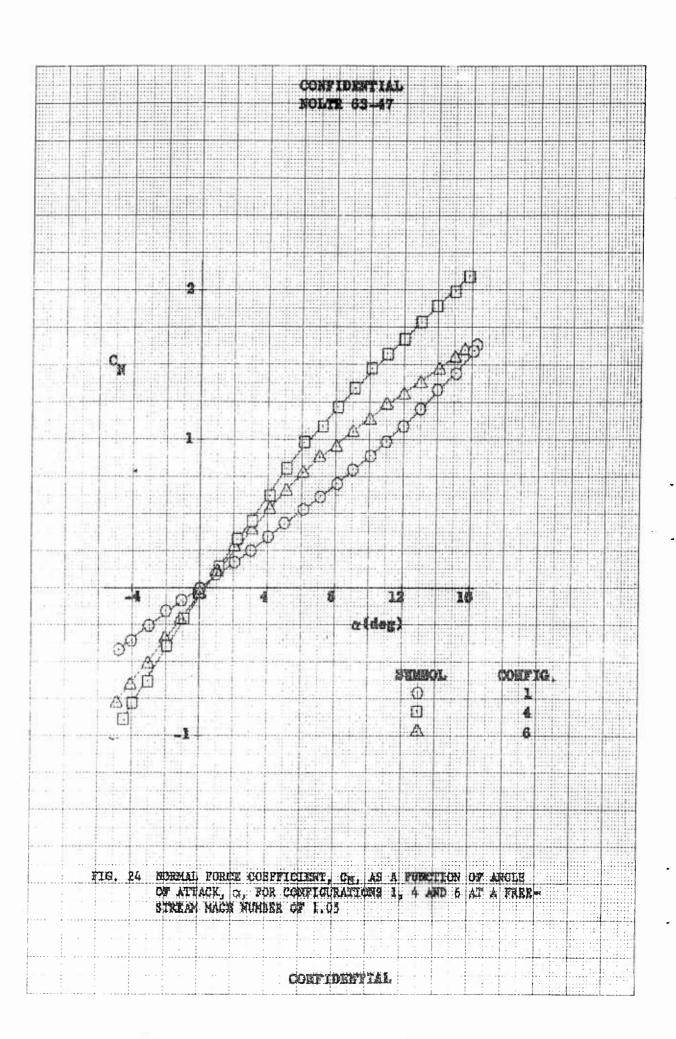


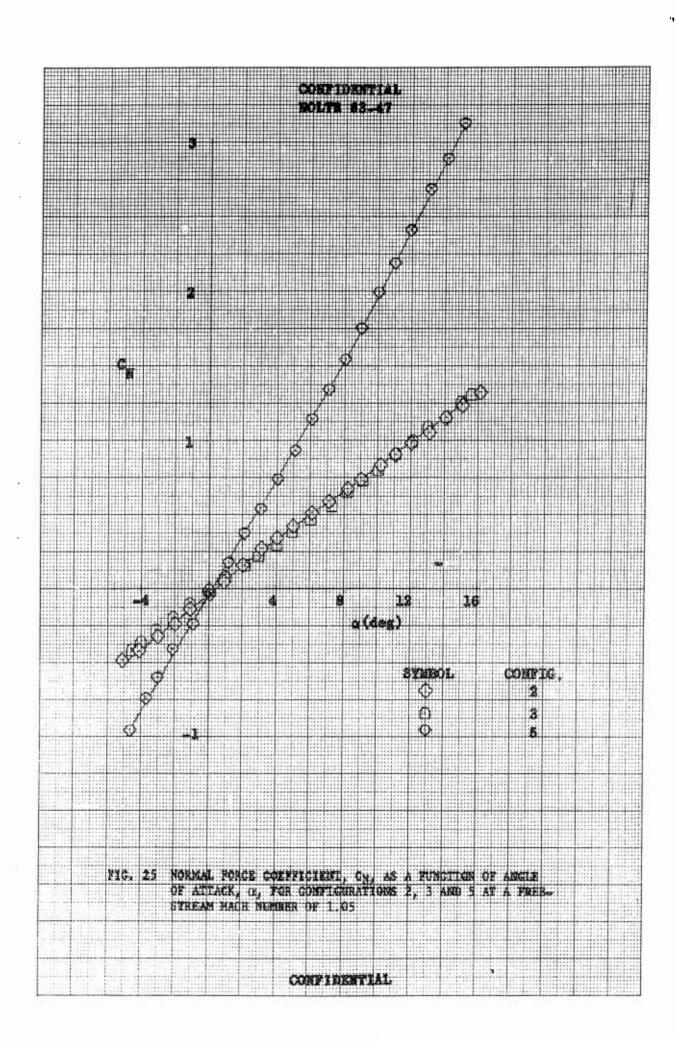


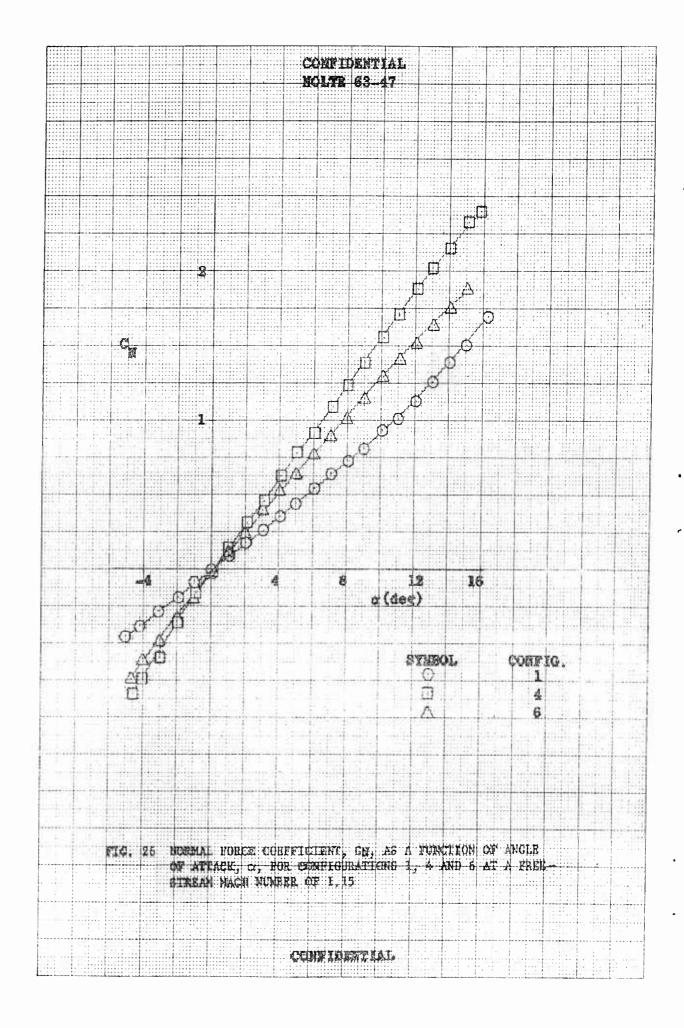


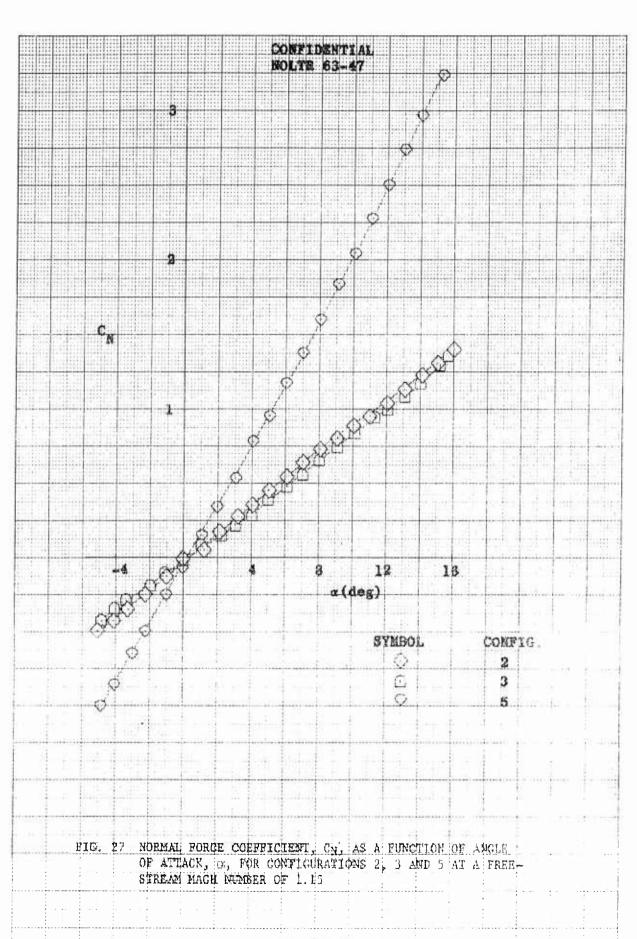


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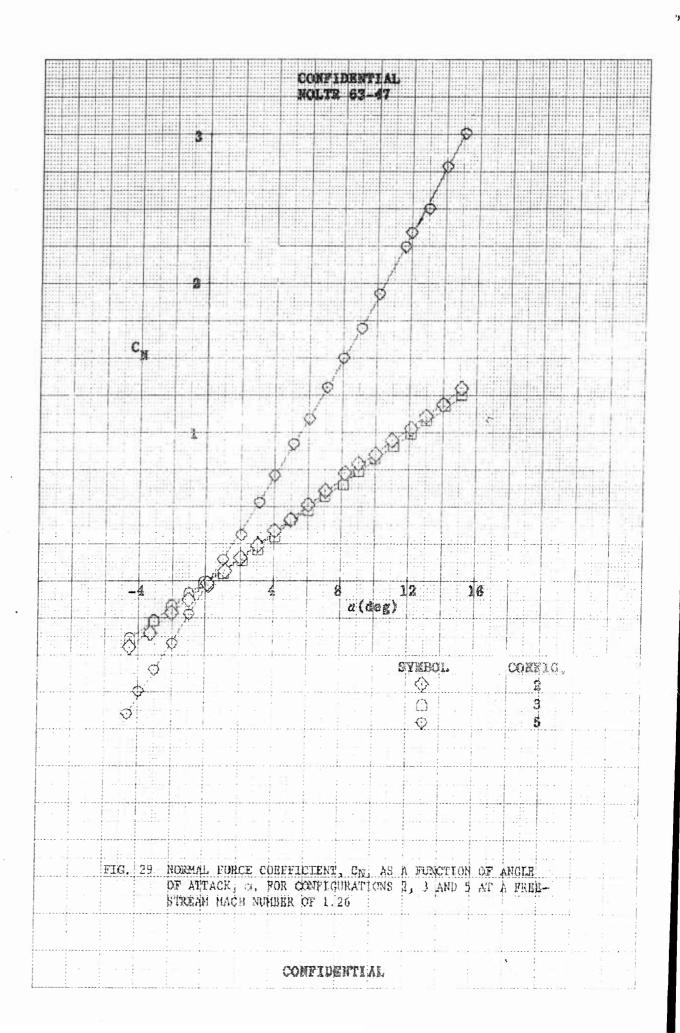


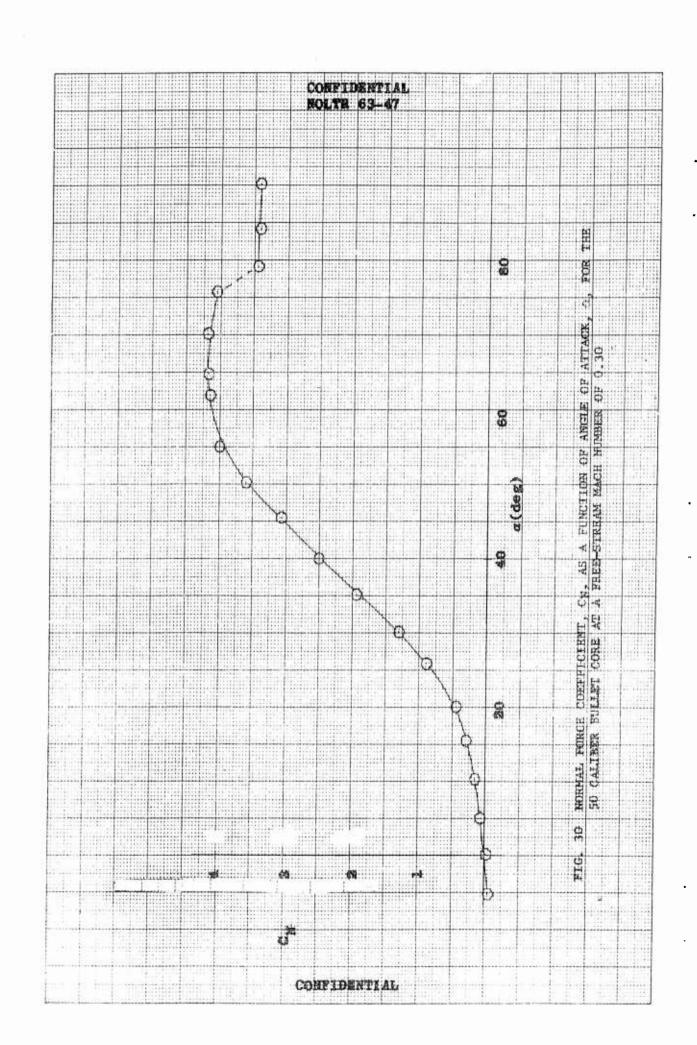


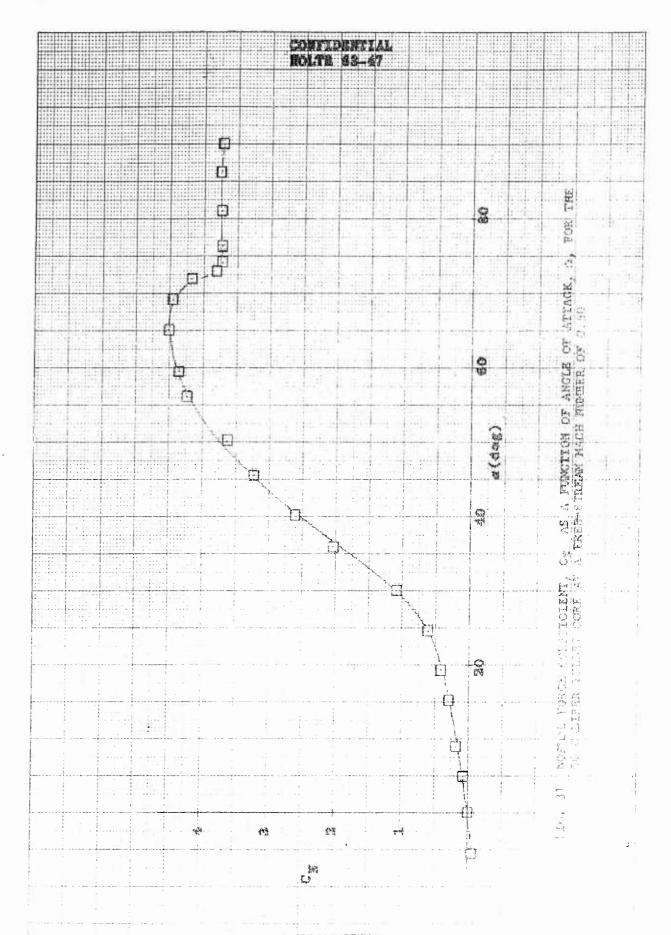


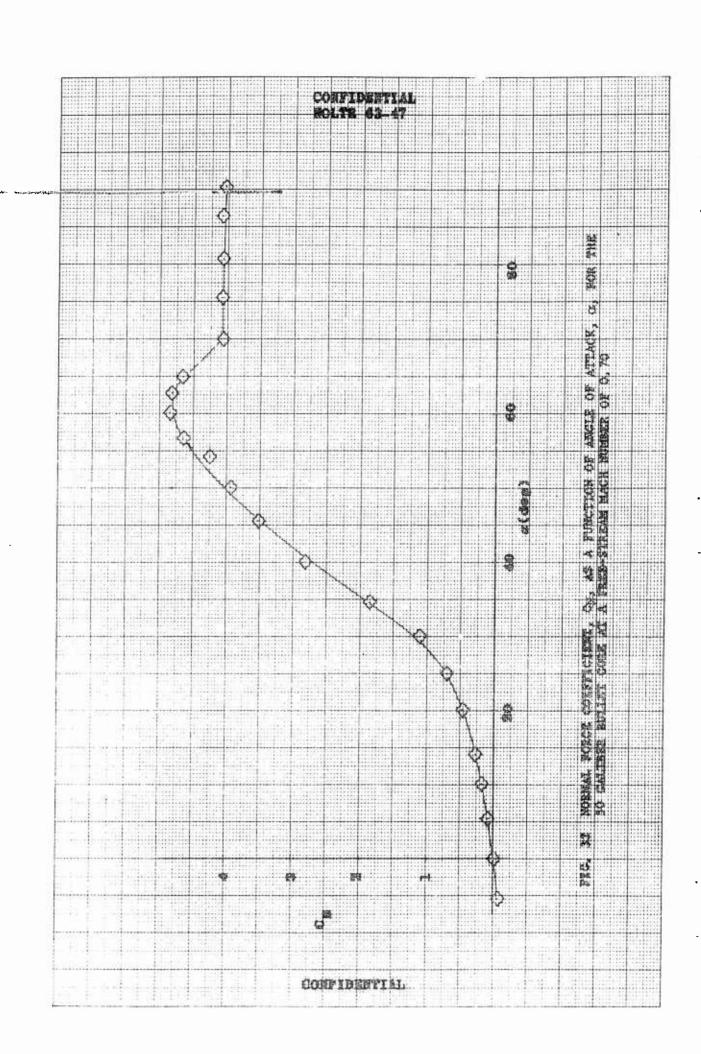
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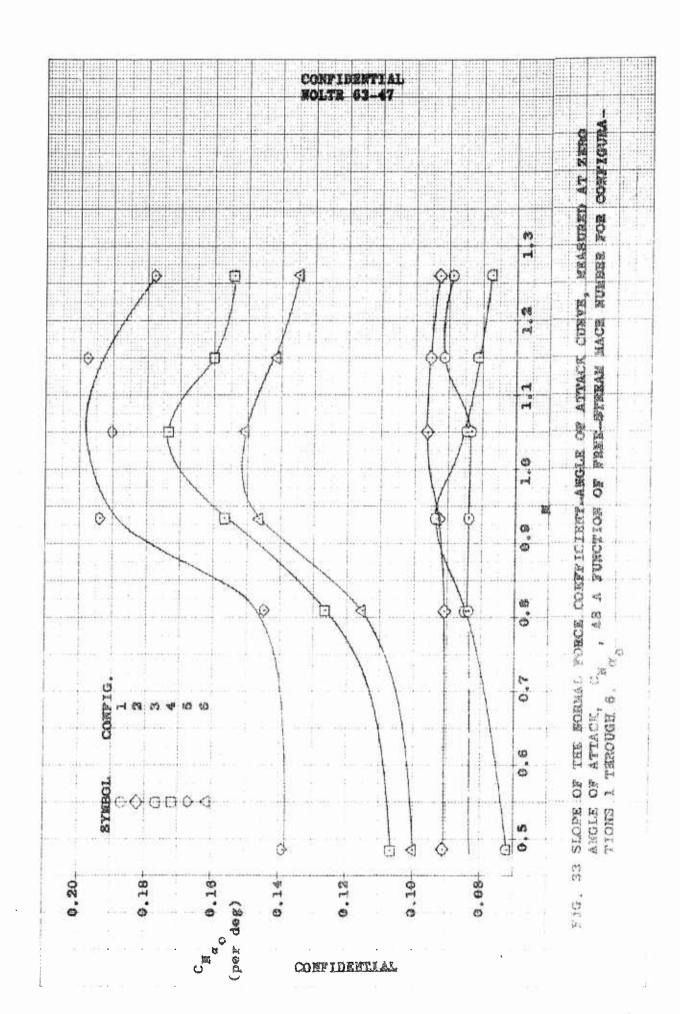
CONFIDENTIAL HOLTE 63-41 16 a (deg) SYMBOL COMPIE. FIG. 28 NORMAL POSCE COMPPLEXENT, GW, AS A FUNCTION OF ANGLE OF ATTACK, C. FOR COMPTIGURATIONS 1. 4 AND G AT A FRES-STREAM MAIN MUNICER OF 1.26 COMPARED LAS.











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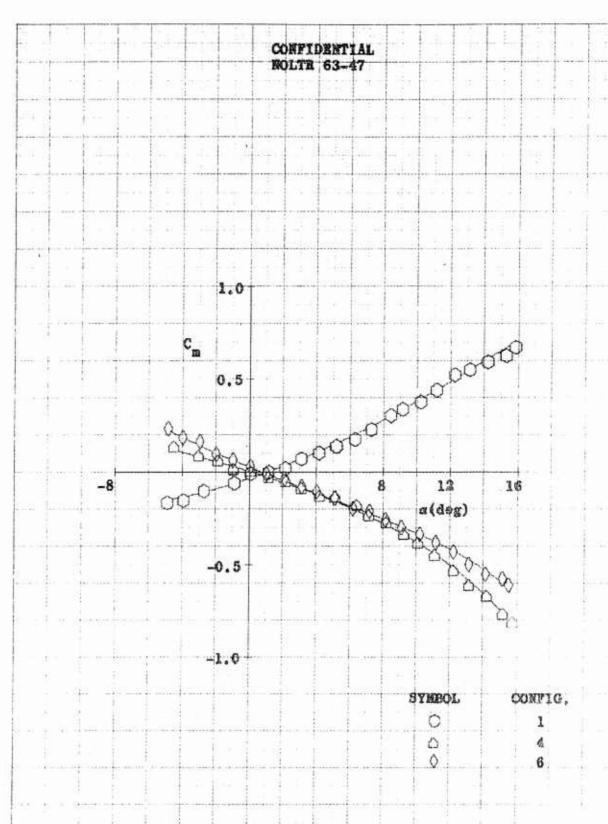
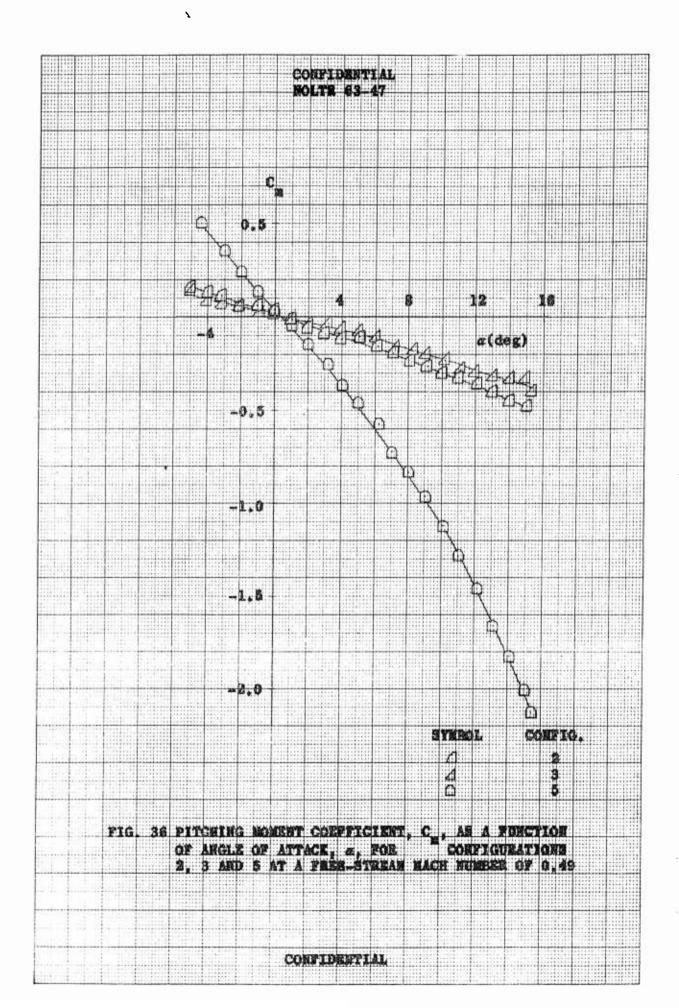
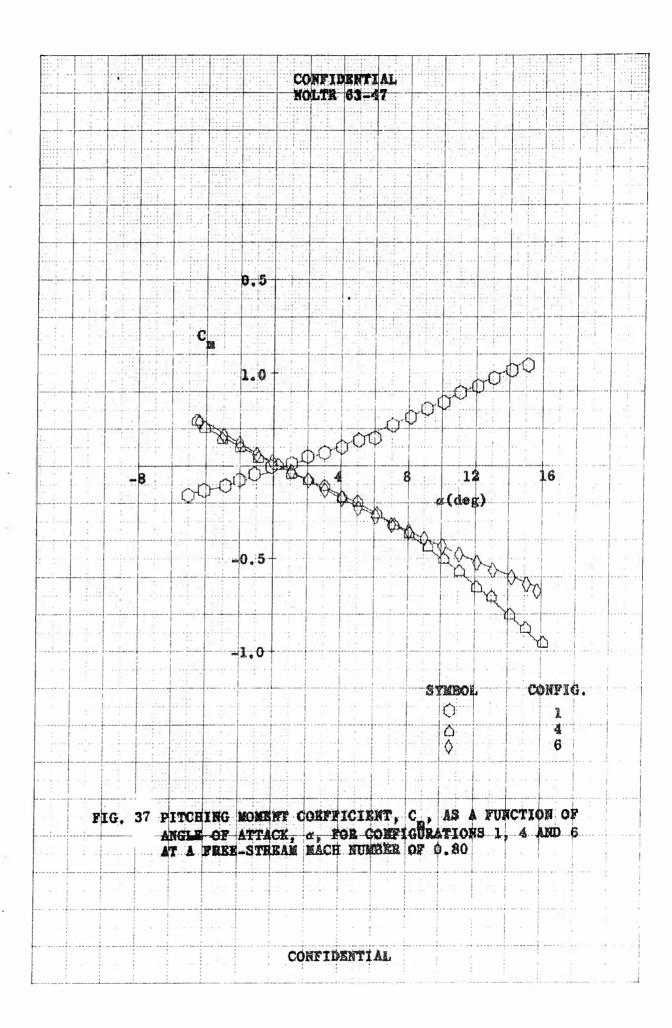
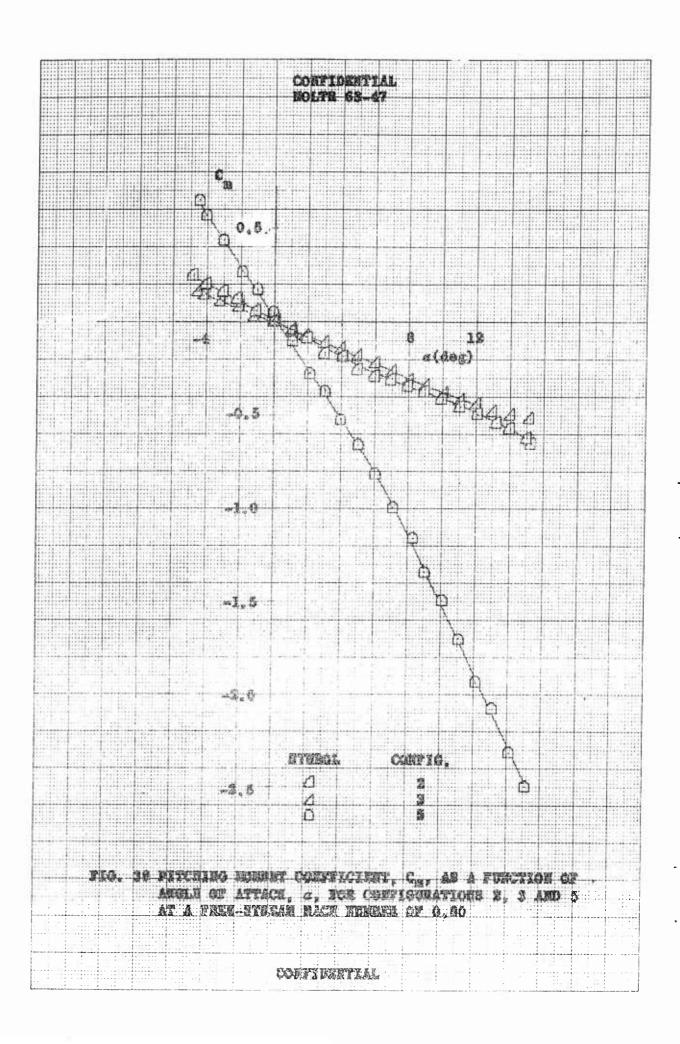
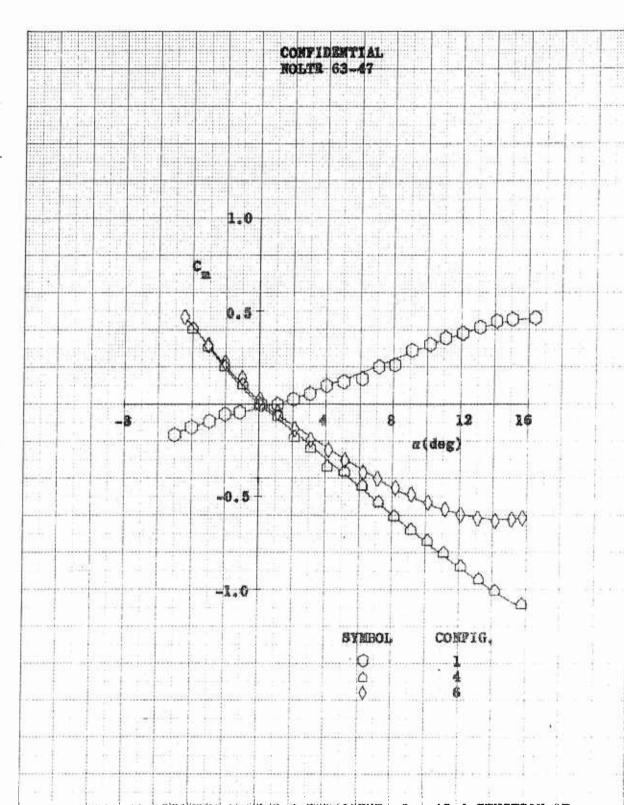


FIG. 35 PITCHING MOMENT COMPFICIENT, C., AS A PUNCTION OF ANGLE OF ATTACK, α, FOR CONFIGURATIONS 1, 4 AND 6 AT A FREE-STREAM WACH HUMBER OF 0.49



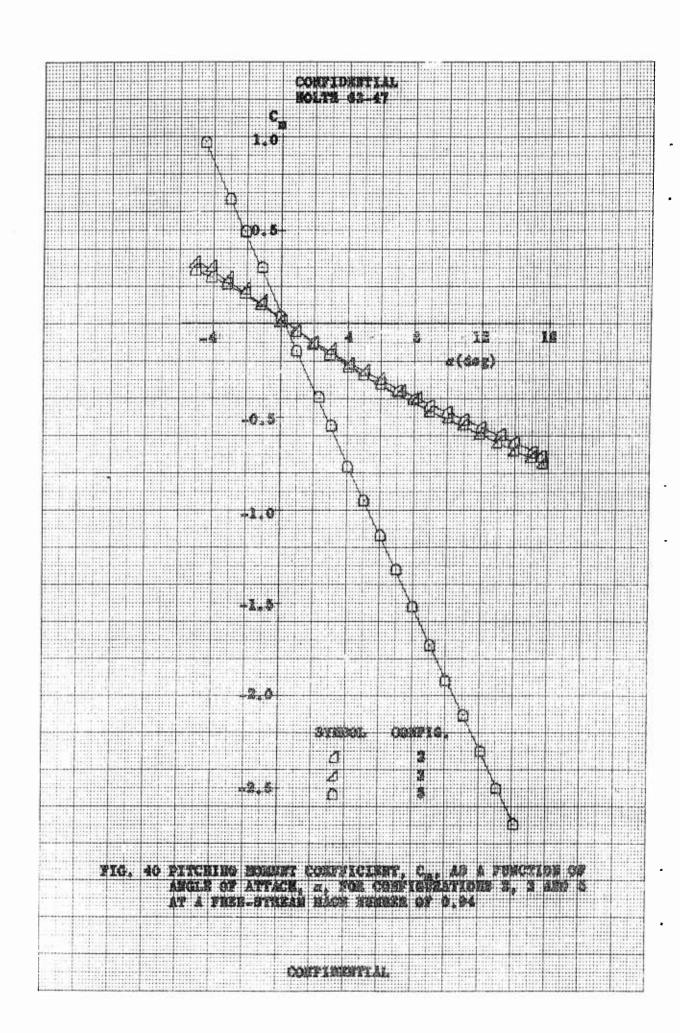






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FIG. 39 PITCHING MOMENT CORFFICIENT, Cm., AS A FUNCTION OF ANGLE OF ATTACK, a, FOR CONFIGURATIONS 1, 4 AND 6 AT A FREE-STREAM MACH NUMBER OF 0.94



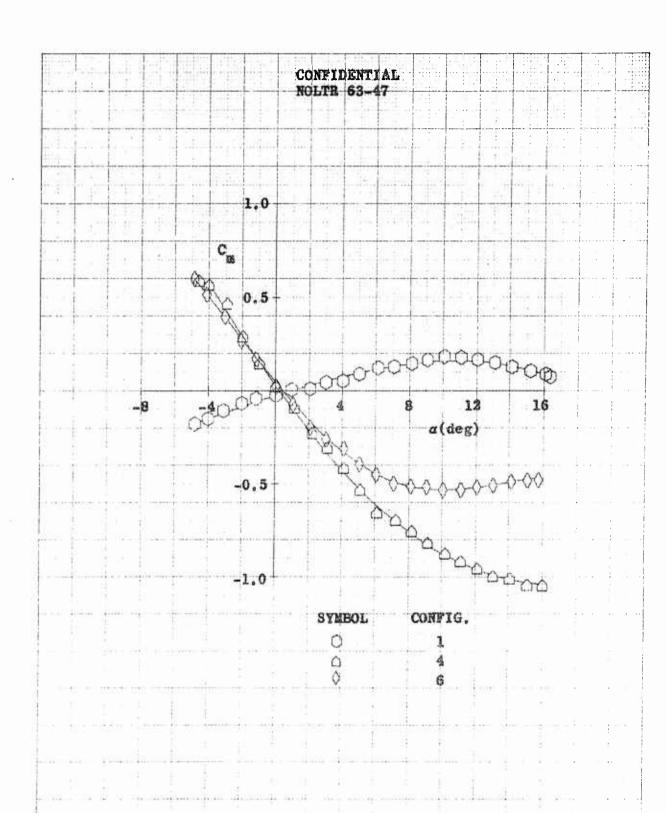
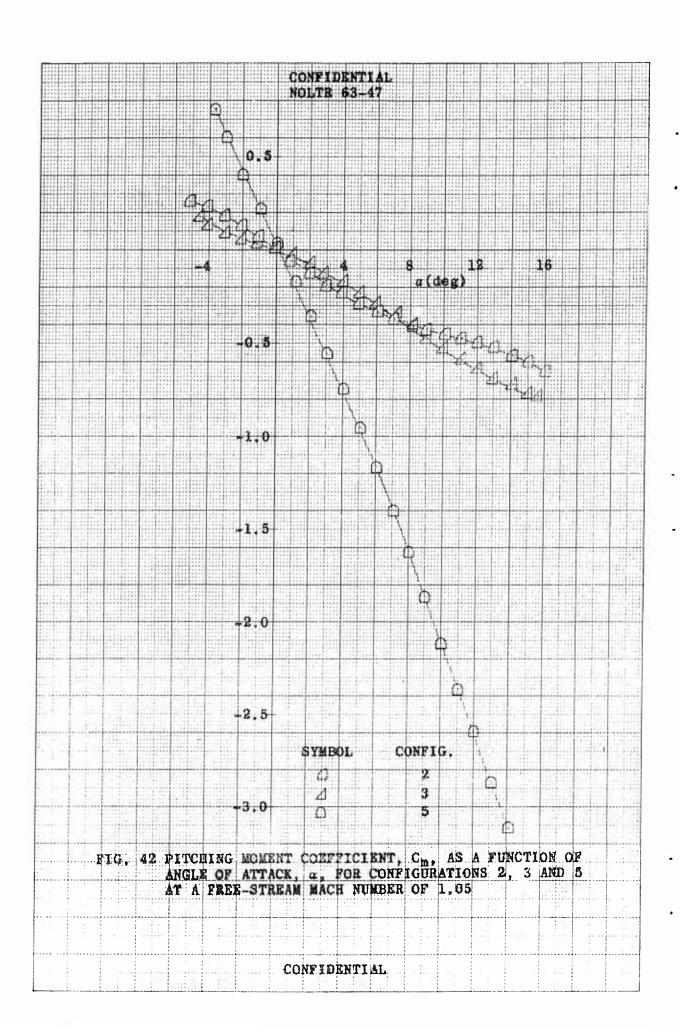


FIG. 41 PITCHING MOMENT COEFFICIENT, $C_{\rm m}$, AS A FUNCTION OF ANGLE OF ATTACK, α , FOR CONFIGURATIONS 1, 4 AND 6 AT A FREE-STREAM MACH NUMBER OF 1.05



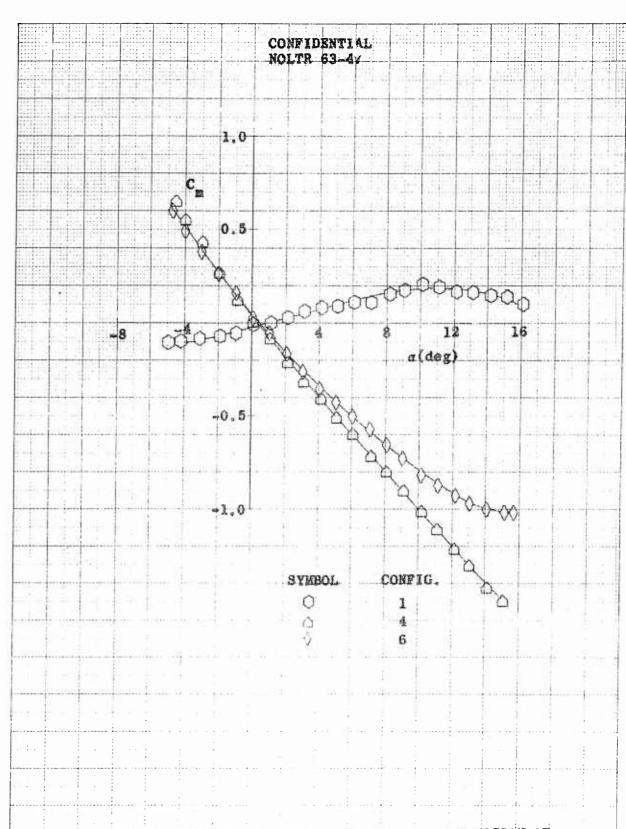
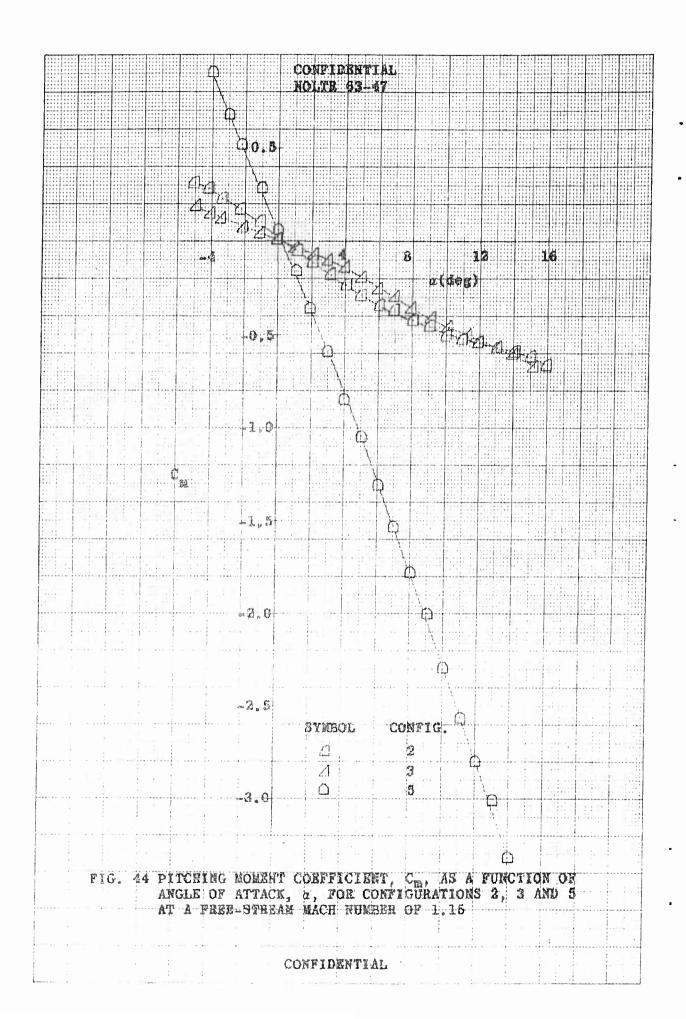


FIG. 43 PITCHING MOMENT COEFFICIENT, C_m , AS A FUNCTION OF ANGLE OF ATTACK, α , FOR CONFIGURATIONS 1, 4 AND 6 AT A FREE-STREAM MACH NUMBER OF 1.15



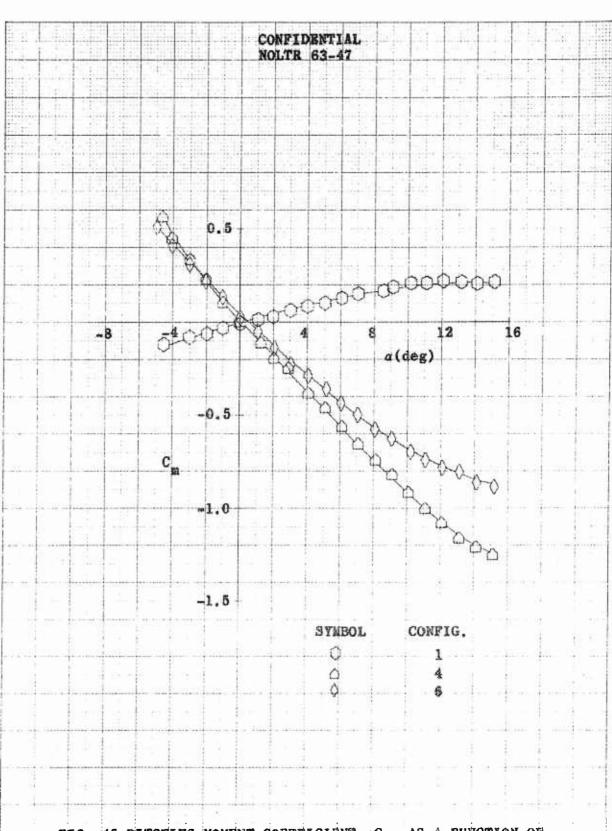
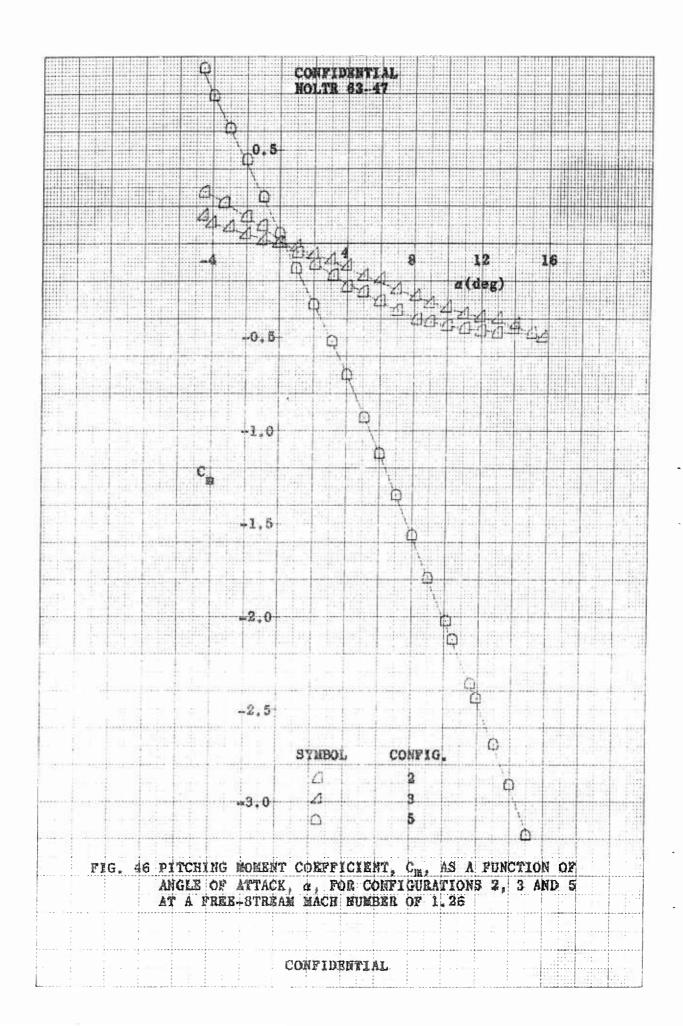
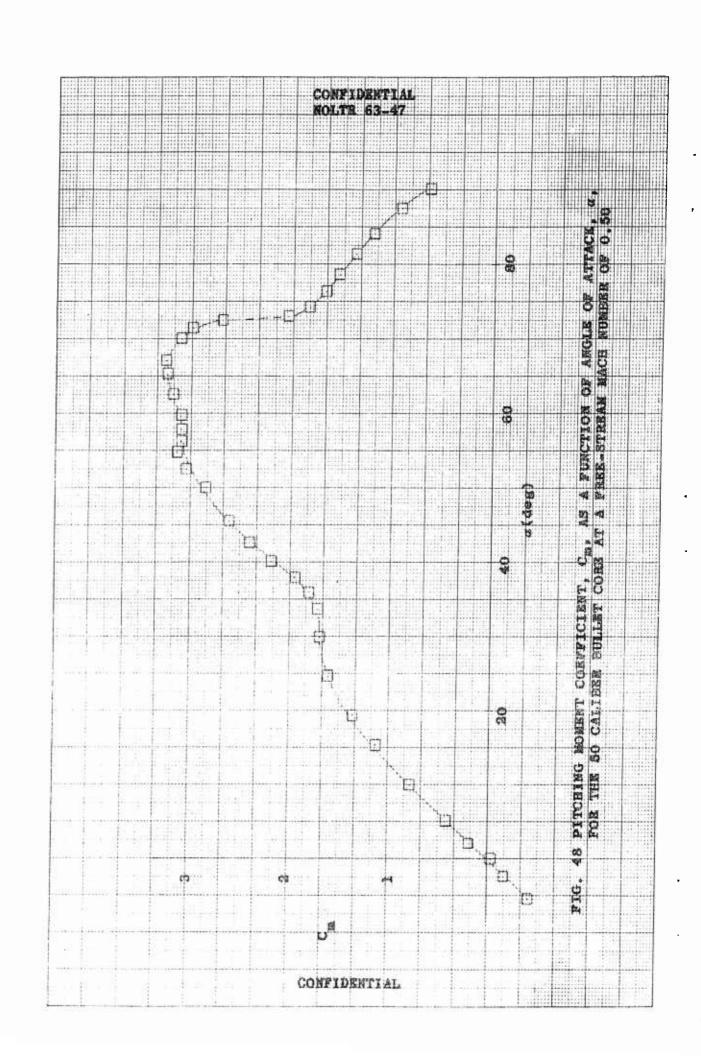
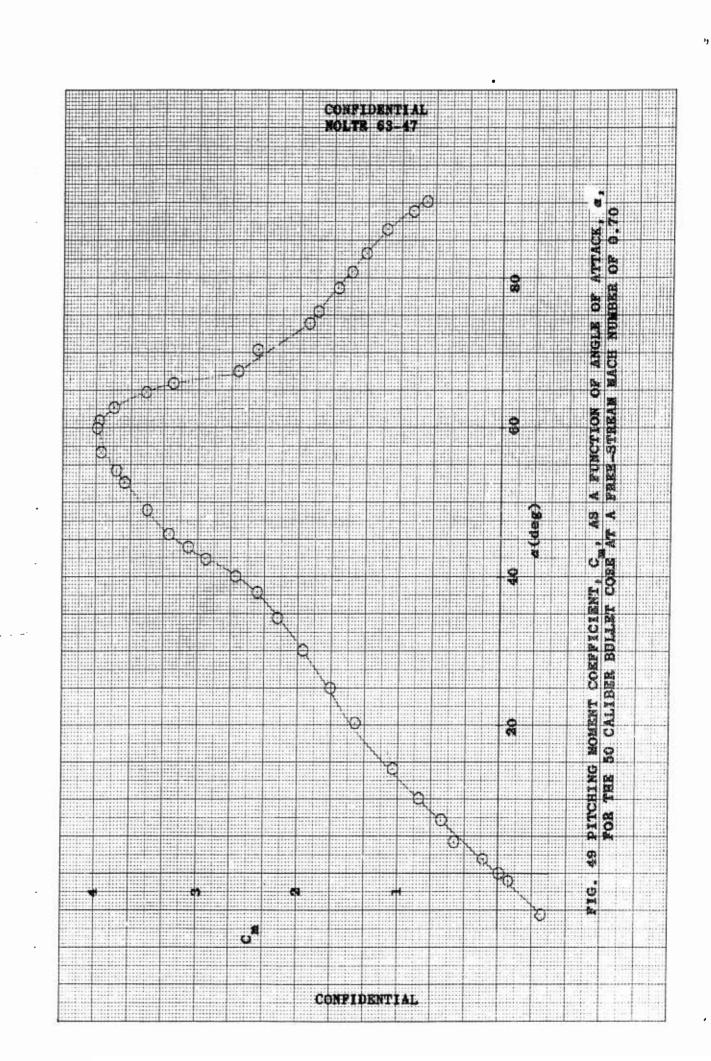


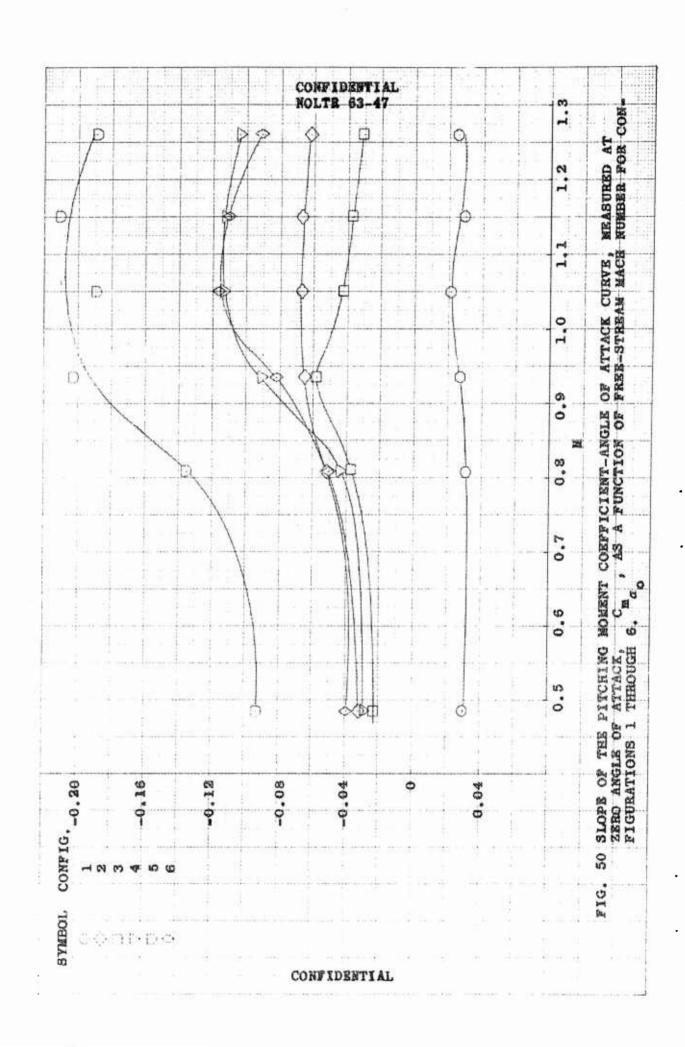
FIG. 45 PITCEING MOMENT CORFFICIENT, C_m , AS A FUNCTION OF ANGLE OF ATTACK, α , FOR CONFIGURATIONS 1, 4 AND 6 AT A FREE-STREAM MACH NUMBER OF 1.26

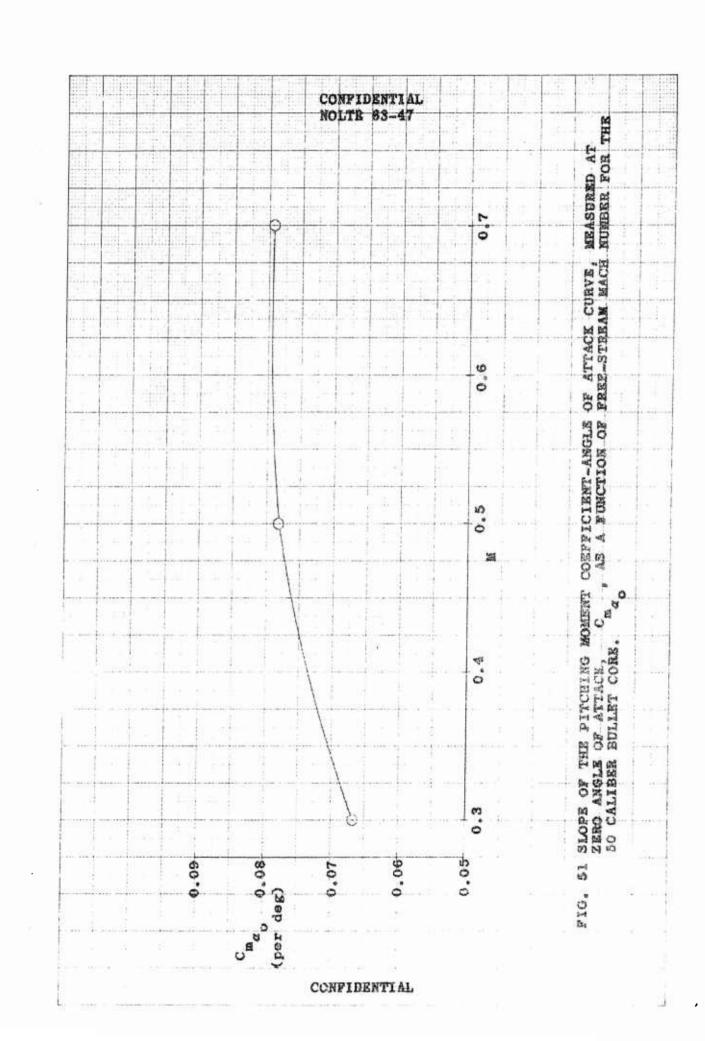
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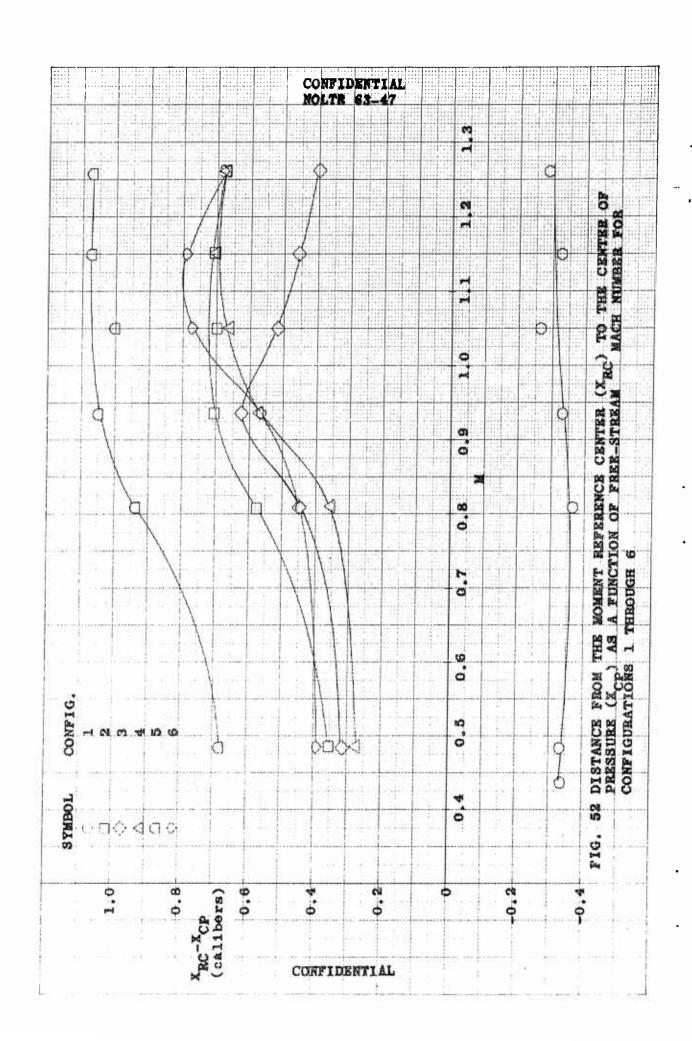


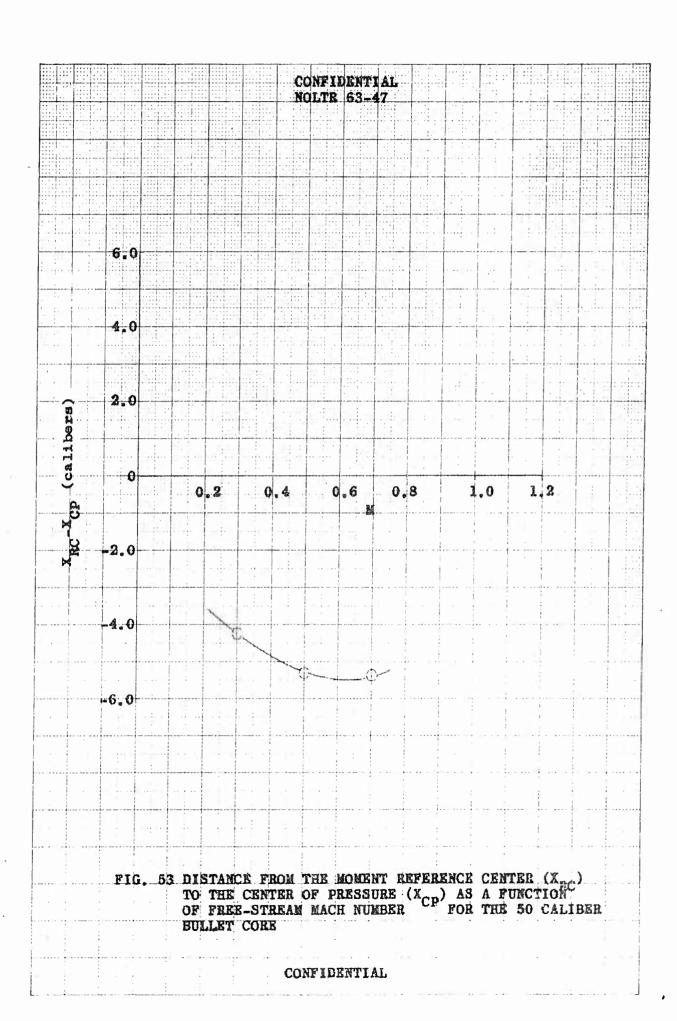


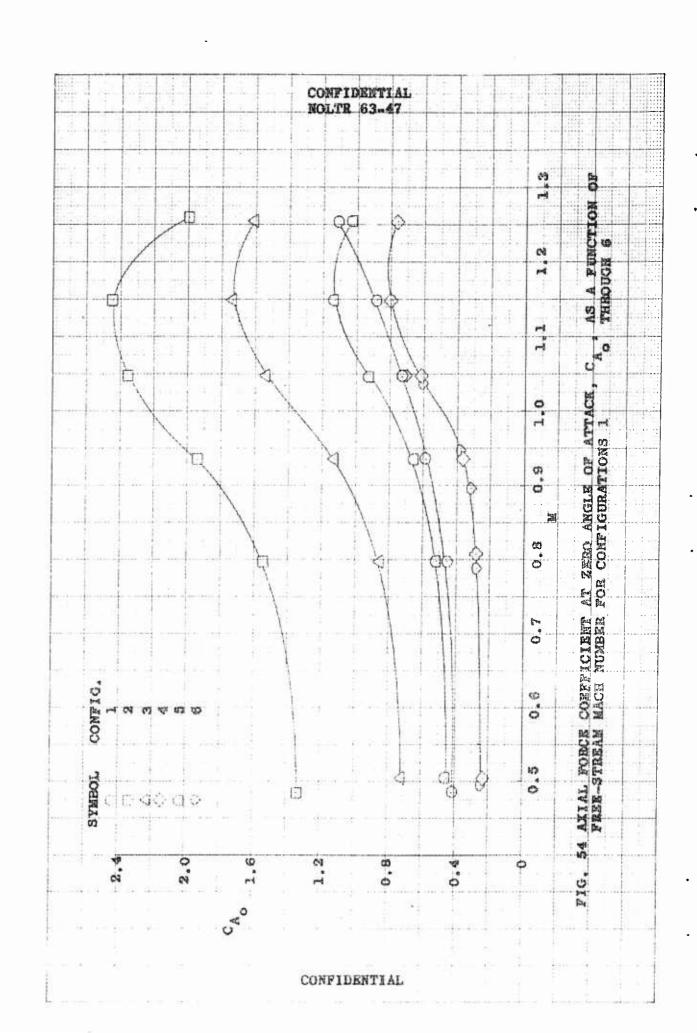


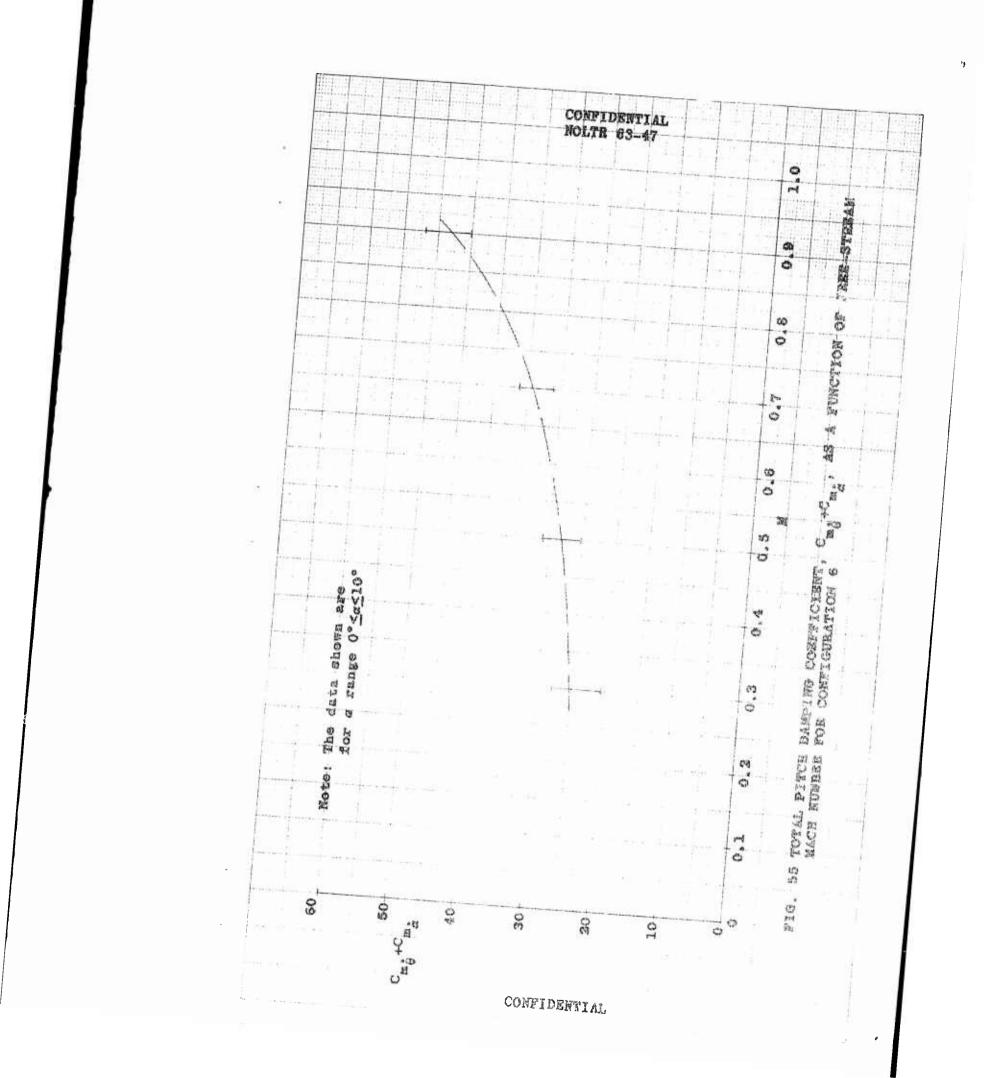


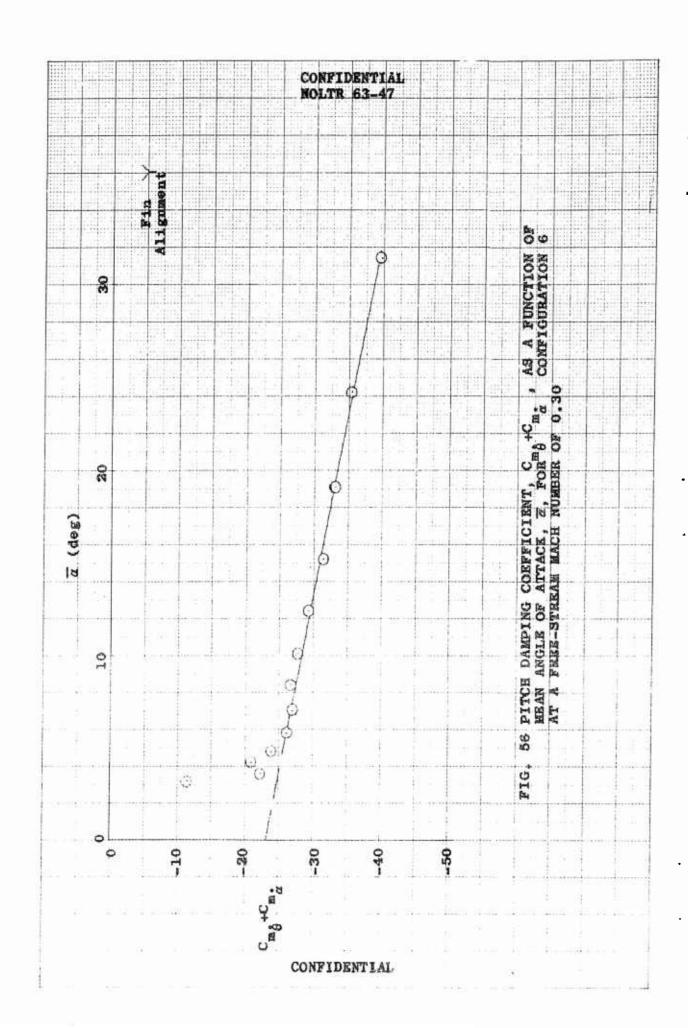


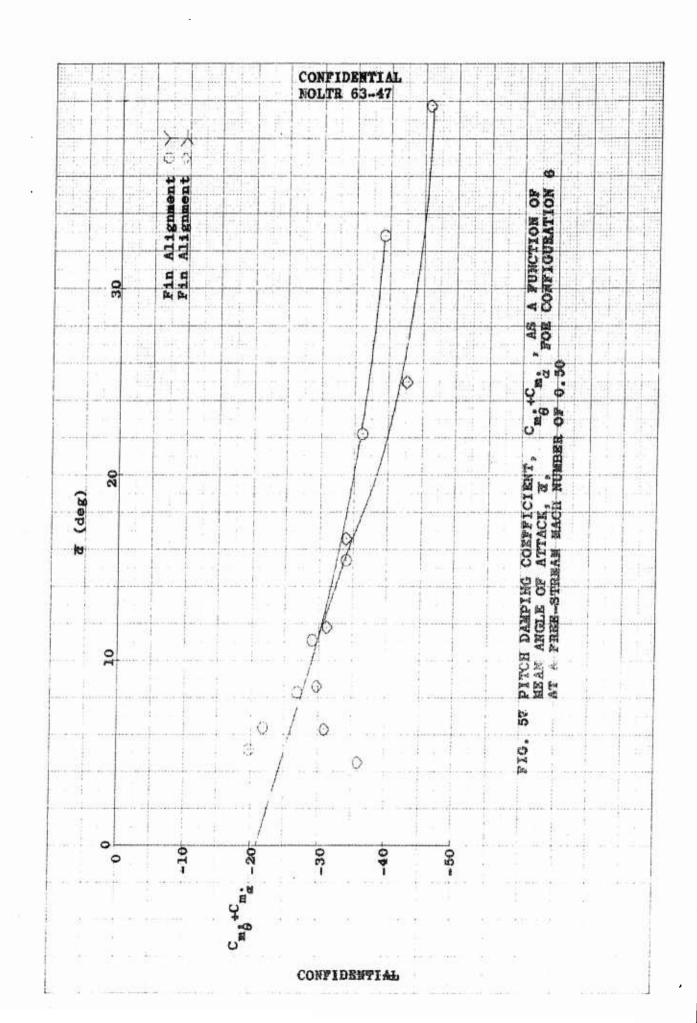


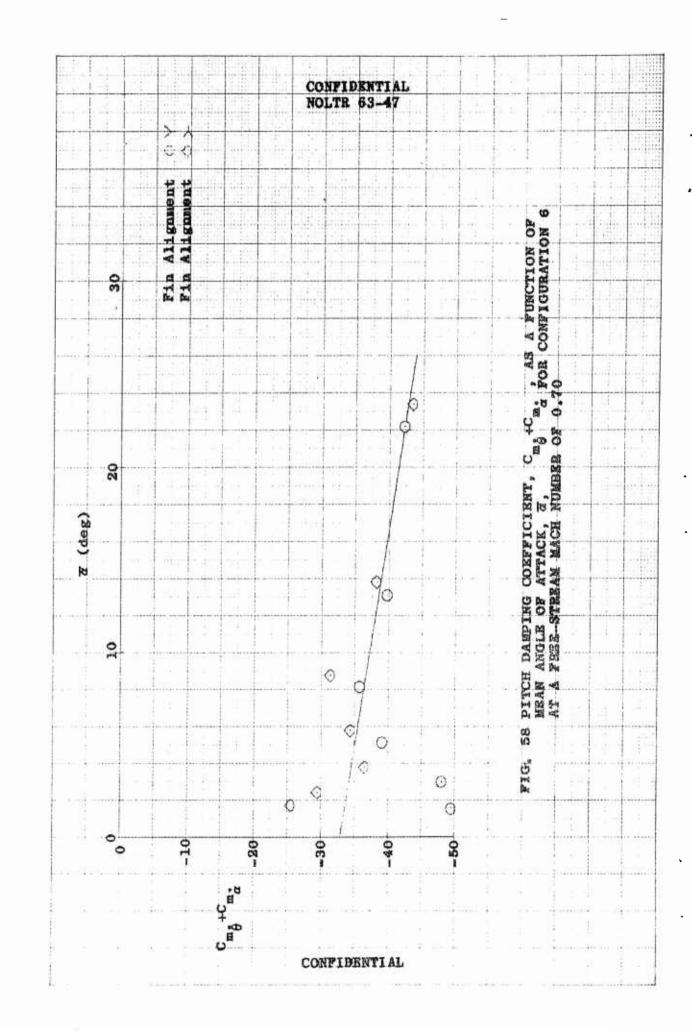


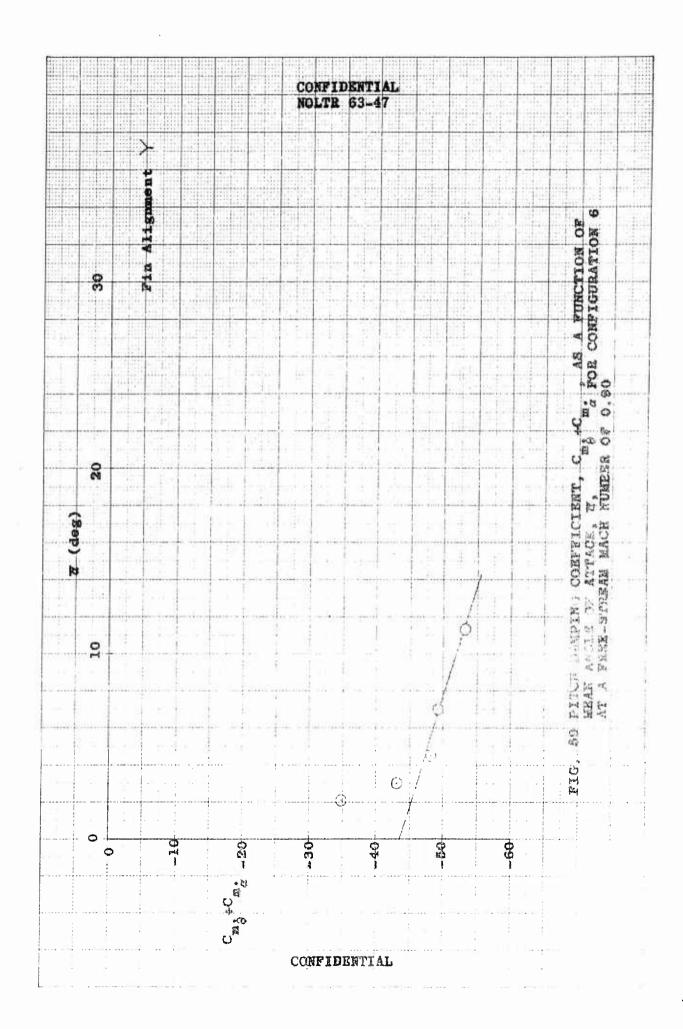












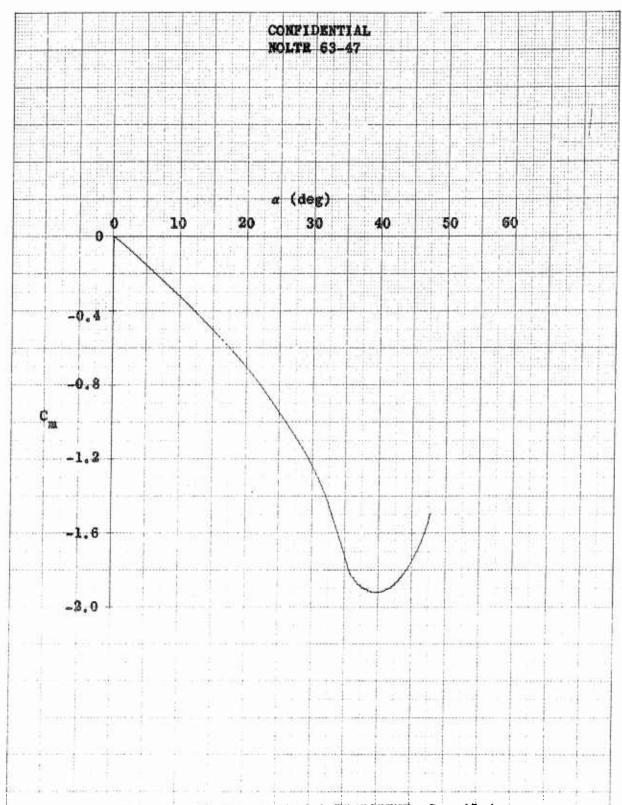
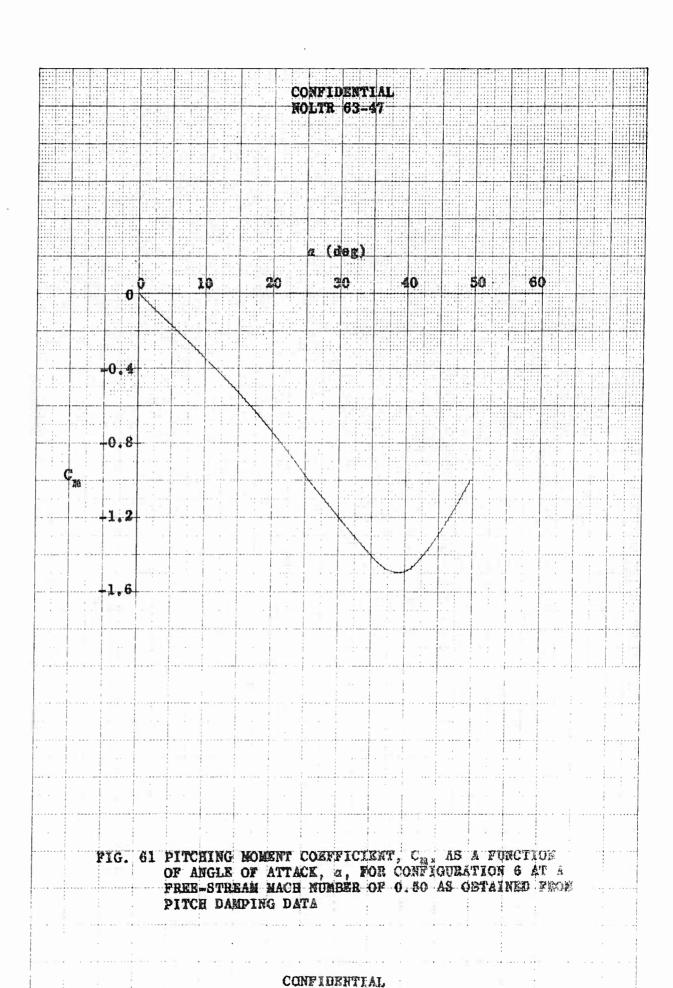
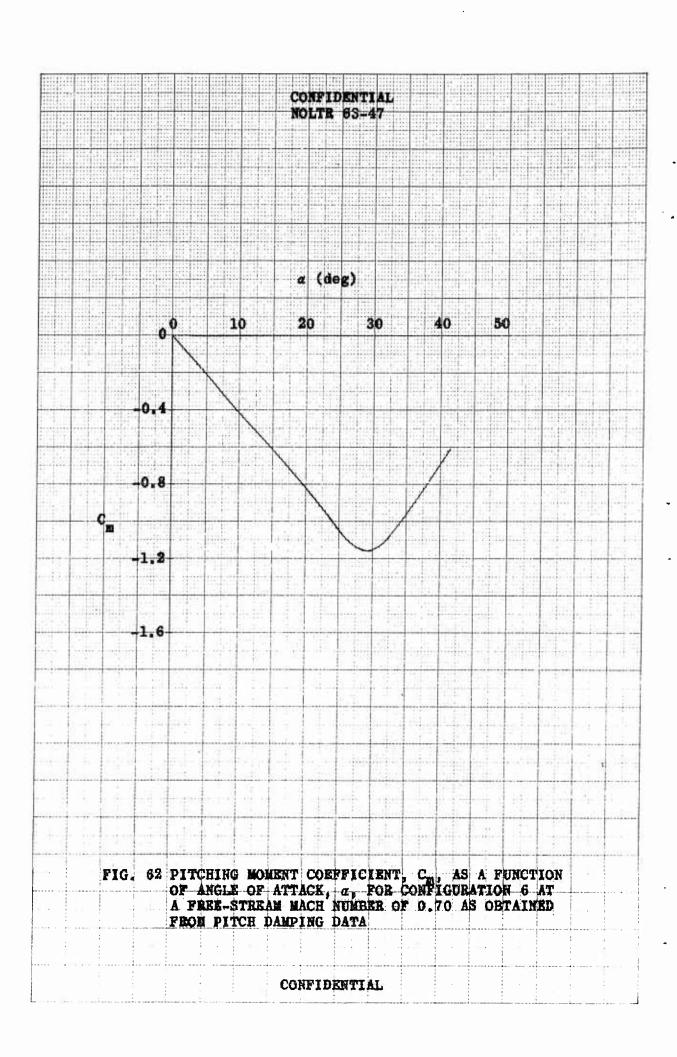
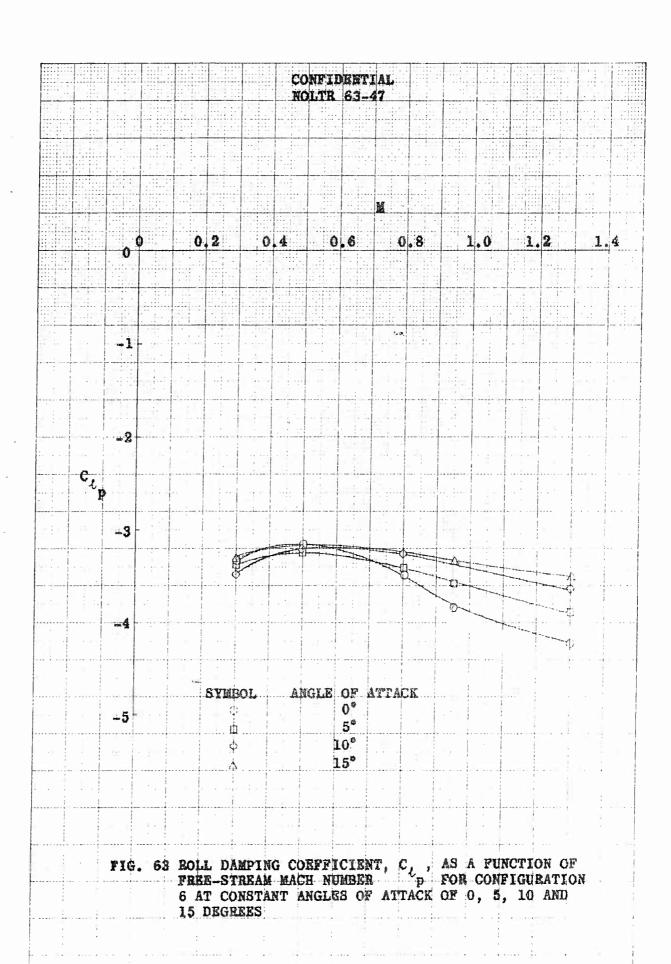
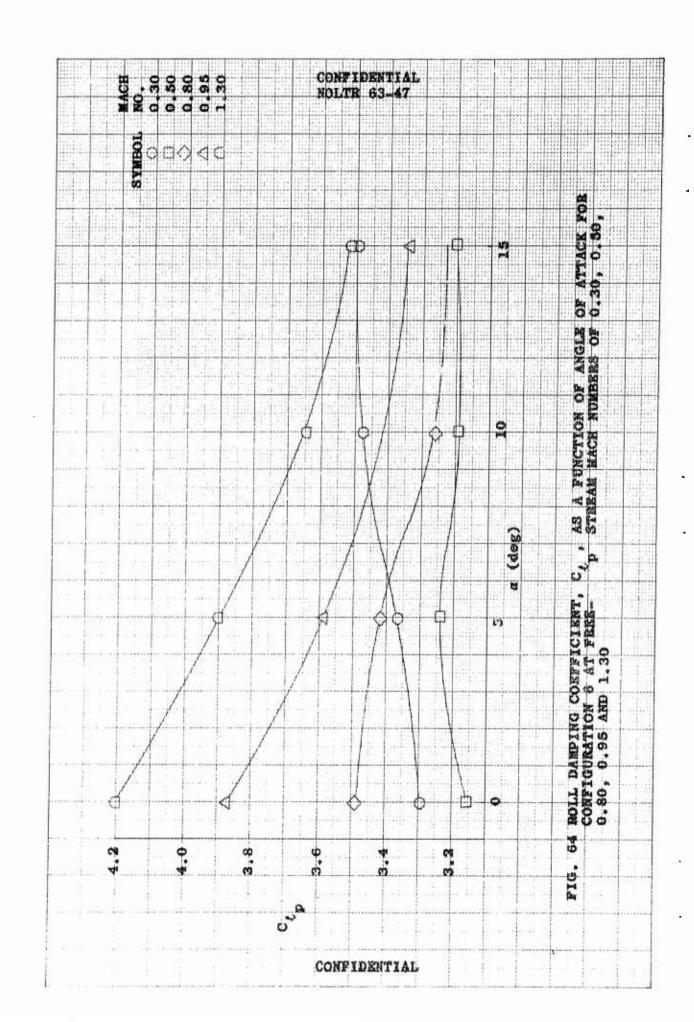


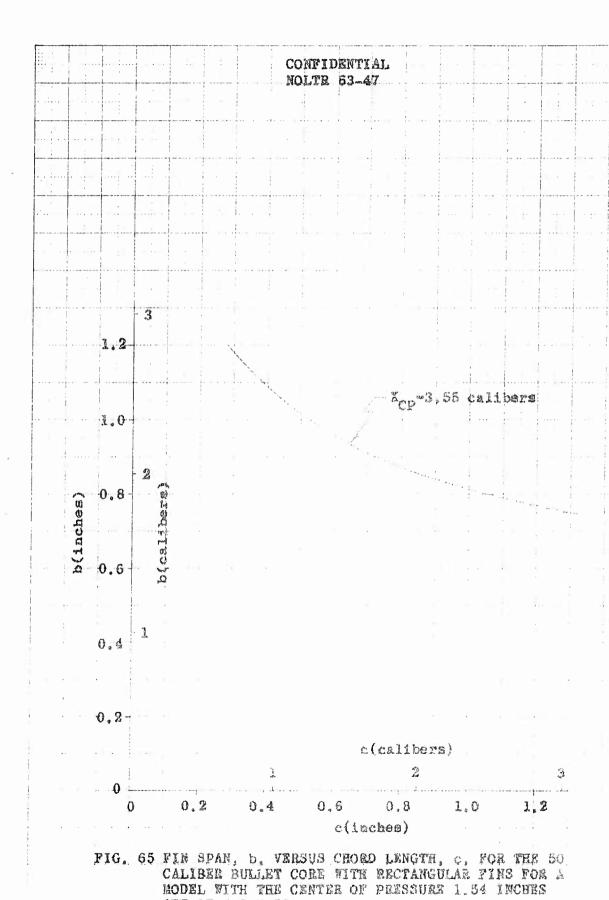
FIG. 60 PITCHING MOMENT COEFFICIENT, C_B, AS A FUNCTION OF ANGLE OF ATTACK, &, FOR COH-FIGURATION 6 AT A FREE-STREAM MACH NUMBER OF 0.30 AS OBTAINED FROM PITCH DAMPING DATA











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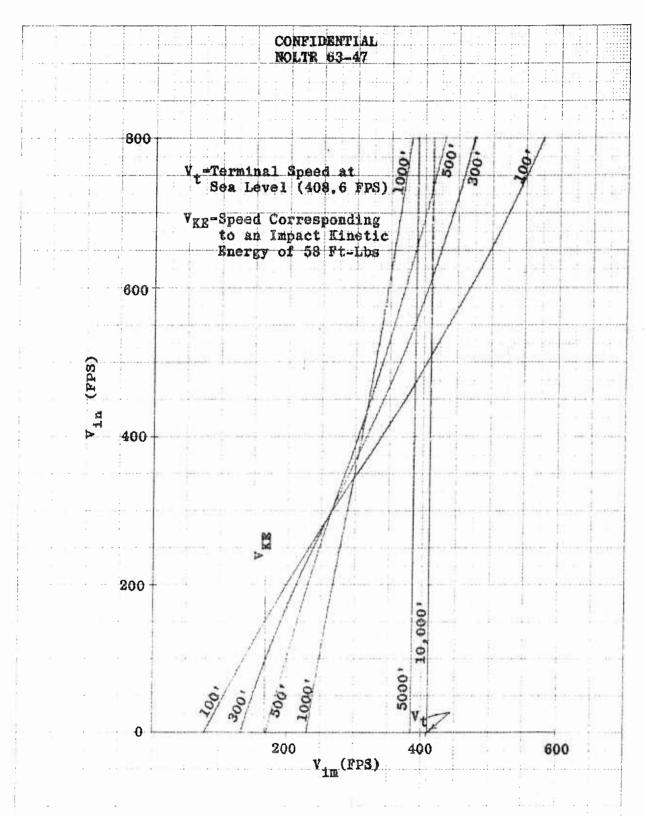


FIG. 66 VELOCITY AT IMPACT (V_{im}) FOR SEVERAL LAUNCH ALTITUDES AND INITIAL HORIZONTAL LAUNCH VELOCITIES (V_{in}) FOR A PARTICLE HAVING A FIXED W/C_D OF 0.25

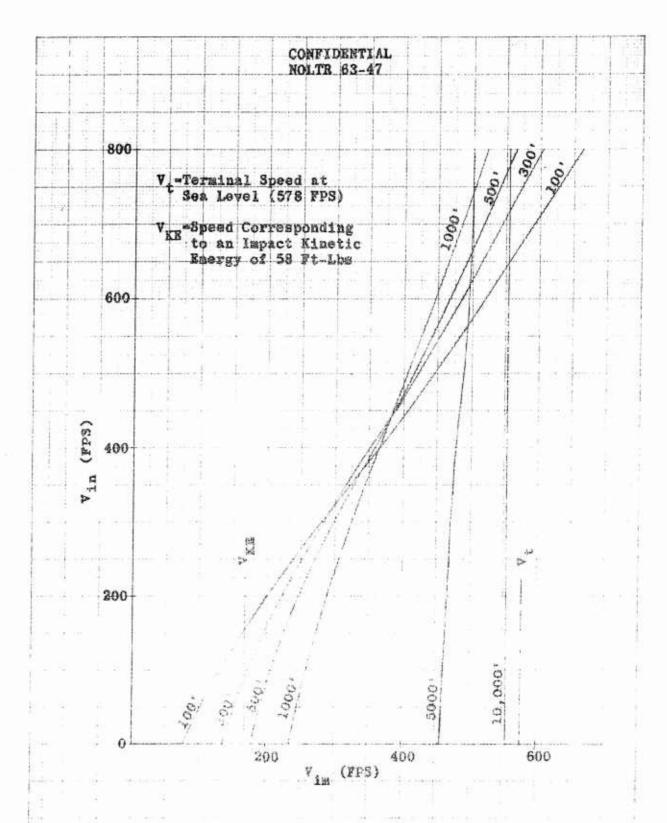


FIG. 67 VELOCITY AT IMPACT (V) FOR SEVERAL LAUNCH ALTITUDES AND INITIAL HORIZONTAL LAUNCH VELOCITIES (V) FOR A PARTICLE HAVING A FIXED W/CD OF 0.50

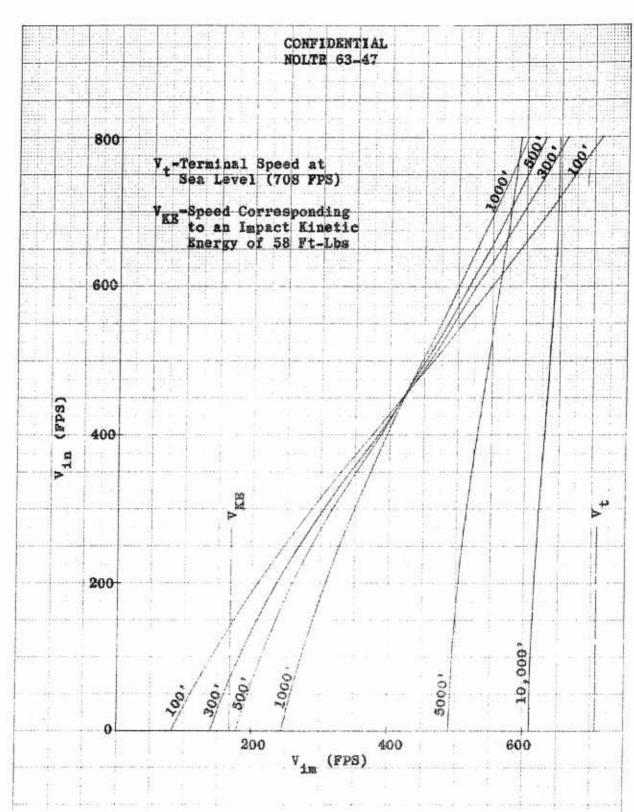


FIG. 68 VELOCITY AT IMPACT (V) FOR SEVERAL LAUNCH ALTITUDES AND INITIAL HORIZONTAL LAUNCH VELOCITIES (V) FOR A PARTICLE HAVING A FIXED W/C OF 0.75

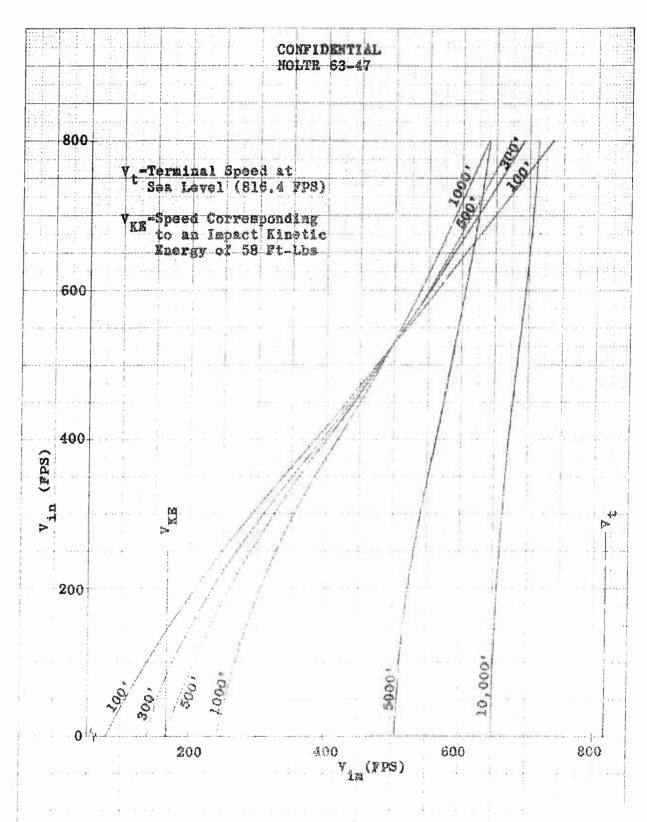


FIG. 69 VELOCITY AT IMPACT (V) FOR SEVERAL LAUNCH ALTITUDES AND INITIAL HORIZONTAL LAUNCH VELOCITIES (V) FOR A PARTICLE HAVING A FIXED W/CD OF 1.00

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| Lazy Dog | LAZY | 0.3 | ØX3Ø | 50 | 8405 pd |
| Static | STAC | 1.0 | 1X\$% | Caliber | CALB |
| Dynamic | DYNA | 1,25 | 1125 | Bullets | BULT |
| Stability | STBI | 1,5 | ǿ5xt. | High speed | HIGS |
| Subsonic | SUBS | Free fall | FREF | Aircraft | AIRC |
| Transonic | TENS | Missile | MIST | Air launched | AIRR |
| Speed | VELC | Aerodynamic | AERD | Fin stabilized | FALS |
| Wind twnel | MENU | Body | BODY | Low drag | LOWD |
| Testing | TEST | Ballistic ranges | BALR | Afterbodv | ል ፕሎፑራ |
| Configuration | COFI | Test facility | TESF | 7 | |
| Mach number | MACH | Antipersonnel | ANTO | | |
| Range | RANG | Weapone | WEAP | | |
| PRMC-HUL-5070 78 (5-62) | | | | | |

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